

# Week 3: Learning from Random Samples

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Princeton

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<sup>1</sup>These slides are heavily influenced by Matt Blackwell, Adam Glynn, Justin Grimmer, Jens Hainmueller, Erin Hartman and Matt Salganik. Some illustrations by Shay O'Brien.

# Where We've Been and Where We're Going...

- Last Week

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  - ▶ probability  $\rightarrow$  inference  $\rightarrow$  regression  $\rightarrow$  causal inference

- 1 Estimation
  - Populations and Samples
  - Estimators
  - Analytical
- 2 Weak Law of Large Numbers and the Central Limit Theorem
  - Chebychev's Inequality
  - Weak Law of Large Numbers
  - The Central Limit Theorem
- 3 Properties of Estimators
  - Four Desirable Properties
  - Example
- 4 Interval Estimation
  - Intervals
  - Large Sample Intervals for a Mean
  - Small Sample Intervals for a Mean
  - Comparing Two Groups
  - Interval Estimation for a Proportion
- 5 Plug-In Principle

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- Chebychev's Inequality
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## 3 Properties of Estimators

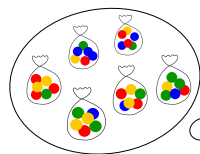
- Four Desirable Properties
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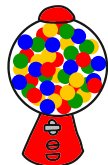
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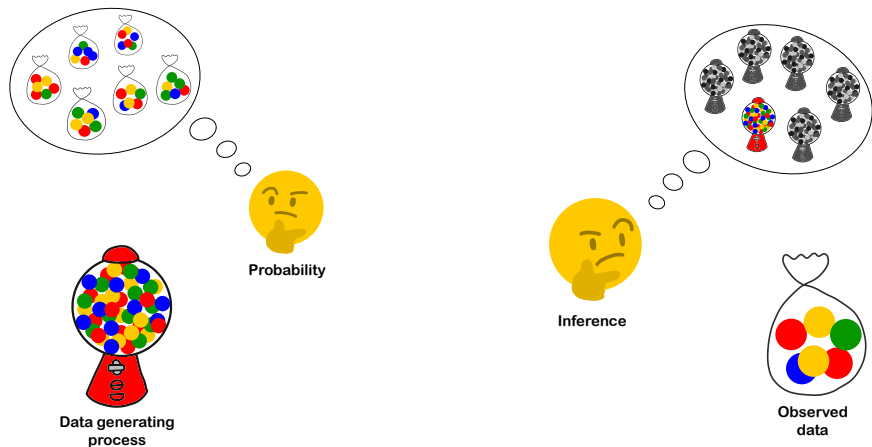
Probability



Data generating  
process



# Where We've Been and Where We're Going...



# *Racial Prejudice and Attitudes Toward Affirmative Action\**

James H. Kuklinski, *University of Illinois at Urbana-Champaign*

Paul M. Sniderman, *Stanford University*

Kathleen Knight, *University of Houston*

Thomas Piazza, *University of California-Berkeley*

Philip E. Tetlock, *Ohio State University*

Gordon R. Lawrence, *Williams College*

Barbara Mellers, *Ohio State University*

<https://www.jstor.org/stable/2111770>

## Primary Goal for This Week

*Theory:* We examine the relationship between blatant racial prejudice and anger toward affirmative action.

*Hypotheses:* (1) Blatantly prejudiced attitudes continue to pervade the white population in the United States. (2) Resistance to affirmative action is more than an extension of this prejudice. (3) White resistance to affirmative action is not unyielding and unalterably fixed.

*Methods:* Analysis of experiments embedded in a national survey of racial attitudes. Some of these experiments are designed to measure racial prejudice unobtrusively.

*Results:* Racial prejudice remains a major problem in the United States, but this prejudice alone cannot explain all of the anger toward affirmative action among whites. Although many whites strongly resist affirmative action, they express support for making extra efforts to help African-Americans.

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## Primary Goal for This Week

We want to be able to interpret the numbers in this table (and a couple of numbers that can be derived from these numbers).

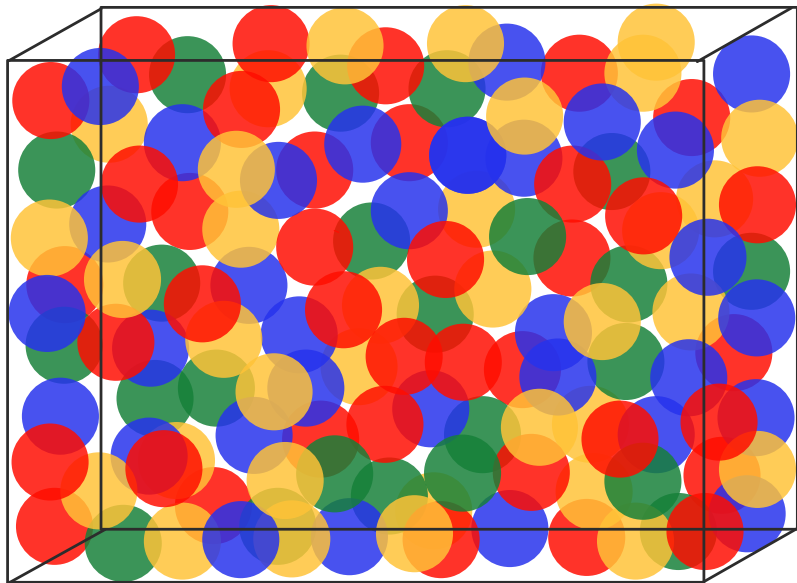
**Table 1. Mean Level of Anger Toward A Black Family Moving in Next Door, by Region (Whites Only)**

Region	Experimental Condition		Estimated Percent Angry
	Baseline	Black Family	
Non-South	2.28 <sup>a</sup> (.07)	2.24 (.05)	0
	425 <sup>b</sup>	461	
South	1.95 (.06)	2.37 (.08)	42
	139	136	

<sup>a</sup>Standard error of the estimate.

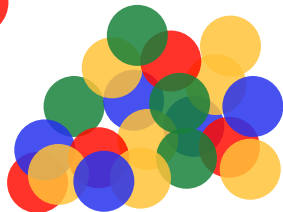
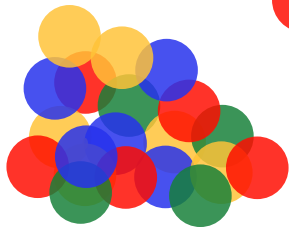
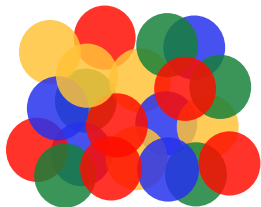
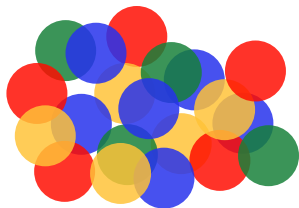
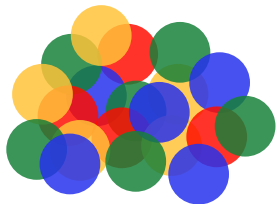
<sup>b</sup>Number of cases.

# An Overview



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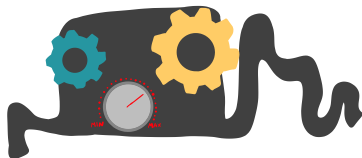


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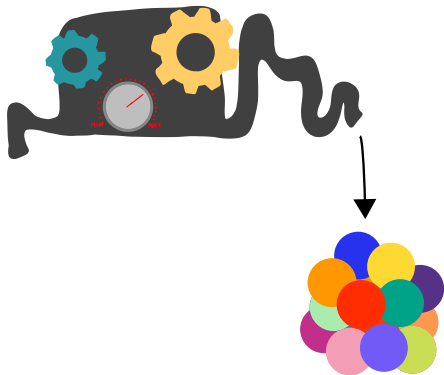




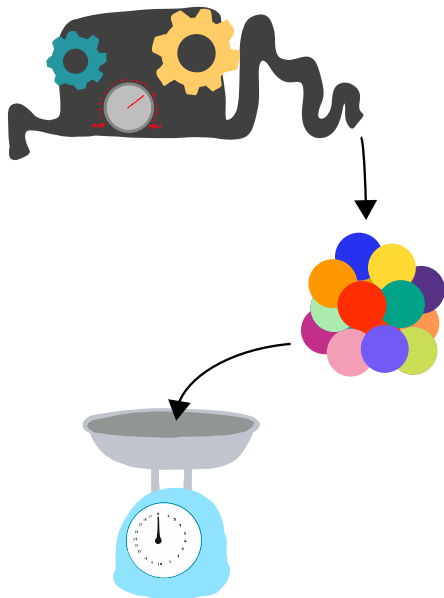
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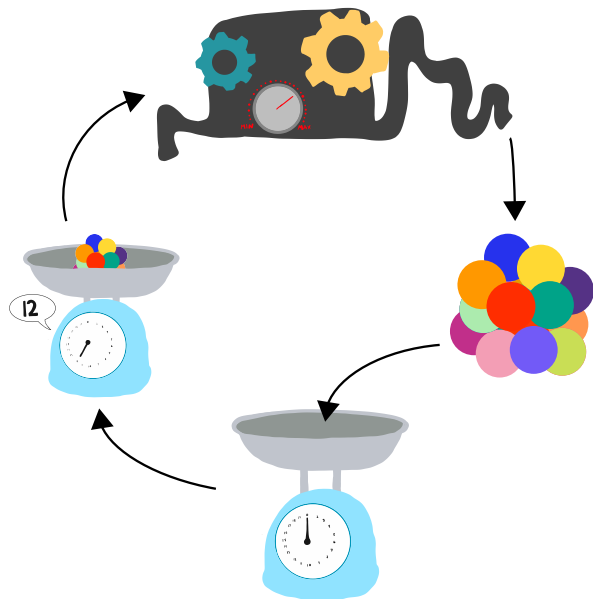
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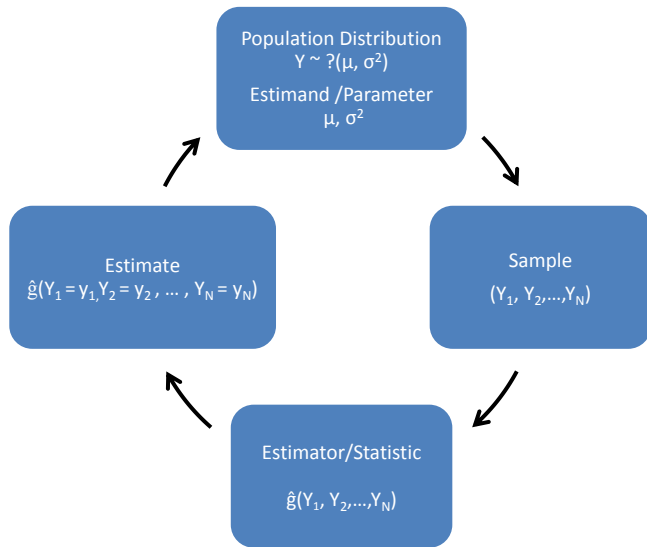
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- Ideally we assume as little as possible about the form of  $f_X$ .

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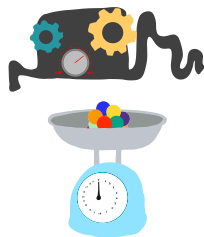
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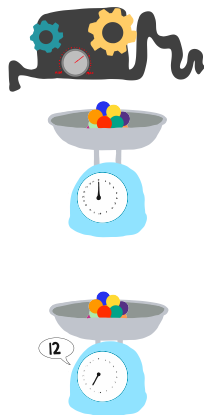
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- **Estimators** are functions which map our data to guesses about the estimand. Often denoted with a “hat” (e.g.  $\hat{\mu}$ )
- **Estimates** are particular values of estimators that are realized in a given sample (e.g. 12)





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- We will leverage the powerful assumption that we are observing **IID**—independent and identically distributed—samples of the random variable of interest.

Plain language:

Data are sampled IID when each observation is drawn from the **same distribution**, and the way an observation is drawn **does not depend on the values of any other draw**.

# IID Formal Definition

## Definition (Independent and Identically Distributed)

Let  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be random variables with CDFs  $F_1, F_2, \dots, F_n$ , respectively. Let  $F_A$  denote the joint CDF of the random variables with indices in the set  $A$ . Then  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  are independently and identically distributed if they satisfy the following:

- Mutually independent:

$$\forall A \subseteq \{1, 2, \dots, n\}, \forall (x_1, x_2, \dots, x_n) \in \mathbb{R}^n, F_A((x_i)_{i \in A}) = \prod_{i \in A} F_i(x_i)$$

- Identically distributed:  $\forall i, j \in \{1, 2, \dots, n\}$  and  $\forall x \in \mathbb{R}, F_i(x) = F_j(x)$

(Aronow and Miller Definition 3.1.1)

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- IID tells us that each one is produced under the **same random process**. This is how we get leverage to do estimation!
- We will usually use unsubscripted capital letters,  $X$ , to refer to properties that all these draws share.  
e.g.  $E[X] = E[X_1] = E[X_2] = \dots = E[X_n]$

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We will return to these issues more in later videos and in future weeks.

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- If the population is **small** relative to the sample size, it will be necessary to think carefully through the implications (see e.g. the challenge problem in problem set 3).

## Sampling in R

```
## draw a sample of size 10 from our population
## drawn without replacement
my_sample <- dplyr::sample_n(my_data, size = 10,
                             replace = FALSE)
## this is a wrapper around sample.int()
my_sample <- my_data[sample.int(nrow(my_data),
                                size = 10, replace = FALSE), ]
```

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- In real applications, we cannot draw repeated samples, so we approximate the sampling distribution.

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Say we have the following population:

```
pop <- c(4, 2, 3, 6, 9, 2, 3, 6, 8, 5, 2, 9, 6, 3,  
         4, 7, 6, 1, 2, 6, 9, 3, 1, 1, 1, 5, 7, 9)
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```
choose(length(pop), 10)
```

```
## [1] 13123110
```

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```
sim_res <- replicate(10000, {  
  mean(pop[sample.int(length(pop), 10)])  
}) %>% tibble(sample_mean = .) %>%  
  rownames_to_column(var = "replicate")  
  
sim_res[1:5, ]
```

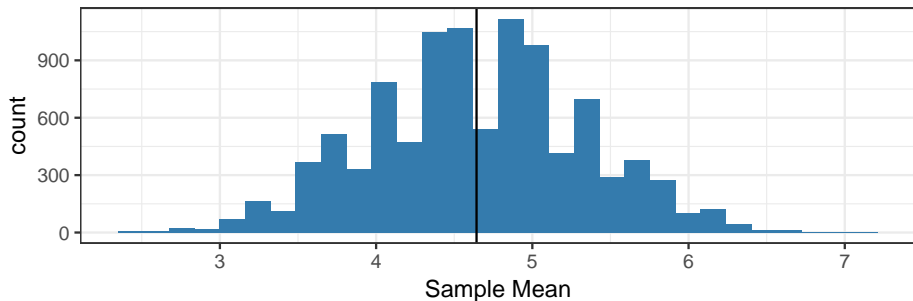
```
## # A tibble: 5 x 2  
##   replicate sample_mean  
##   <chr>      <dbl>  
## 1         1         5.4  
## 2         2         4.9  
## 3         3         3.7  
## 4         4         3.6  
## 5         5         5.3
```

# The Sampling Distribution

And we can plot this sampling distribution

```
true_pop_mean = mean(pop)
ggplot(sim_res, aes(x = sample_mean)) +
  geom_histogram(fill = blue) +
  geom_vline(xintercept = true_pop_mean) +
  ggtitle("Sampling Distribution\nof Sample Mean") +
  xlab("Sample Mean") + theme_bw()
```

Sampling Distribution  
of Sample Mean



# An Analytical Approach to the Sampling Distributions

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- We will start with a common estimator, the **sample mean**,  
$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i.$$
- Under the identically and independently distributed assumption we can characterize properties of the distribution like the expectation and variance.

# Describing the Sampling Distribution for the Sample Mean

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- $E[\bar{X}_n]$
- $V[\bar{X}_n]$
- $f_{\bar{X}_n} \sim ?$

## Expectation of $\bar{X}_n$

Let  $X_1, X_2, \dots, X_n$  be identically and independently distributed from a population distribution with mean ( $E[X_i] = \mu$ ) and variance ( $V[X_i] = \sigma^2$ ).

$$E[\bar{X}_n] =$$

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Let  $X_1, X_2, \dots, X_n$  be identically and independently distributed from a population distribution with mean ( $E[X_i] = \mu$ ) and variance ( $V[X_i] = \sigma^2$ ).

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Note the  $n$  in the denominator: as we have more observations, the variance of the sampling distribution will shrink.

## What about the “?”

If  $X_1, \dots, X_n \sim i.i.d. N(\mu, \sigma^2)$ , then

$$\bar{X}_n \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

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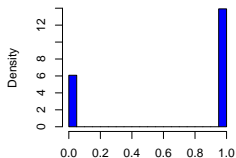
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What if  $X_1, \dots, X_n$  are not normally distributed?

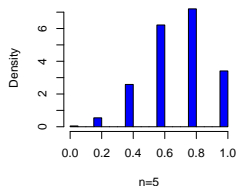
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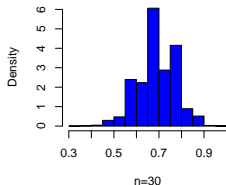
Population Distribution



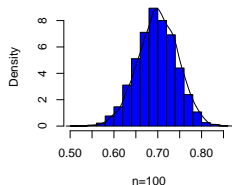
Sampling Distribution of the Mean



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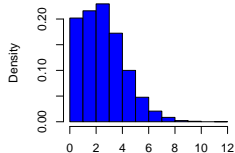


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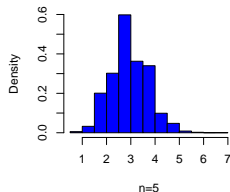


# Poisson (Count) Distribution

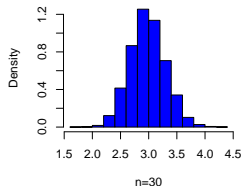
Population Distribution



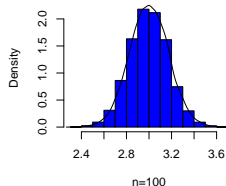
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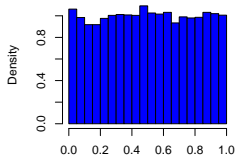


Sampling Distribution of the Mean

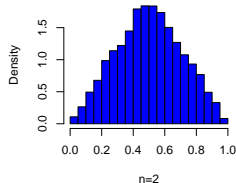


# Uniform Distribution

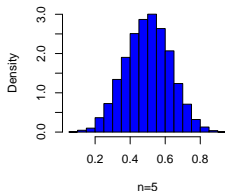
**Population Distribution**



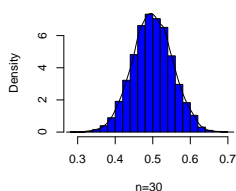
**Sampling Distribution of the Mean**



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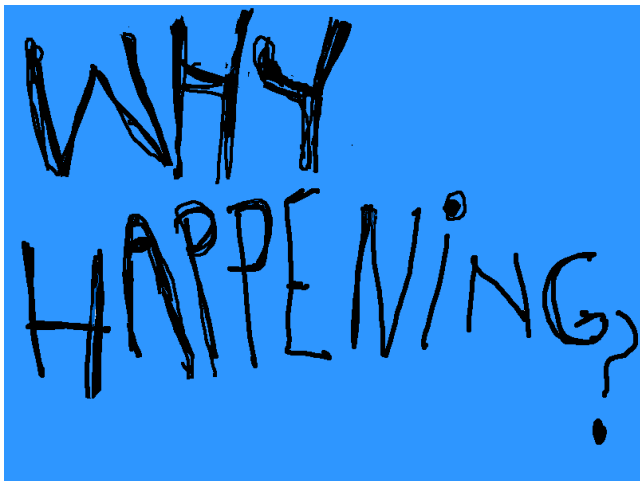


## Why would this be true?



Images from *Hyperbole and a Half* by Allie Brosh.

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Next time: the answer to 'why happening?' and the most important theorem in statistics.

# Where We've Been and Where We're Going...

- Last Week
  - ▶ random variables
  - ▶ joint distributions
- This Week
  - ▶ estimators and sampling distributions
  - ▶ estimator properties (bias, variance, consistency)
  - ▶ confidence intervals
- Next Week
  - ▶ hypothesis testing
  - ▶ what is regression?
- Long Run
  - ▶ probability  $\rightarrow$  inference  $\rightarrow$  regression  $\rightarrow$  causal inference



- 1 Estimation
  - Populations and Samples
  - Estimators
  - Analytical
- 2 Weak Law of Large Numbers and the Central Limit Theorem
  - Chebychev's Inequality
  - Weak Law of Large Numbers
  - The Central Limit Theorem
- 3 Properties of Estimators
  - Four Desirable Properties
  - Example
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The key thing to remember is that the sample mean is itself a **random variable**.

**Warning:** This video is a little bit mathier. At the end I'll wrap up with things you need to know so don't stress out your first watch through.

# Bounding a Random Variable



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This let's us bound the behavior of a random variable knowing **only** the expectation and variance (regardless of distributional shape!).

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To apply this to the **sample mean**, we plug in the expectation and variance to the Chebychev's inequality and re-arranging terms, we get the following handy result.

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Let  $X_1, X_2, \dots, X_n$  be i.i.d. random variables with finite variance  $V[X] > 0$ . Then,  $\forall \epsilon > 0$ ,

$$P [ |\bar{X}_n - E[X]| \geq \epsilon ] \leq \frac{V[X]}{\epsilon^2 n}$$

*(Aronow and Miller Theorem 3.2.5)*

This allows us to put an upper bound on the probability that the sample mean for a given sample size and known variance will be some arbitrary distance from the true mean.

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  - ▶  $E[\bar{X}_n] = E[X]$  and  $V[\bar{X}_n] = \frac{V[X]}{n}$
  - ▶ We know Bernoulli has variance of  $\pi(1 - \pi)$  which is maximized at  $\pi = .5$ .

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None were outside the range!

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## Definition (Convergence in Probability)

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$$\lim_{n \rightarrow \infty} P[|T_{(n)} - c| \geq \epsilon] = 0$$

We will write this as

$$T_{(n)} \xrightarrow{P} c \quad \text{or} \quad \text{plim}_{n \rightarrow \infty} T_{(n)} = c.$$

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NB: Any continuous function of the sequence itself convergence to the value of the function at the probability limit by the Continuous Mapping Theorem (Aronow and Miller Theorem 3.2.7)

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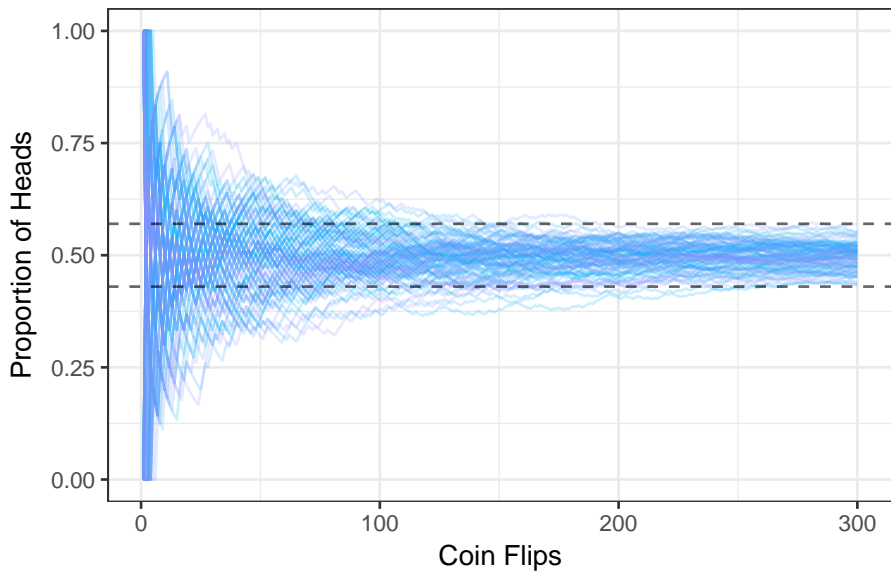
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- The distribution of  $\bar{X}_n$  collapses on  $E[X]$ .
- No assumptions necessary about the distribution of  $X$  beyond i.i.d. sampling and a finite variance!

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Okay that's pretty cool, but we are almost ready to state the coolest result in statistics.

# Convergence in Distribution

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Let  $(T_{(1)}, T_{(2)}, T_{(3)}, \dots)$  be a sequence of random variables with CDFs  $(F_{(1)}, F_{(2)}, F_{(3)}, \dots)$  and let  $T$  be a random variable with CDF  $F_T$ . Then  $T_{(n)}$  **converges in distribution** to  $T$  if for all  $t \in \mathbb{R}$  at which  $F_T$  is continuous

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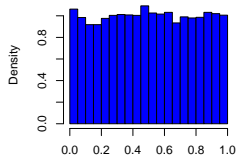
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- This is often called the  $Z$ -score.

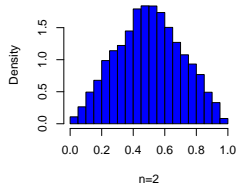


# The Puzzle

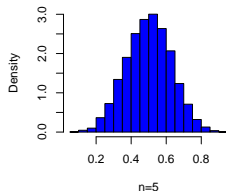
**Population Distribution**



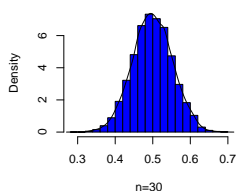
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- NB: the equivalence of the two forms is due to Slutsky's Theorem (see e.g. Aronow and Miller Theorem 3.2.25).

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$$Z = \frac{\bar{X}_n - \pi}{1/\sqrt{4n}} = 2\sqrt{n}(\bar{X}_n - \pi) \sim \mathcal{N}(0, 1)$$

It is easier to work with this standardized variable so:

$$P(|Z| > 0.02(2\sqrt{n})) \leq 0.05$$

# Replanning that Survey

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To solve for  $n$  we plug in the quantile  $P(Z \leq q) = 0.025$  which we can get from the **inverse CDF** of the standard Normal.



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This is **much lower** than the 12,500 from Chebyshev, but that makes sense here because we used **more information**.

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nsims <- 10000
holder <- vector(mode="numeric", length=nsims)
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  my.sample <- rbinom(n=2401, size=1, prob=.55)
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```

We get 0.0485!

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It is okay if you didn't follow all the math here. We will keep coming back to these ideas.

The Central Limit Theorem is deep and amazing. Want to learn more about Central Limit Theorem?

Watch this video (Joe Blitzstein):

<https://www.youtube.com/watch?v=0prNqnHsVIA&list=PLLVp1P80IVc8EtkrD3Q8td0GmId7DjW0&index=31&t=0s>

There are many CLT variants that deal with non-iid random variables as well!



# We Covered...

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Next time: properties of estimators.

# Where We've Been and Where We're Going...

- Last Week
  - ▶ random variables
  - ▶ joint distributions
- This Week
  - ▶ estimators and sampling distributions
  - ▶ estimator properties (bias, variance, consistency)
  - ▶ confidence intervals
- Next Week
  - ▶ hypothesis testing
  - ▶ what is regression?
- Long Run
  - ▶ probability  $\rightarrow$  inference  $\rightarrow$  regression  $\rightarrow$  causal inference

- 1 Estimation
  - Populations and Samples
  - Estimators
  - Analytical
- 2 Weak Law of Large Numbers and the Central Limit Theorem
  - Chebychev's Inequality
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  - The Central Limit Theorem
- 3 Properties of Estimators
  - Four Desirable Properties
  - Example
- 4 Interval Estimation
  - Intervals
  - Large Sample Intervals for a Mean
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  - Interval Estimation for a Proportion
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# Example: The scariest pieces of mail ever!

American Political Science Review

Vol. 102, No. 1 February 2008

DOI: 10.1017/S000305540808009X

## **Social Pressure and Voter Turnout: Evidence from a Large-Scale Field Experiment**

ALAN S. GERBER *Yale University*

DONALD P. GREEN *Yale University*

CHRISTOPHER W. LARIMER *University of Northern Iowa*

<https://doi.org/10.1017/S000305540808009X>

## Example: The scariest pieces of mail ever!

*Voter turnout theories based on rational self-interested behavior generally fail to predict significant turnout unless they account for the utility that citizens receive from performing their civic duty. We distinguish between two aspects of this type of utility, intrinsic satisfaction from behaving in accordance with a norm and extrinsic incentives to comply, and test the effects of priming intrinsic motives and applying varying degrees of extrinsic pressure. A large-scale field experiment involving several hundred thousand registered voters used a series of mailings to gauge these effects. Substantially higher turnout was observed among those who received mailings promising to publicize their turnout to their household or their neighbors. These findings demonstrate the profound importance of social pressure as an inducement to political participation.*

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## Example: The scariest pieces of mail ever!

Dear Registered Voter:

### WHAT IF YOUR NEIGHBORS KNEW WHETHER YOU VOTED?

Why do so many people fail to vote? We've been talking about the problem for years, but it only seems to get worse. This year, we're taking a new approach. We're sending this mailing to you and your neighbors to publicize who does and does not vote.

The chart shows the names of some of your neighbors, showing which have voted in the past. After the August 8 election, we intend to mail an updated chart. You and your neighbors will all know who voted and who did not.

### DO YOUR CIVIC DUTY — VOTE!

---

MAPLE DR	Aug 04	Nov 04	Aug 06
9995 JOSEPH JAMES SMITH	Voted	Voted	_____
9995 JENNIFER KAY SMITH		Voted	_____
9997 RICHARD B JACKSON		Voted	_____
9999 KATHY MARIE JACKSON		Voted	_____

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# Basic Analysis

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They make their data available

(<https://isps.yale.edu/research/data/d001>). We can analyze it.

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load("gerber_green_larimer.RData")
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social$voted <- 1 * (social$voted == "Yes")
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Is this a “real” effect? Is it big?

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- We'd like an estimator that has a known sampling distribution (approximately) when the sample size is large.

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- **Asymptotic Normality**: As our sample size grows large, does the sampling distribution of our estimator approach a normal distribution?

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(not getting the right answer on average)



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An estimator is **unbiased** if and only if:

$$\text{Bias}(\hat{\mu}) = 0$$

# Example: Estimators for Population Mean

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Candidate estimators:

- 1  $\hat{\mu}_1 = Y_1$  (the first observation)
- 2  $\hat{\mu}_2 = \frac{1}{2}(Y_1 + Y_n)$  (average of the first and last observation)
- 3  $\hat{\mu}_3 = 42$
- 4  $\hat{\mu}_4 = \bar{Y}_n$  (the sample average)

How do we choose between these estimators?

# Bias of Example Estimators

Which of these estimators are unbiased?

①  $E[Y_1 - \mu] =$

②  $E[\frac{1}{2}(Y_1 + Y_n) - \mu] =$

③  $E[42 - \mu] =$

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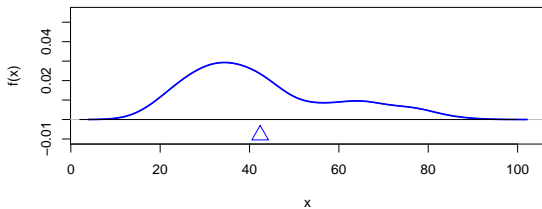
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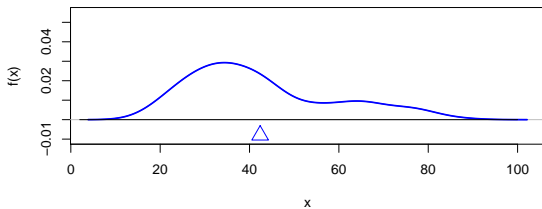
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- Estimator 3 is biased.

## Age population distribution in blue

Sampling Distribution for  $\bar{X}_4$

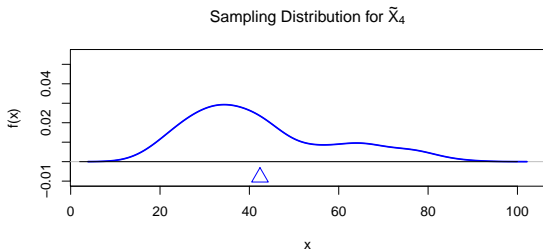
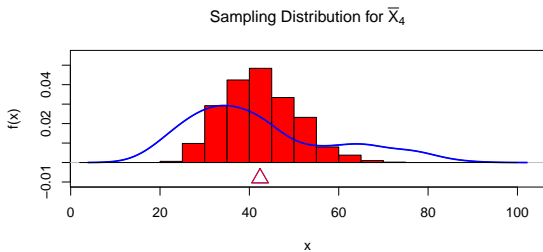


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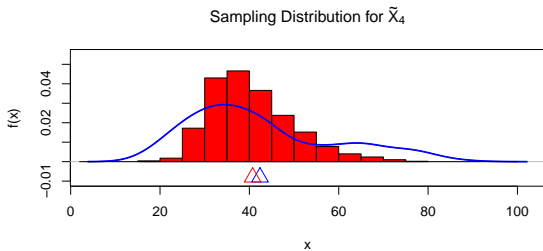
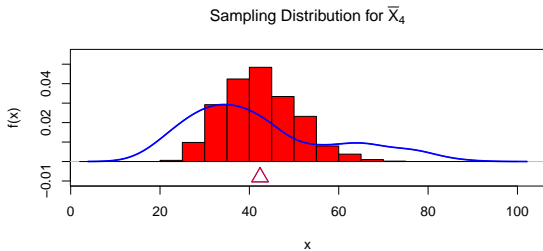




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(doesn't change much sample to sample)

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Aronow and Miller discuss efficiency in terms of MSE (more on this in a second).

# Variance of Example Estimators

What is the variance of our estimators?

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②  $V[\frac{1}{2}(Y_1 + Y_n)] =$

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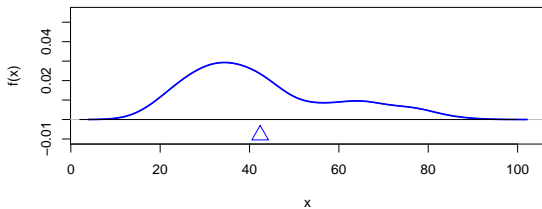
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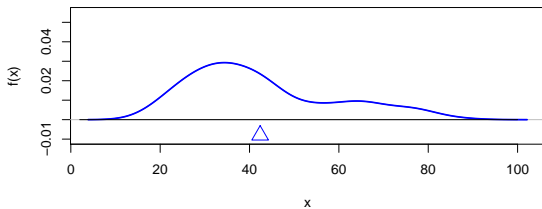
Among the unbiased estimators, the sample average has the smallest variance. This means that Estimator 4 (the sample average) is likely to be closer to the true value  $\mu$ , than Estimators 1 and 2.

## Age population distribution in blue

Sampling Distribution for  $\bar{X}_4$

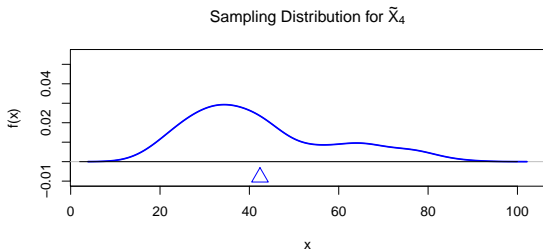
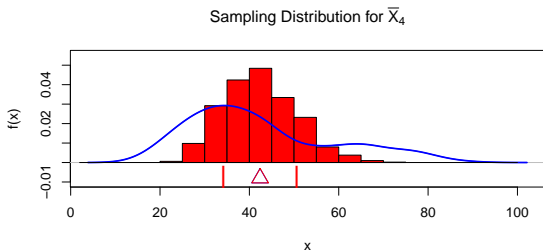


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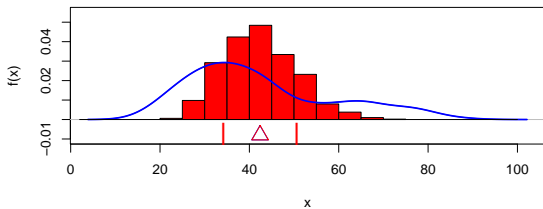


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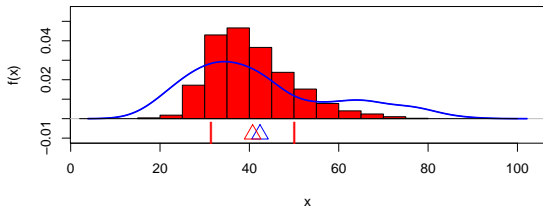


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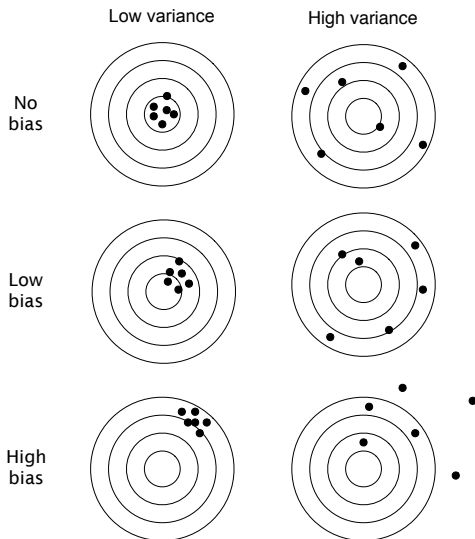
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Sampling Distribution for  $\tilde{X}_4$



# Trading Off Bias and Variance



Salganik (2018), Figure 3.1

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To compare estimators in terms of both efficiency and unbiasedness we can use the **Mean Squared Error** (MSE), the expected squared difference between  $\hat{\theta}$  and  $\theta$ :

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Sometimes (as in Aronow and Miller Definition 3.2.16) efficiency is defined as having lower MSE.

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- Asymptotic properties of an estimator are defined by the behavior of  $\hat{\theta}_1, \dots, \hat{\theta}_n$  when  $n$  goes to infinity.

### 3: Consistency

(does it get closer to the right answer as sample size increases)

#### Definition

An estimator  $\hat{\theta}_n$  is **consistent** if the sequence  $\hat{\theta}_1, \dots, \hat{\theta}_n$  converges in probability to the true parameter value  $\theta$  as sample size  $n$  grows to infinity:

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Our candidate estimators:

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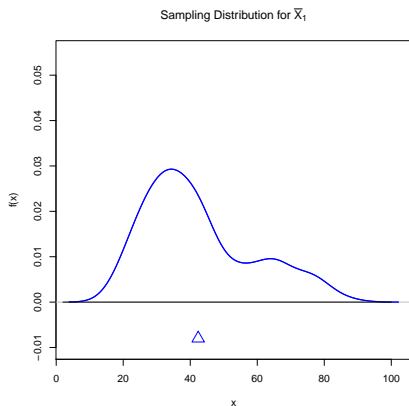
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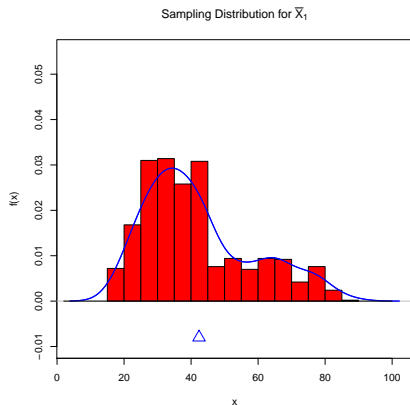
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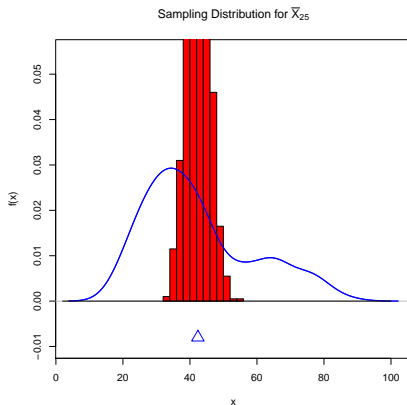
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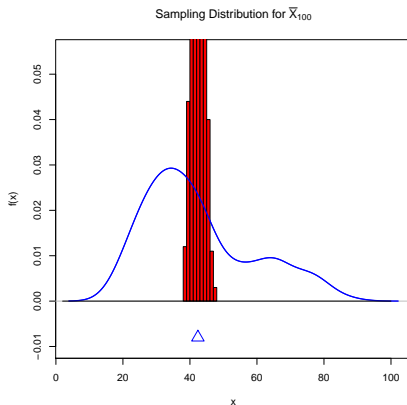
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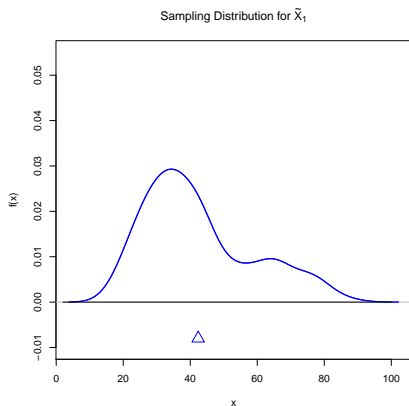
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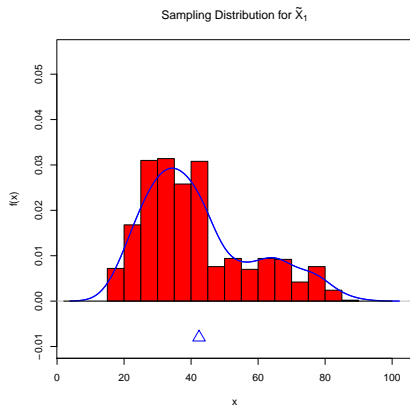
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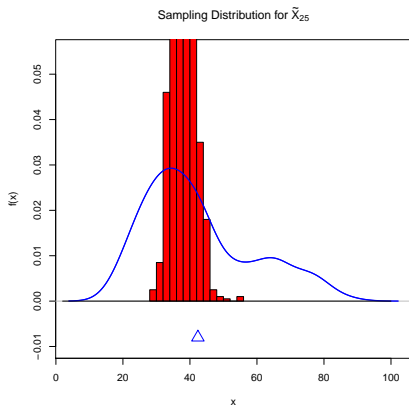
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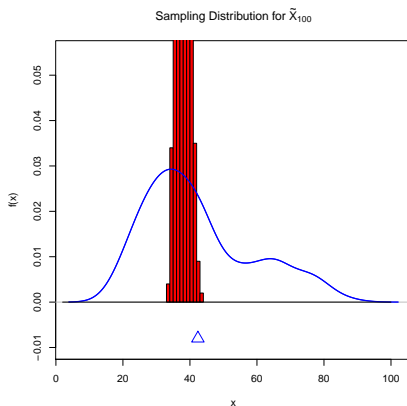
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This will play a crucial role in our ability to form confidence intervals.



# Summary of Properties

Concept	Criteria	Intuition
Unbiasedness	$E[\hat{\mu}] = \mu$	Right on average
Efficiency	$V[\hat{\mu}_1] < V[\hat{\mu}_2]$	Low variance
Consistency	$\hat{\mu}_n \xrightarrow{P} \mu$	Converge to estimand as $n \rightarrow \infty$
Asymptotic Normality	$\hat{\mu}_n \overset{\text{approx.}}{\sim} N(\mu, \frac{\sigma^2}{n})$	Approximately normal in large $n$

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## **Social Pressure and Voter Turnout: Evidence from a Large-Scale Field Experiment**

ALAN S. GERBER *Yale University*

DONALD P. GREEN *Yale University*

CHRISTOPHER W. LARIMER *University of Northern Iowa*

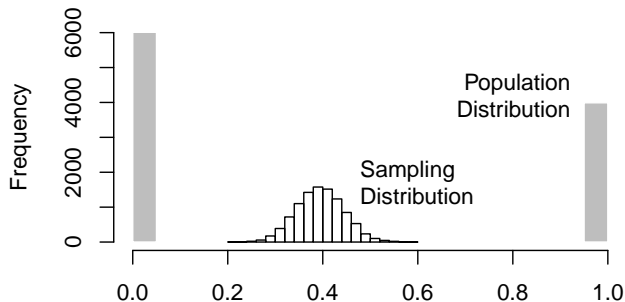
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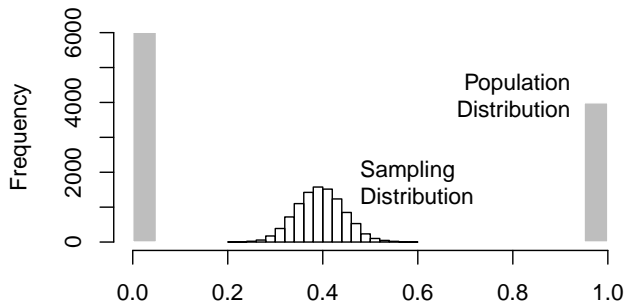
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But remember that we only get to see **one** draw from the sampling distribution. Thus ideally we want an estimator with good **properties**.

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- By the properties of Normals, we know that this implies that  
 $\hat{\theta} \sim \mathcal{N}(0, SE(\hat{\theta}))$

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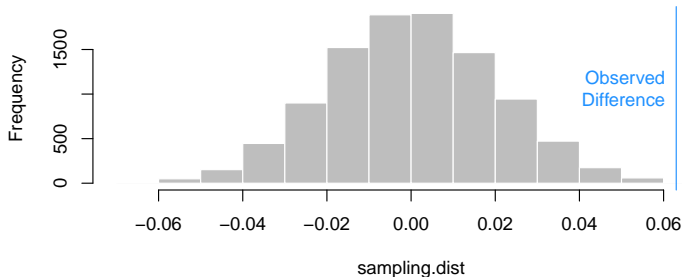


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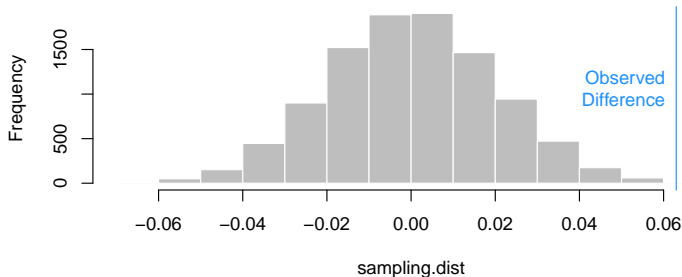
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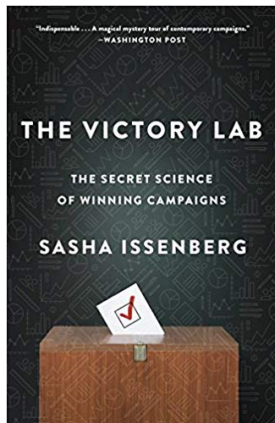
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Does the observed difference in means seem plausible if there really were no difference between the two groups in the population?

## The scariest pieces of mail ever! continued



Summarizes the relationships between political science research and campaigns. Also, attempts to weaponize the results of Gerber et al (2008).

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Next Time: interval estimation

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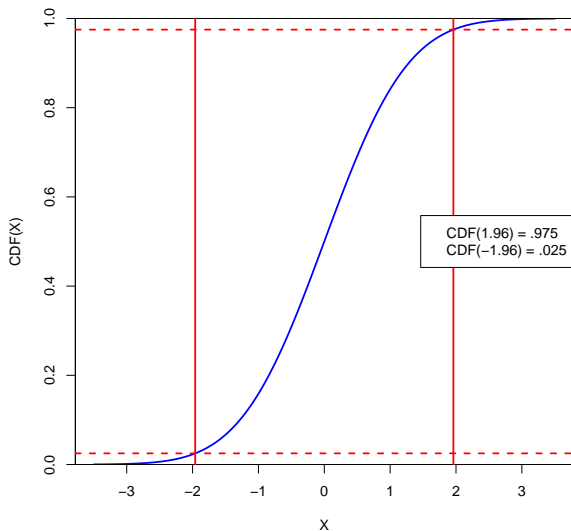
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This implies

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We call this estimator a 95% **confidence interval** for  $\mu$ .

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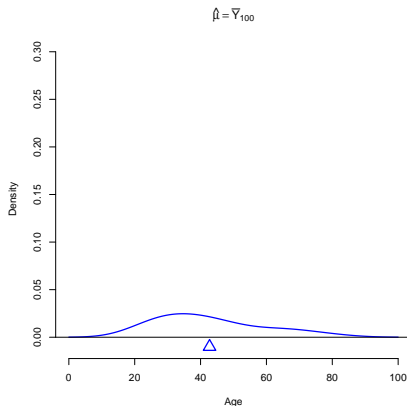
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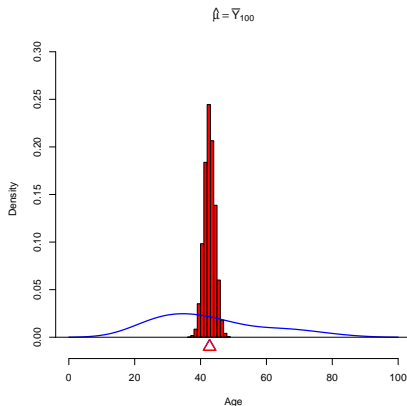
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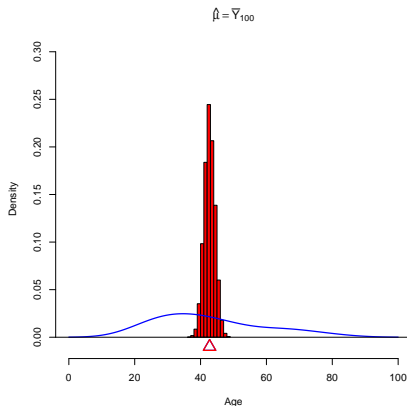
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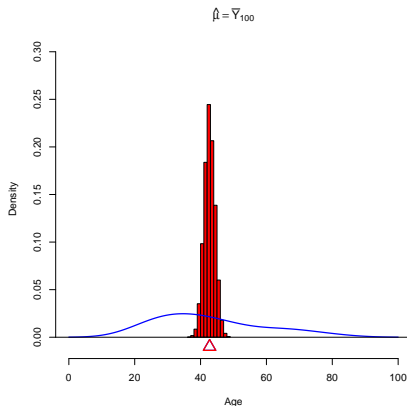
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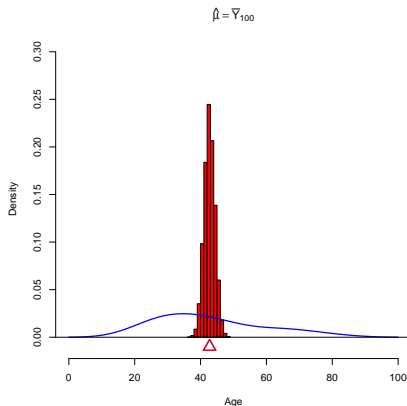
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# The standard error of $\bar{Y}$

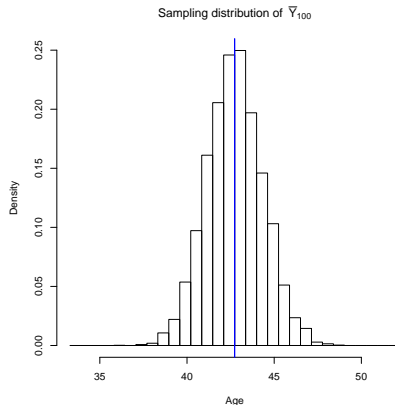
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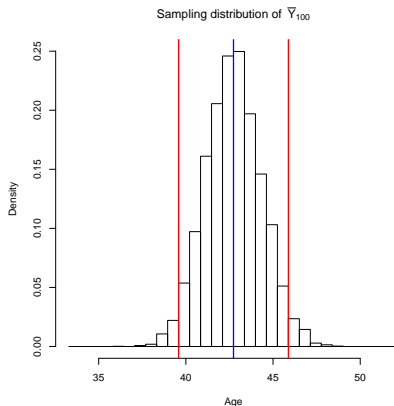


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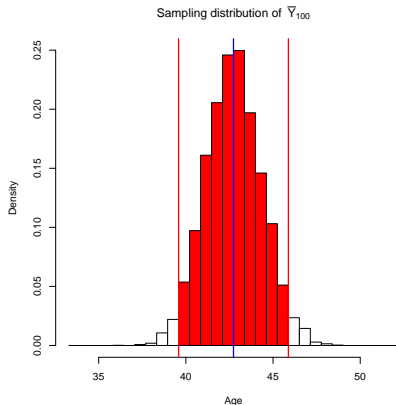


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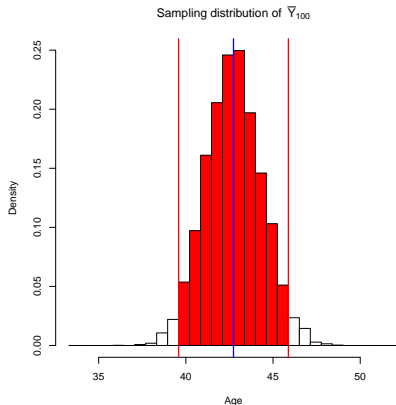


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But we can **not** directly use this now because  $\sigma^2$  is unknown.

## Normal Population with Unknown $\sigma^2$

In practice, it is rarely the case that we somehow know the **true value** of  $\sigma^2$  and our previous example relied on that knowledge.

Suppose now that we have an i.i.d. random sample of size  $n$   $X_1, \dots, X_n$  where  $\sigma^2$  is **unknown**. Then, as before,

$$\bar{X}_n \sim N(\mu, \sigma^2/n) \quad \text{and so} \quad \frac{\bar{X}_n - \mu}{\sigma/\sqrt{n}} \sim N(0, 1).$$

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Instead, we need an **estimator** of  $\sigma^2$ ,  $\hat{\sigma}^2$ .

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$S_{1n}^2$  (unbiased and consistent) is commonly called the **sample variance**.

## Estimating $\sigma$ and the SE

Returning to Kulinski et. al. . .

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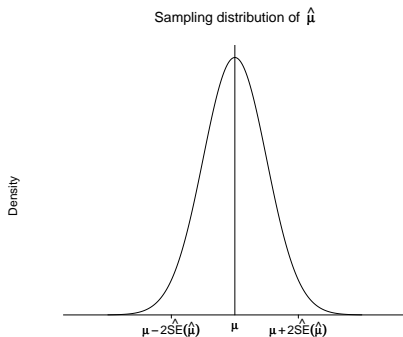
We will plug in  $S$  for  $\sigma$  and our estimated standard error will be

$$\widehat{SE}[\hat{\mu}] = \frac{S}{\sqrt{n}}$$

# 95% Confidence Intervals

If  $X_1, \dots, X_n$  are i.i.d. and  $n$  is large, then

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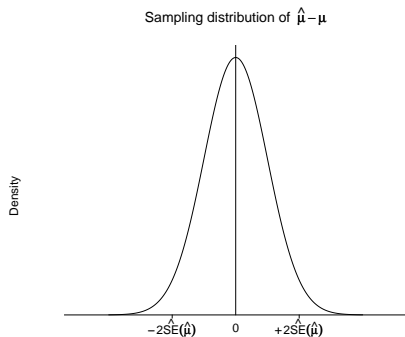


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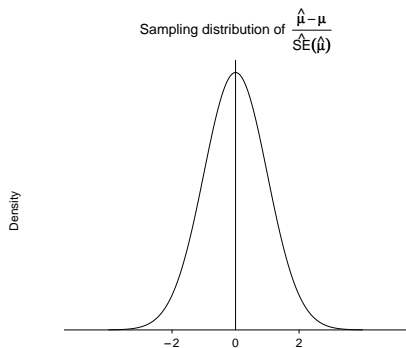
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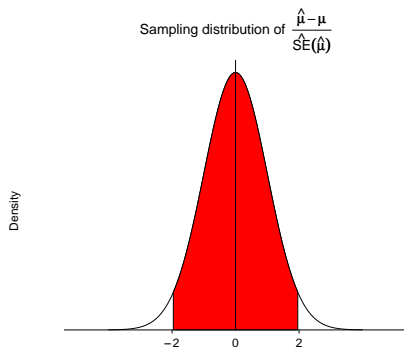
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We can work backwards from this:

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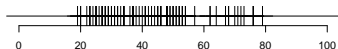
The random quantities in this statement are  $\hat{\mu}$  and  $\widehat{SE}[\hat{\mu}]$ .  
Once the data are observed, nothing is random!



# What does this mean?

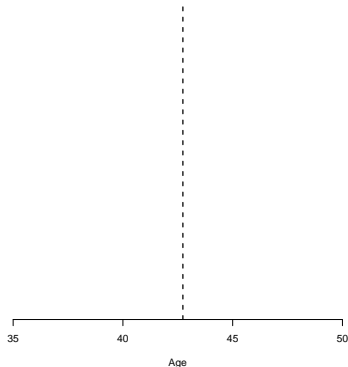
We can simulate this process using the Kuklinski data:

- 1) Draw a sample of size 100:



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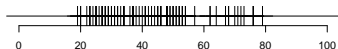
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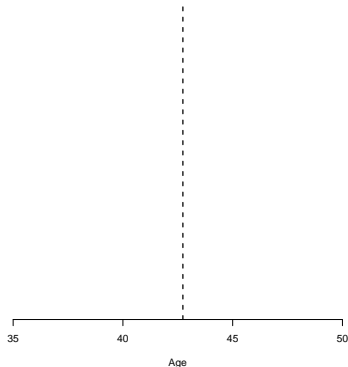
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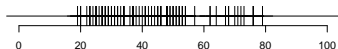
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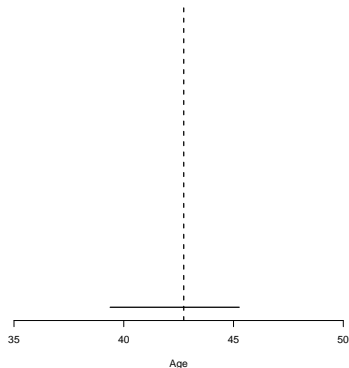


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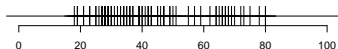
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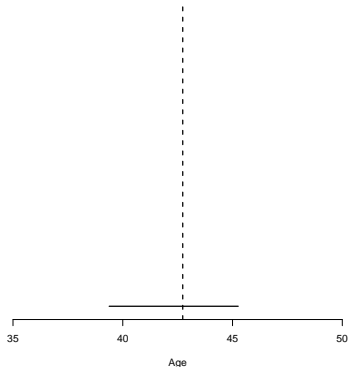
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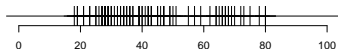
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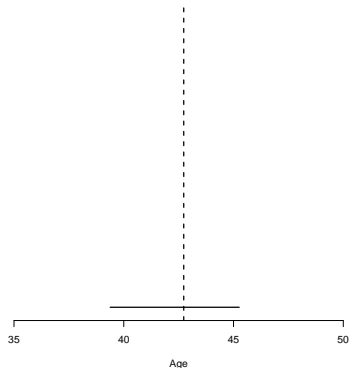
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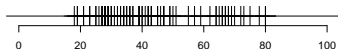
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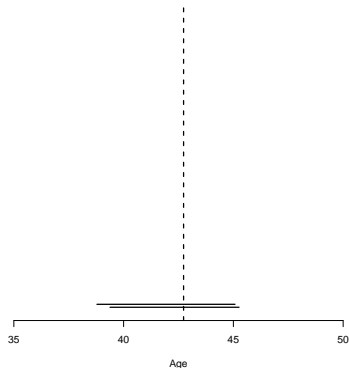


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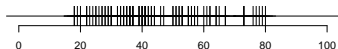
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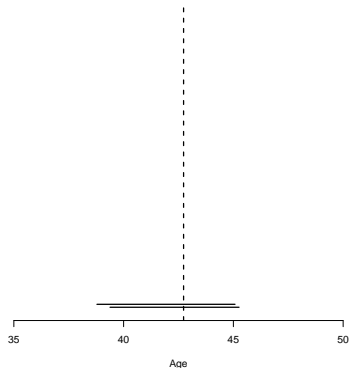
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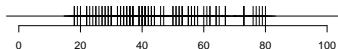
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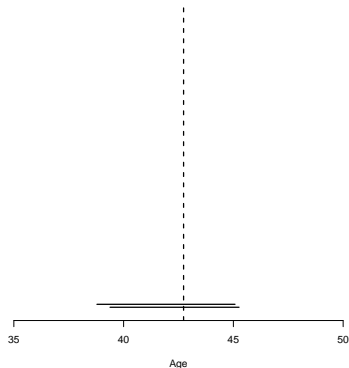
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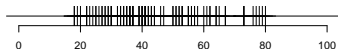




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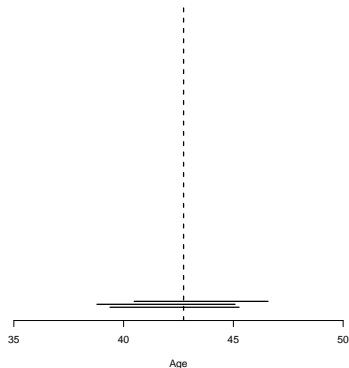


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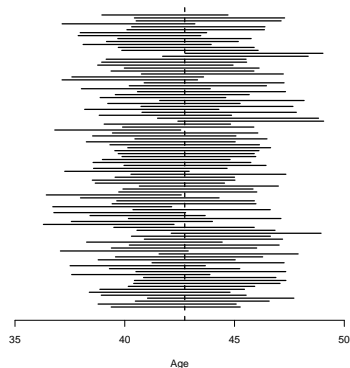
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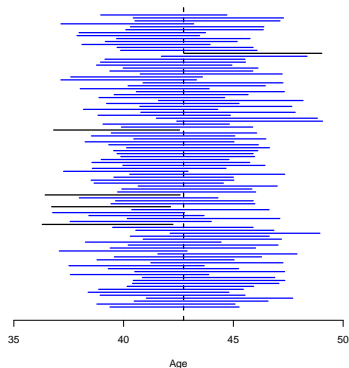
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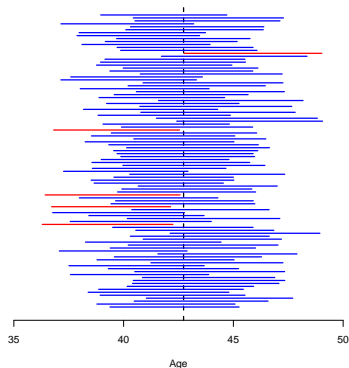
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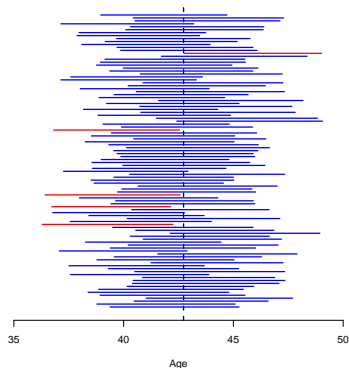


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In the long run, we expect 95% of the CIs generated to contain the true value.



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  - ▶ Therefore, we refer to .95 as the **coverage probability**

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- You want the the shortest confidence interval with the desired coverage probability.

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$$P\left(-z \leq \frac{\hat{\mu} - \mu}{\widehat{SE}[\hat{\mu}]} \leq z\right) = (1 - \alpha)\%$$

How can we find  $z$ ?

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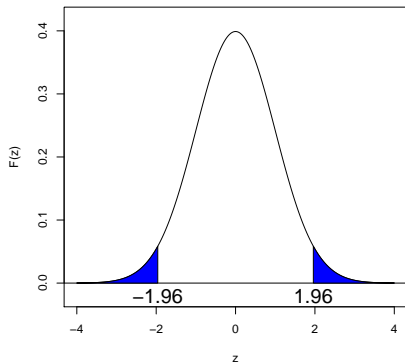
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This gives us a value of 1.96 for  $z$ .



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What if we want a 50% confidence interval?

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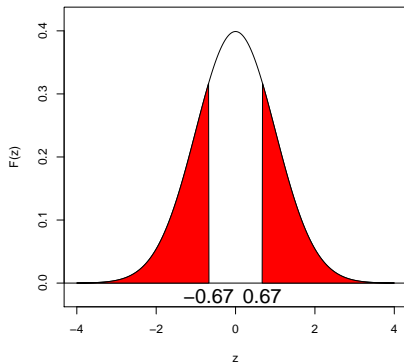
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# Statistical problems emerge from real science



Comparing different methods of growing barley (Full history:

<https://www.jstor.org/stable/2245613>)

<https://en.wikipedia.org/wiki/Guinness#/media/File:Guinness.jpg>

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When the sample size is small, we need to know something about the distribution in order to construct confidence intervals with the correct coverage (because we can't appeal to the CLT or assume that  $S$  is a good approximation of  $\sigma$ ).

# BIOMETRIKA.

---

## THE PROBABLE ERROR OF A MEAN.

By STUDENT.

<https://www.jstor.org/stable/2331554>

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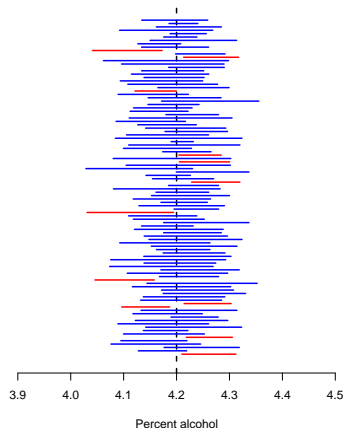
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We rarely know  $\sigma$  and have to use an estimate instead:

$$\frac{\bar{X} - \mu}{\frac{s}{\sqrt{n}}} \sim t_{n-1}$$

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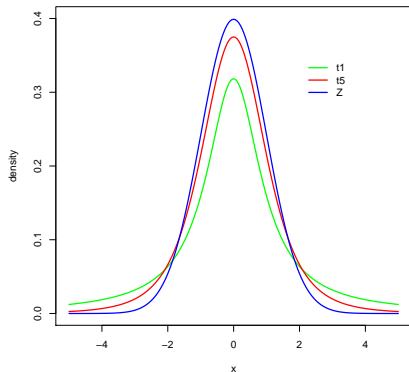
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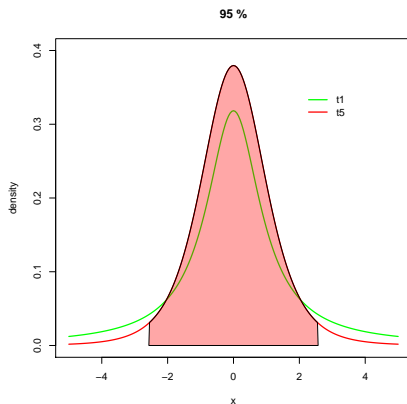


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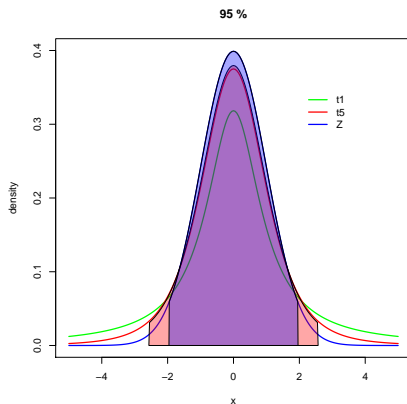


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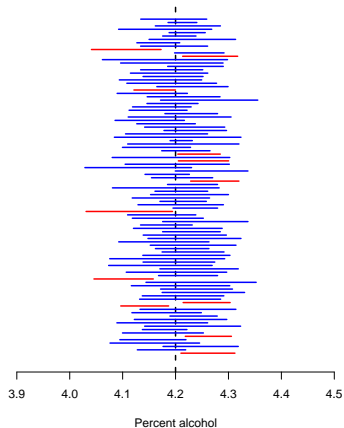
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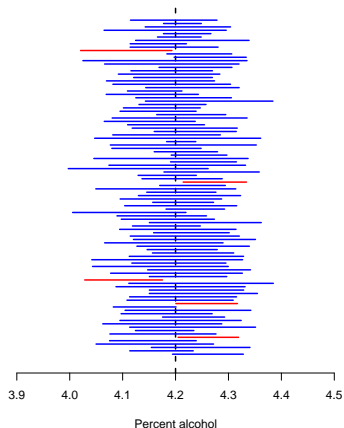
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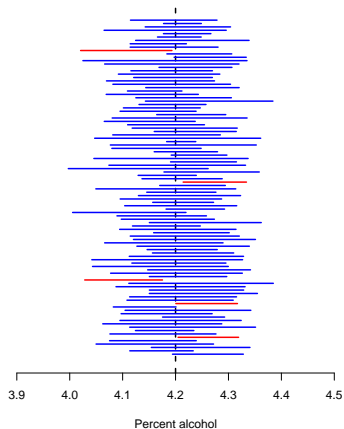
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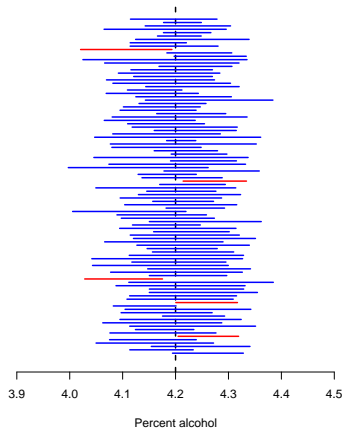
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95 of the 100 CIs in this sample cover the truth.



## Another Rationale for the $t$ -Distribution

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Thus, we need to derive the sampling distribution of the new random variable. It turns out that  $T_n$  follows **Student's  $t$ -distribution** with  $n - 1$  **degrees of freedom**.

### Theorem (Distribution of $t$ -Value from a Normal Population)

*Suppose we have an i.i.d. random sample of size  $n$  from  $N(\mu, \sigma^2)$ . Then, the sample mean  $\bar{X}_n$  standardized with the estimated standard error  $S_n/\sqrt{n}$  satisfies,*

$$T_n \equiv \frac{\bar{X}_n - \mu}{S_n/\sqrt{n}} \sim \tau_{n-1}$$

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We will usually be interested in comparing  $\mu_1$  to  $\mu_2$ , although we will sometimes need to compare  $\sigma_1^2$  to  $\sigma_2^2$  in order to make the first comparison.

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## CIs for $\mu_1 - \mu_2$

Using the same type of argument that we used for the univariate case, we write a  $(1 - \alpha)\%$  CI as the following:

$$\bar{X}_1 - \bar{X}_2 \pm z_{\alpha/2} \sqrt{\frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}}$$

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- **Problem** Show that the sample proportion,  $\hat{\pi} = \frac{1}{n} \sum_{i=1}^n Y_i$ , of the above iid Bernoulli sample, is unbiased for the true population proportion,  $\pi$ , and that the sampling variance is equal to  $\frac{\pi(1-\pi)}{n}$ .

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- Note that if we have an estimate of the population proportion,  $\hat{\pi}$ , then we also have an estimate of the sampling variance:  $\frac{\hat{\pi}(1-\hat{\pi})}{n}$ .
- Given the facts from the previous problem, we just apply the same logic from the population mean to show the following confidence interval:

$$P \left( \hat{\pi} - z_{\alpha/2} \times \sqrt{\frac{\hat{\pi}(1 - \hat{\pi})}{n}} \leq \pi \leq \hat{\pi} + z_{\alpha/2} \times \sqrt{\frac{\hat{\pi}(1 - \hat{\pi})}{n}} \right) = (1 - \alpha)$$

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**TABLE 2. Effects of Four Mail Treatments on Voter Turnout in the August 2006 Primary Election**

	Experimental Group				
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- Let's use what we have learned up until now and the information in the table to calculate a 95% confidence interval for the difference in proportions voting between the Neighbors group and the Civic Duty group.

## Gerber, Green, and Larimer experiment

Let's go back to the Gerber, Green, and Larimer experiment from last class. Here are the results of their experiment:

**TABLE 2. Effects of Four Mail Treatments on Voter Turnout in the August 2006 Primary Election**

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- You may assume that the samples within each group are iid and the two samples are independent.



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- Remember that we can calculate the sample variance for a sample proportion like so:  $(\hat{\pi}_C(1 - \hat{\pi}_C))/n_C$

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```
n.n <- 38201
samp.var.n <- (0.378 * (1 - 0.378))/n.n
n.c <- 38218
samp.var.c <- (0.315 * (1 - 0.315))/n.c
se.diff <- sqrt(samp.var.n + samp.var.c)
## lower bound
(0.378 - 0.315) - 1.96 * se.diff
## [1] 0.05626701
## upper bound
(0.378 - 0.315) + 1.96 * se.diff
## [1] 0.06973299
```

Thus, the confidence interval for the effect is [0.056267, 0.069733].



We can use our analytic samples to find a confidence interval

$$CI(\alpha) = [r - z_{\alpha/2} * SE, r + z_{\alpha/2} * SE]$$

Our estimate

Alpha

Standard error of our estimate

Critical value

$\alpha/2$  because we're looking for a two-sided interval

# Review

To use the confidence interval formula, we need to find:

1. The distribution
2. Confidence level
  - Alpha
3. Sidedness
4. Critical value(s)
5. Standard error of our estimate

```
##Calculating our critical value  
cv <- qnorm(.975)  
cv  
  
## [1] 1.959964
```

for a proportion, the formula is:

$$SE(\hat{p}) = \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}$$

```
##Finding the standard error of our estimate  
se <- sqrt(red.sample*(1-red.sample)/n.samp)  
se  
  
## [1] 0.01966499
```

## Calculating the confidence interval

$$CI(\alpha) = [r - z_{\alpha/2} * SE, r + z_{\alpha/2} * SE]$$

```
##Finding and printing the confidence interval  
c(red.sample - cv*se,  
  red.sample + cv*se)
```

```
## [1] 0.2234573 0.3005427
```

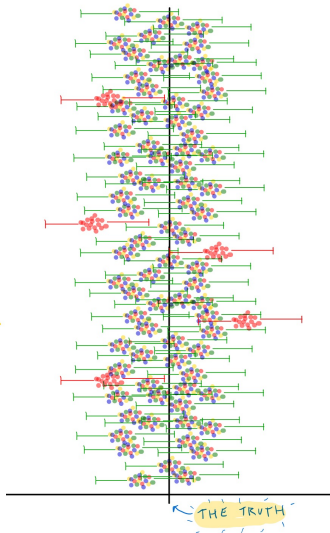
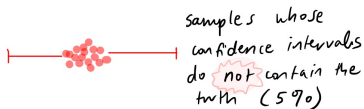
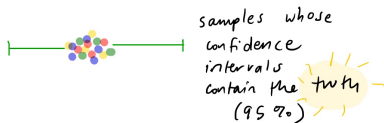
## Our results

26.2% red with a 95 percent  
confidence interval of **[22.3, 30.1]**



# Review

We hope our  
sample is in  
the 95%



# We Covered...

## We Covered. . .

- Interval estimates provide a means of assessing uncertainty.

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Next Time:

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Next Time: The plug-in principle!

# Where We've Been and Where We're Going...

- Last Week
  - ▶ random variables
  - ▶ joint distributions
- This Week
  - ▶ estimators and sampling distributions
  - ▶ estimator properties (bias, variance, consistency)
  - ▶ confidence intervals
- Next Week
  - ▶ hypothesis testing
  - ▶ what is regression?
- Long Run
  - ▶ probability  $\rightarrow$  inference  $\rightarrow$  regression  $\rightarrow$  causal inference

- 1 Estimation
  - Populations and Samples
  - Estimators
  - Analytical
- 2 Weak Law of Large Numbers and the Central Limit Theorem
  - Chebychev's Inequality
  - Weak Law of Large Numbers
  - The Central Limit Theorem
- 3 Properties of Estimators
  - Four Desirable Properties
  - Example
- 4 Interval Estimation
  - Intervals
  - Large Sample Intervals for a Mean
  - Small Sample Intervals for a Mean
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  - Interval Estimation for a Proportion
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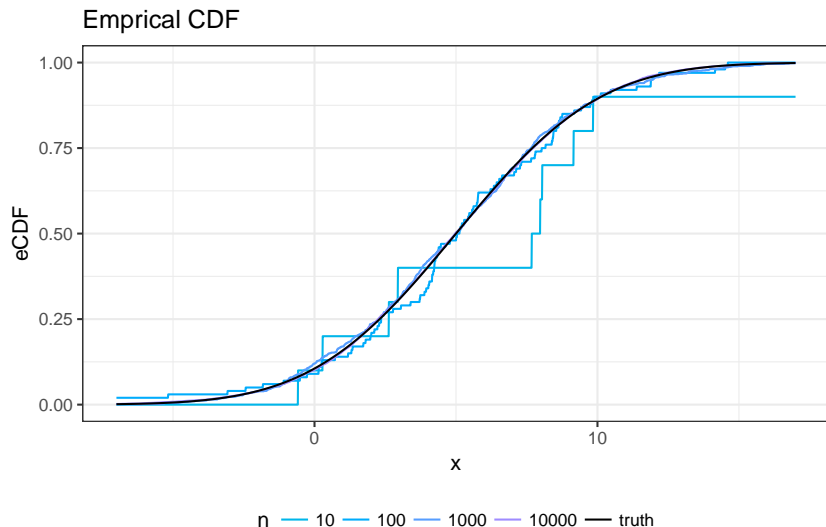
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- Ex: If we're interested in the population mean, we use the sample mean
- This is justified because of the **plug-in principle**.
- The Weak Law of Large Numbers tells us that the **empirical CDF** is a good sample analog of the true CDF (which fully describes a distribution).

# The Plug-in Principle in Action

Say we have a  $\mathcal{N}(5, 4)$  distribution



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if  $T$  is well-behaved, then  $\hat{\theta}$  is also asymptotically normal.

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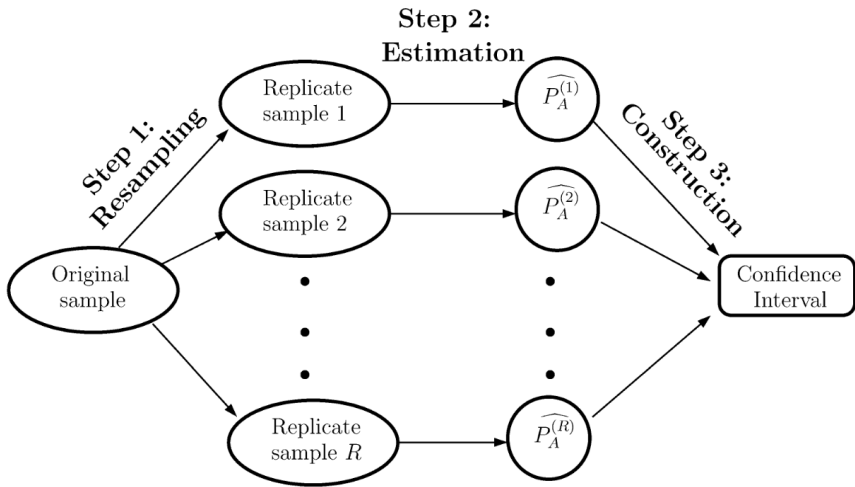
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# Bootstrapped Sampling Distributions

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What if there was a way to replacing analytical derivations, which can be hard, with computer simulations which are easy?

The plug-in principle gives us a way forward.



Source: Salganik (2006)

This works for almost\* any estimator

\*basically it works when plug-in estimation works

*Statistical Science*  
1986, Vol. 1, No. 1, 54-77

# **Bootstrap Methods for Standard Errors, Confidence Intervals, and Other Measures of Statistical Accuracy**

**B. Efron and R. Tibshirani**

Efron and Tibshirani (1986), <http://www.jstor.org/stable/2245500>



# The Bootstrap

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**Bootstrap:** Use the eCDF as a plug-in for the CDF, and **resample** from that. I.e. we are pretending our sample eCDF looks sufficiently close to our true CDF, and so we're sampling from the eCDF as an approximation to repeated sampling from the true CDF. This is called a **resampling** method.

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- 2 Calculate our would-be estimate using this **bootstrap sample**.
- 3 Repeat steps 1 and 2 many (B) times.
- 4 Using the resulting collection of **bootstrap estimates**, calculate the standard deviation of the **bootstrap distribution** of our estimator. This serves our estimate of the standard deviation of the **sampling distribution**

## Example of a Bootstrap

```
samp <- c(9.7, 4.99, 5.9, 3.58, 8.15, 5.54, 4.77, 5.01, 4.89,  
          3.42, 8.63, 7.17, 8.93, 7.5, 4.93, 8.6, 6.26, 7.31,  
          8.96, 3.95)
```

```
obs_mean = mean(samp)
```

```
obs_mean
```

```
## [1] 6.4095
```

## Example of a Bootstrap

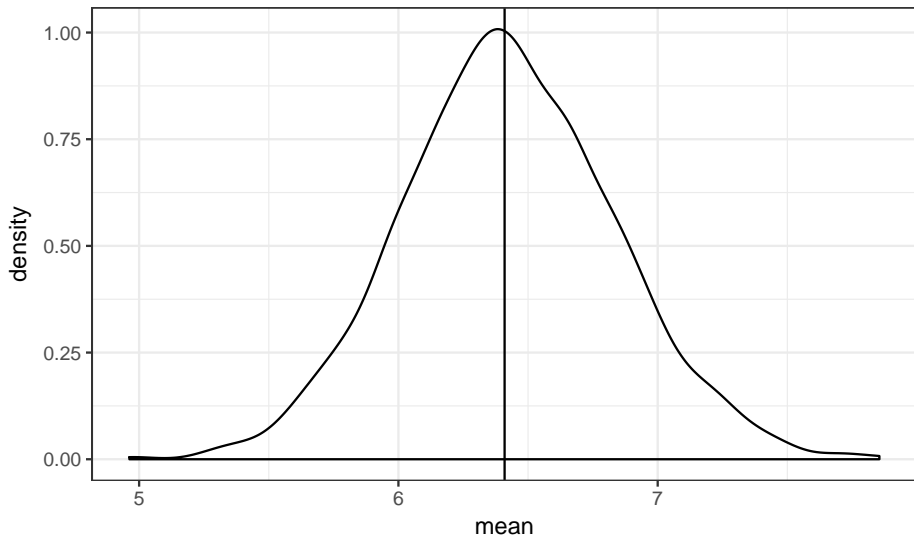
```
# resample WITH REPLACEMENT reps times
# recalculate the mean within each bootstrap replicate
boot_samp_dist <- replicate(2000, {
  mean(samp[sample.int(length(samp), replace = TRUE)])
})
```

```
ggplot(tibble(boot_samp_dist = boot_samp_dist),
  aes(x = boot_samp_dist)) +
  geom_density() +
  geom_vline(xintercept = obs_mean) +
  theme_bw() + ggtitle("Bootstrap Sampling Distribution
  For the Sample Mean") +
  xlab("mean")
```



## Example of a Bootstrap

Bootstrap Sampling Distribution  
For the Sample Mean



# Two ways to calculate bootstrap intervals

## Two ways to calculate bootstrap intervals

- 1) Using **normal** approximation intervals, use the estimates from step 4.

$$\left[ \bar{X} - \Phi^{-1}(1 - \alpha/2) * \hat{\sigma}_{\text{boot}}, \bar{X} + \Phi^{-1}(1 - \alpha/2) * \hat{\sigma}_{\text{boot}} \right]$$

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- 2) **Percentile** method for the CI: Sort  $B$  bootstrap estimates from smallest to largest.  $\alpha$  interval is constructed as

$$CI_{1-\alpha} = [\alpha/2 * B \text{ sample}, (1 - \alpha/2) * B \text{ sample}]$$

- ▶ Percentile method does not rely on normal approximation, and behaves better with small  $n$ .

We covered

## We covered

- The plug-in principle.

## We covered

- The plug-in principle.
- The bootstrap.



## We covered

- The plug-in principle.
- The bootstrap.
- We will return to both in future weeks.

# This Week in Review

- Estimation!
- Central Limit Theorem!
- Properties of Estimators!
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Going Deeper:

Aronow and Miller (2019) *Foundations of Agnostic Statistics*.  
Cambridge University Press. Chapter 3.

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Next week: hypothesis testing and regression!