Week 10: Causality with Measured Confounding

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Princeton

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¹These slides are heavily influenced by Matt Blackwell, Jens Hainmueller, Erin Hartman, Kosuke Imai and Gary King.

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Week 10: Measured Confounding

Where We've Been and Where We're Going ...

- Last Week
 - intro to causal inference
- This Week
 - Monday:
 - ★ experimental Ideal
 - \star identification with measured confounding
 - Wednesday:
 - ★ regression estimation
- Next Week
 - identification with unmeasured confounding
 - instrumental variables
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causal inference

Questions?



- 2 Assumption of No Unmeasured Confounding
- Estimation Under No Unmeasured Confounding
- 4 Regression Estimators
- 5 Regression and Causality
- 6 Regression Under Heterogeneous Effects
 - 7 Fun with Visualization, Replication and the NYT

1 The Experimental Ideal

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Lancet 2001: negative correlation between coronary heart disease mortality and level of vitamin C in bloodstream (controlling for age, gender, blood pressure, diabetes, and smoking)



Lancet 2002: no effect of vitamin C on mortality in controlled placebo trial (controlling for nothing)



Lancet 2003: comparing among individuals with the same age, gender, blood pressure, diabetes, and smoking, those with higher vitamin C levels have lower levels of obesity, lower levels of alcohol consumption, are less likely to grow up in working class, etc.

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Confounders



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- Better than hoping: design observational study to approximate an experiment
 - "The planner of an observational study should always ask himself: How would the study be conducted if it were possible to do it by controlled experimentation" (Cochran 1965)

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 - Treatment assignment does not depend on any potential outcomes.
 - Sometimes written as $D_i \perp (\mathbf{Y}(1), \mathbf{Y}(0))$

Remember selection bias?

$$\begin{split} E[Y_i|D_i = 1] - E[Y_i|D_i = 0] \\ &= E[Y_i(1)|D_i = 1] - E[Y_i(0)|D_i = 0] \\ &= E[Y_i(1)|D_i = 1] - E[Y_i(0)|D_i = 1] + E[Y_i(0)|D_i = 1] - E[Y_i(0)|D_i = 0] \\ &= \underbrace{E[Y_i(1) - Y_i(0)|D_i = 1]}_{\text{Average Treatment Effect on Treated}} + \underbrace{E[Y_i(0)|D_i = 1] - E[Y_i(0)|D_i = 0]}_{\text{selection bias}} \end{split}$$

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When all goes well, an experiment eliminates selection bias.

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- Tries to minimize "snooping" by picking the best modeling strategy before seeing the outcome.

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Never used our knowledge of the randomization for this quantity.

Stratification Example: Smoking and Mortality (Cochran, 1968)

TABLE 1

DEATH RATES PER 1,000 PERSON-YEARS

Smoking group	Canada	U.K.	U.S.
Non-smokers	20.2	11.3	13.5
Cigarettes	20.5	14.1	13.5
Cigars/pipes	35.5	20.7	17.4

Stratification Example: Smoking and Mortality (Cochran, 1968)

TABLE 2 Mean Ages, Years

Smoking group	Canada	U.K.	U.S.
Non-smokers	54.9	49.1	57.0
Cigarettes	50.5	49.8	53.2
Cigars/pipes	65.9	55.7	59.7

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- for each country, divide each group into different age subgroups
- calculate death rates within age subgroups
- average within age subgroup death rates using fixed weights (e.g. number of cigarette smokers)

	Death Rates	# Pipe-	# Non-
	Pipe Smokers	Smokers	Smokers
Age 20 - 50	15	11	29
Age 50 - 70	35	13	9
Age + 70	50	16	2
Total		40	40

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What is the average death rate for Pipe Smokers? $15 \cdot (11/40) + 35 \cdot (13/40) + 50 \cdot (16/40) = 35.5$

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 $15 \cdot (29/40) + 35 \cdot (9/40) + 50 \cdot (2/40) = 21.2$

Smoking and Mortality (Cochran, 1968)

Table 3

Adjusted Death Rates using 3 Age groups

Smoking group	Canada	U.K.	U.S.
Non-smokers	20.2	11.3	13.5
Cigarettes	28.3	12.8	17.7
Cigars/pipes	21.2	12.0	14.2

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One option is to discretize as we discussed with age, we will discuss more later this week!

Identification Assumption

•
$$(Y_1, Y_0) \perp D \mid X$$
 (selection on observables)

2 $0 < \Pr(D = 1|X) < 1$ with probability one (common support)

Identification Result

Given selection on observables we have

$$\mathbb{E}[Y_1 - Y_0 | X] = \mathbb{E}[Y_1 - Y_0 | X, D = 1]$$

= $\mathbb{E}[Y | X, D = 1] - \mathbb{E}[Y | X, D = 0]$

Therefore, under the common support condition:

$$\tau_{ATE} = \mathbb{E}[Y_1 - Y_0] = \int \mathbb{E}[Y_1 - Y_0|X] dP(X)$$
$$= \int \left(\mathbb{E}[Y|X, D = 1] - \mathbb{E}[Y|X, D = 0]\right) dP(X)$$

Identification Assumption

- **1** $(Y_1, Y_0) \perp D \mid X$ (selection on observables)
- **2** $0 < \Pr(D = 1|X) < 1$ with probability one (common support)

Identification Result

Similarly,

$$\tau_{ATT} = \mathbb{E}[Y_1 - Y_0 | D = 1]$$

=
$$\int \left(\mathbb{E}[Y | X, D = 1] - \mathbb{E}[Y | X, D = 0] \right) dP(X | D = 1)$$

To identify τ_{ATT} the selection on observables and common support conditions can be relaxed to:

- $Y_0 \perp\!\!\perp D \mid X$ (SOO for Controls)
- $\Pr(D = 1|X) < 1$ (Weak Overlap)

	Potential Outcome	Potential Outcome		
unit	under Treatment	under Control		
i	Y_{1i}	Y _{0i}	Di	Xi
1	$\mathbb{E}[Y_1 X=0,D=1]$	$\mathbb{E}[Y_0 X=0,D=1]$	1	0
2			1	0
3	$\mathbb{E}[Y_1 X=0,D=0]$	$\mathbb{E}[Y_0 X=0,D=0]$	0	0
4			0	0
5	$\mathbb{E}[Y_1 X=1,D=1]$	$\mathbb{E}[Y_0 X=1,D=1]$	1	1
6			1	1
7	$\mathbb{E}[Y_1 X=1,D=0]$	$\mathbb{E}[Y_0 X=1,D=0]$	0	1
8			0	1

	Potential Outcome	Potential Outcome		
unit	under Treatment	under Control		
i	Y_{1i}	Y _{0i}	Di	Xi
1	$\mathbb{E}[\mathbf{V} \mid \mathbf{V} = 0 \mathbf{D} = 1]$	$\mathbb{E}[Y_0 X=0,D=1]=$	1	0
2	$\mathbb{E}[r_1 X = 0, D = 1]$	$\mathbb{E}[Y_0 X=0,D=0]$	1	0
3	$\mathbb{E}[\mathbf{V} \mid \mathbf{V} = 0 \mathbf{D} = 0]$		0	0
4	$\mathbb{E}[r_1 \lambda=0, D=0]$	$\mathbb{E}[T_0 X=0,D=0]$	0	0
5	$\mathbb{E}[Y_1 X=1,D=1]$	$\mathbb{E}[Y_0 X=1, D=1] =$	1	1
6		$\mathbb{E}[Y_0 X=1,D=0]$	1	1
7	$\mathbb{E}[\mathbf{V} \mid \mathbf{Y} = 1 \ \mathbf{D} = 0]$	$\mathbb{E}[\mathbf{V} \mid \mathbf{Y} = 1 \ \mathbf{D} = 0]$	0	1
8	$\mathbb{E}[I_1 X = 1, D = 0]$	$\mathbb{E}[I_0 X - 1, D = 0]$	0	1

 $(Y_1, Y_0) \perp D \mid X$ implies that we conditioned on all confounders. The treatment is randomly assigned within each stratum of X:

$$\begin{split} \mathbb{E}[Y_0|X=0,D=1] &= & \mathbb{E}[Y_0|X=0,D=0] \text{ and} \\ \mathbb{E}[Y_0|X=1,D=1] &= & \mathbb{E}[Y_0|X=1,D=0] \end{split}$$

	Potential Outcome	Potential Outcome		
unit	under Treatment	under Control		
i	Y_{1i}	Y _{0i}	Di	Xi
1	$\mathbb{E}[\mathbf{V} \mid \mathbf{Y} = 0, \mathbf{D} = 1]$	$\mathbb{E}[Y_0 X=0,D=1]=$	1	0
2	$\mathbb{E}[r_1 \lambda = 0, D = 1]$	$\mathbb{E}[Y_0 X=0,D=0]$	1	0
3	$\mathbb{E}[Y_1 X=0,D=0] =$		0	0
4	$\mathbb{E}[Y_1 X=0,D=1]$	$\mathbb{E}[I_0 X=0,D=0]$	0	0
5	$\mathbb{E}[V V = 1 D = 1]$	$\mathbb{E}[Y_0 X=1, D=1] =$	1	1
6	$\mathbb{E}[r_1 \lambda = 1, D = 1]$	$\mathbb{E}[Y_0 X=1,D=0]$	1	1
7	$\mathbb{E}[Y_1 X=1, D=0] =$	$\mathbb{E}[V \mid V = 1 D = 0]$	0	1
8	$\mathbb{E}[Y_1 X=1,D=1]$	$\mathbb{E}[I_0 X - 1, D = 0]$	0	1

 $(Y_1, Y_0) \perp D \mid X$ also implies

$$\mathbb{E}[Y_1|X = 0, D = 1] = \mathbb{E}[Y_1|X = 0, D = 0]$$
 and
 $\mathbb{E}[Y_1|X = 1, D = 1] = \mathbb{E}[Y_1|X = 1, D = 0]$



- 2 Assumption of No Unmeasured Confounding
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- No unmeasured confounding assumes that we've measured all sources of confounding.

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- Another way: use DAGs and look at back-door paths.

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 Here there is a backdoor path D ← X → Y, where X is a common cause for the treatment and the outcome.

$$\begin{array}{ccc} U \dashrightarrow X \\ \downarrow & \downarrow \\ D \dashrightarrow Y \end{array}$$

• *D* is enrolling in a job training program.

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- D is enrolling in a job training program.
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- Big assumption here: no arrow from U to Y.



- D is exercise.
- Y is having a disease.
- U is lifestyle.
- X is smoking
- Big assumption here: no arrow from U to Y.

What's the problem with backdoor paths?



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- In the DAG here, if we condition on X, then the backdoor path is blocked.

Not all backdoor paths



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Every time you do, a puppy cries.



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 - See the Elwert and Winship piece for more!

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 - if it is possible to remove the confounding, and
 - what variables to condition on to eliminate the confounding.



Remove arrows out of X.

Stewart (Princetor

Week 10: Measured Confounding

November 26 and 28, 2018 33 / 89













Implications (via Vanderweele and Shpitser 2011)



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- Choose all pre-treatment covariates (would condition on C₂ inducing M-bias)
- 2 Choose all covariates which directly cause the treatment and the outcome (would leave open a backdoor path $A \leftarrow C_3 \leftarrow U_3 \rightarrow Y$.)

• No unmeasured confounding places no restrictions on the observed data.

$$\underbrace{\left(Y_{i}(0)\middle|D_{i}=1,X_{i}\right)}_{\text{unchanged}} \stackrel{d}{=} \underbrace{\left(Y_{i}(0)\middle|D_{i}=0,X_{i}\right)}_{\text{three of }}$$

unobserved

observed

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Dep. var.			Presidential Republican vote share			
			2000-1996	1996-1992	1992-1988	
	(1)	(2)	(3)	(4)	(5)	
Availability of Fox News via cable in 2000	0.0109	0.0105	0.0036	-0.0024	0.0026	
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 TABLE VI

 The Fox News Effect: Interactions and Placebo Specifications

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- Unconfoundedness could still be violated even if you pass this test!

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 - All discussed in the next couple of weeks!

Where We've Been and Where We're Going ...

- Last Week
 - intro to causal inference
- This Week
 - Monday:
 - ★ experimental Ideal
 - \star identification with measured confounding
 - Wednesday:
 - ★ regression estimation
- Next Week
 - identification with unmeasured confounding
 - instrumental variables
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causal inference

Questions?



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- Today we will talk about regression because that's the subject of the class.

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 - regression
 - combinations of the above
- Today we will talk about regression because that's the subject of the class.
- A big topic I'm skipping over as outside the scope of class is the propensity score (conditional expectation of the treatment given the covariates).

Regression

David Freedman:

I sometimes have a nightmare about Kepler. Suppose a few of us were transported back in time to the year 1600, and were invited by the Emperor Rudolph II to set up an Imperial Department of Statistics in the court at Prague. Despairing of those circular orbits, Kepler enrolls in our department. We teach him the general linear model, least squares, dummy variables, everything. He goes back to work, fits the best circular orbit for Mars by least squares, puts in a dummy variable for the exceptional observation - and publishes. And that's the end, right there in Prague at the beginning of the 17th century.

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- When is regression causal? When the CEF is causal.
- This means that the question of whether regression has a causal interpretation is a question about identification

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 - ▶ τ will provide well-defined linear approximation to the average causal response function $\mathbb{E}[Y|D = 1, X] \mathbb{E}[Y|D = 0, X]$. Approximation may be very poor if $\mathbb{E}[Y|D, X]$ is misspecified and then τ may be biased for the ATE.

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③ Heterogeneous treatment effects (τ differs for different values of X)

 If outcomes are linear in X, τ is unbiased and consistent estimator for conditional-variance-weighted average of the underlying causal effects. This averagecan be different from the ATE.

Identification Assumption

- Constant treatment effect: $\tau = Y_{1i} Y_{0i}$ for all i
- Control outcome is linear in X: $Y_{0i} = \beta_0 + X'_i\beta + \epsilon_i$ with $\epsilon_i \perp X_i$ (no omitted variables and linearly separable confounding)

Identification Result

Then $\tau_{ATE} = \mathbb{E}[Y_1 - Y_0]$ is identified by a regression of the observed outcome on the covariates and the treatment indicator $Y_i = \beta_0 + \tau D_i + X'_i \beta + \epsilon_i$

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- As a result,

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• Thus, a regression where D_i and X_i are entered linearly can recover the ATE.

Stewart (Princeton)

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- To understand what happens when they don't hold, we need to understand the properties of regression with minimal assumptions: this is often called an agnostic view of regression.
- The Aronow and Miller book (and lecture 7) provide some context but essentially as long as we have iid sampling, we will asymptotically obtain the best linear approximation to the CEF.



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- The question, then, is when does knowing the CEF tell us something about causality?
- Angrist and Pishke argues that a regression is causal when the CEF it approximates is causal. Identification is king.
- We will show that under certain conditions, a regression of the outcome on the treatment and the covariates can recover a causal parameter, but perhaps not the one in which we are interested.

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• Note that if ignorability holds (as in an experiment) for $Y_i(0)$, then it will also hold for v_i^0 , since $\mathbb{E}[Y_i(0)]$ is constant. Thus, this satisfies the usual assumptions for regression.

Now with covariates

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- Consistency assumption allows us to write this as:

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• Works with continuous or ordinal *D_i* if effect of these variables is truly linear.



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- Thus, OLS estimates the ATE with no covariates.

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- What about the regression estimand, τ_R ? How does it relate to the ATE/ATT?
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- Linear in X_i by construction!

• How can we investigate τ_R ? Well, we can rely on the regression anatomy:

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- With a little work we can show:

$$\tau_R = \frac{\mathbb{E}\left[\tau(X_i)(D_i - \mathbb{E}[D_i|X_i])^2\right]}{\mathbb{E}\left[(D_i - E[D_i|X_i])^2\right]} = \frac{\mathbb{E}\left[\tau(X_i)\sigma_d^2(X_i)\right]}{\mathbb{E}\left[\sigma_d^2(X_i)\right]}$$

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σ²_d(x) = Var[D_i|X_i = x] is the conditional variance of treatment assignment.

$$\tau_R = \mathbb{E}[\tau(X_i)W_i] = \sum_{x} \tau(x) \frac{\sigma_d^2(x)}{\mathbb{E}[\sigma_d^2(X_i)]} \mathbb{P}[X_i = x]$$

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- OLS weights strata higher if the treatment variance in those strata $(\sigma_d^2(x))$ is higher in those strata relative to the average variance across strata $(\mathbb{E}[\sigma_d^2(X_i)])$.
- The ATE weights only by their size.

$$W_i = \frac{\sigma_d^2(X_i)}{\mathbb{E}[\sigma_d^2(X_i)]}$$

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• Maximum variance with $\mathbb{P}[D_i = 1 | X_i = x] = 1/2$.

Group 1
 Group 2

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- Constant probability of treatment: $e(x) = \mathbb{P}[D_i = 1 | X_i = x] = e$.
 - Implies that the OLS weights are 1.
- Incorrect linearity assumption in X_i will lead to more bias.

Other ways to use regression

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- Then, $\hat{\mu}_d(x)$ is just a predicted value from the regression for $X_i = x$.
- How can we use this?

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$$\tau_{imp} = \frac{1}{N} \sum_{i} \hat{\mu}_1(X_i) - \hat{\mu}_0(X_i)$$

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Sometimes called an imputation estimator.

Simple imputation estimator

• Use predict() from the within-group models on the data from the entire sample.

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- Useful trick: use a model on the entire data and model.frame() to get the right design matrix:

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- Useful trick: use a model on the entire data and model.frame() to get the right design matrix:

```
## heterogeneous effects
y.het <- ifelse(d == 1, y + rnorm(n, 0, 5), y)
mod <- lm(y.het ~ d + X)
mod1 <- lm(y.het ~ X, subset = d == 1)
mod0 <- lm(y.het ~ X, subset = d == 0)
y1.imps <- predict(mod1, model.frame(mod))
y0.imps <- predict(mod0, model.frame(mod))
mean(y1.imps - y0.imps)</pre>
```

[1] 0.61

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 - Easiest is generalized additive models (GAMs)

Imputation estimator visualization



Imputation estimator visualization



Imputation estimator visualization



Nonlinear relationships

• Same idea but with nonlinear relationship between Y_i and X_i :



Nonlinear relationships

• Same idea but with nonlinear relationship between Y_i and X_i :



Nonlinear relationships

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Using semiparametric regression

• Here, CEFs are nonlinear, but we don't know their form.

library(mgcv)
mod0 <- gam(y ~ s(x), subset = d == 0)
summary(mod0)</pre>

```
##
## Family: gaussian
## Link function: identity
##
## Formula:
## v ~ s(x)
##
## Parametric coefficients:
##
              Estimate Std. Error t value Pr(>|t|)
## (Intercept) -0.0225 0.0154 -1.46
                                              0.16
##
## Approximate significance of smooth terms:
##
        edf Ref.df F p-value
## s(x) 6.03 7.08 41.3 <2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
```

Using semiparametric regression

- Here, CEFs are nonlinear, but we don't know their form.
- We can use GAMs from the mgcv package to for flexible estimate:

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Using GAMs



Using GAMs


Using GAMs



'Wait...so what are we actually doing most of the time?'

A Discussion

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- It is a useful descriptive tool for approximating a conditional expectation function
- Once again though, the estimand of interest isn't necessarily the regression coefficient.
- There are many other approaches to estimation, but identification is key.

Next Week

- Causality with Unmeasured Confounding
- Reading:
 - Angrist and Pishke Chapter 4 Instrumental Variables and Chapter 6 on Regression Discontinuity Designs
 - Morgan and Winship Chapter 9 Instrumental Variable Estimators of Causal Effects
 - Optional: Hernan and Robins Chapter 16 Instrumental Variable Estimation



- 2 Assumption of No Unmeasured Confounding
- Estimation Under No Unmeasured Confounding
- 4 Regression Estimators
- 5 Regression and Causality
- 6 Regression Under Heterogeneous Effects
 - 7 Fun with Visualization, Replication and the NYT

1 The Experimental Ideal

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7 Fun with Visualization, Replication and the NYT

AMERICAS

How Stable Are Democracies? 'Warning Signs Are Flashing

The Interpreter

By AMANDA TAUB NOV. 29, 2016

WASHINGTON — Yascha Mounk is used to being the most pessimistic person in the room. Mr. Mounk, a lecturer in government at Harvard, has spent the past few years challenging one of the bedrock assumptions of Western politics: that once a country becomes a liberal democracy, it will stay that way.

His research suggests something quite different: that liberal democracies around the world may be at serious risk of decline.

Mr. Mounk's interest in the topic began rather unusually. In 2014, he published a book, "<u>Stranger in My Own Country</u>." It started as a memoir of his experiences growing up as a Jew in Germany, but became a broader investigation of how contemporary European nations were struggling to construct new, multicultural national identities.

Week 10: Measured Confounding

The Danger of Deconsolidation

THE DEMOCRATIC DISCONNECT

Roberto Stefan Foa and Yascha Mounk

Roberto Stefan Foa is a principal investigator of the World Values Survey and fellow of the Laboratory for Comparative Social Research. His writing has appeared in a wide range of journals, books, and publications by the UN, OECD, and World Bank. Yascha Mounk is a lecturer on political theory in Harvard University's Government Department and a Carnegie Fellow at New America, a Washington, D.C.-based think tank. His dissertation on the role of personal responsibility in contemporary politics and philosophy will be published by Harvard University Press, and his essays have appeared in Foreign Affairs, the New York Times, and the Wall Street Journal.



Stewart (Princeton) Week 10: Measured Confounding November 26 and 28, 2018 87 / 89



Ryan D. Enos @RyanDEnos · 19h Lots of worried chatter a/b @amandataub article on work of @Yascha_Mounk. Important, but want to raise cautions 1/



New research tries to spot the collapse of liberal democracies before they happen, and it suggests that Western democracy may be seriously ill.

nytimes.com

Stewart (Princeton)



Percentage of people who say it is "essential" to live in a democracy

Source: Yascha Mounk and Roberto Stefan Foa, "The Signs of Democratic Deconsolidation," Journal of Democracy | By The New York Times

.@RyanDEnos Compare NYT/JoD (left) to the very same data analysed differently by Bartels and Achen (2016) (right). Extreme score vs means.

Sweden Egypt

Germany

How democratically is this country being governed?

88 / 89

Across numerous countries, including Australia, Britain, the Netherlands, New Zealand, Sweden and the United States, the percentage of people who say it is "essential" to live in a democracy has plummeted, and it is especially low among younger generations.



@RyanDEnos They also stop at the 80s cohort. The data has the 90's as well. I wonder why they would stop there...



Week 10: Measured Confounding

Percentage of people who say it is *extremely important to live* in a country that is governed democratically





Benjamin Sack @bcsack · 15h

@RyanDEnos Same analysis strategy with comparable data from @ESS_Survey (similar item, 0-10 scale) shows slightly different pattern, too

Stewart (Princeton)

Week 10: Measured Confounding



How important is it for you to live in a country that is governed democratically?



614 Bantam Øjpbach · 15h

@RyanDEnos @bshor @nataliemjb @TomWGvdMeer this is a "quick and dirty" plot I did with WVS wave 6. Not quite so terrifying.



How important is it for you to live in a country that is governed democratically? United States, 2011



my take on the democratic deconsolidation graph that scared everyone yesterday. Blue is 1940s cohort, red is 1980s.

First, United States

Thoughts

Two stories here:

Thoughts

Two stories here:

Visualization and data coding choices are important

Thoughts

Two stories here:

- Visualization and data coding choices are important
- The internet is amazing (especially with replication data being available!)