

Week 12: Repeated Observations and Panel Data

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¹These slides are heavily influenced by Matt Blackwell, Adam Glynn, Jens Hainmueller, and Erin Hartman.

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

- 1 Differencing Models
- 2 Difference-in-Differences
- 3 Fixed Effects
- 4 Non-parametric Identification and Fixed Effects
- 5 Wrap-Up
 - Questions
 - Concluding Thoughts for the Course

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 - ▶ possess some cultural trait correlated with better health outcomes
- If we have data on countries over time, can we make any progress in spite of these problems?

Ross Data

```
##      cty_name year democracy infmort_unicef
## 1 Afghanistan 1965         0             230
## 2 Afghanistan 1966         0              NA
## 3 Afghanistan 1967         0              NA
## 4 Afghanistan 1968         0              NA
## 5 Afghanistan 1969         0              NA
## 6 Afghanistan 1970         0             215
```

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- Time is a typical application, but applies to other groupings:
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- NB: we won't be using T for treatment today because it is extremely consistently used for time. We will end up using D for treatment which is another common letter for treatment.

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- **Time series, cross-sectional (TSCS) data**: smaller n , large T
- We are primarily going to focus on similarities today but there are some differences.

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We will start by considering performance of estimators assuming this model is true.

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 - ① Heteroskedasticity (see clustering from diagnostics week)
 - ② Possible violation of zero conditional mean errors
- Both problems arise out of ignoring the **unmeasured heterogeneity** inherent in a_i

Pooled OLS with Ross data

```
pooled.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur),
                 data = ross)
summary(pooled.mod)

##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  9.76405    0.34491   28.31  <2e-16 ***
## democracy   -0.95525    0.06978  -13.69  <2e-16 ***
## log(GDPcur) -0.22828    0.01548  -14.75  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.7948 on 646 degrees of freedom
## (5773 observations deleted due to missingness)
## Multiple R-squared:  0.5044, Adjusted R-squared:  0.5029
## F-statistic: 328.7 on 2 and 646 DF,  p-value: < 2.2e-16
```

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- Ignore the heterogeneity \rightsquigarrow **correlation between the combined error and the independent variables:**

$$E[v_{it}|\mathbf{X}] = E[a_i + u_{it}|\mathbf{X}] \neq 0$$

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- Pooled OLS will be **biased and inconsistent** because zero conditional mean error fails for the combined error.

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- Two time periods:

$$y_{i1} = \mathbf{x}'_{i1}\boldsymbol{\beta} + a_i + u_{i1}$$

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$$\Delta y_i = y_{i2} - y_{i1}$$

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$$= (\mathbf{x}'_{i2}\boldsymbol{\beta} + a_i + u_{i2}) - (\mathbf{x}'_{i1}\boldsymbol{\beta} + a_i + u_{i1})$$

$$= (\mathbf{x}'_{i2} - \mathbf{x}'_{i1})\boldsymbol{\beta} + (a_i - a_i) + (u_{i2} - u_{i1})$$

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- Due to 'no perfect collinearity': \mathbf{x}_{it} has to change over time for **some** units. High variance if its slow moving.
- Differencing will **reduce** the variation in the independent variables and thus **increase** standard errors.

First Differences in R (via plm package)

```
library(plm)

fd.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur), data = ross,
              index = c("id", "year"), model = "fd")

summary(fd.mod)

## Oneway (individual) effect First-Difference Model
##
## Call:
## plm(formula = log(kidmort_unicef) ~ democracy + log(GDPcur),
##      data = ross, model = "fd", index = c("id", "year"))
##
## Unbalanced Panel: n=166, T=1-7, N=649
##
## Residuals :
##      Min. 1st Qu.  Median 3rd Qu.    Max.
## -0.9060 -0.0956  0.0468  0.1410  0.3950
##
## Coefficients :
##              Estimate Std. Error t-value Pr(>|t|)
## (intercept) -0.149469   0.011275 -13.2567 < 2e-16 ***
## democracy   -0.044887   0.024206  -1.8544  0.06429 .
## log(GDPcur) -0.171796   0.013756 -12.4886 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Total Sum of Squares:    23.545
## Residual Sum of Squares: 17.762
## R-Squared      : 0.24561
##      Adj. R-Squared : 0.24408
## F-statistic: 78.1367 on 2 and 480 DF, p-value: < 2.22e-16
```

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Next Time: Difference-in-Differences

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Motivation: Studying the Minimum Wage

Minimum Wages and Employment: A Case Study of the Fast-Food Industry in New Jersey and Pennsylvania

By DAVID CARD AND ALAN B. KRUEGER*

On April 1, 1992, New Jersey's minimum wage rose from \$4.25 to \$5.05 per hour. To evaluate the impact of the law we surveyed 410 fast-food restaurants in New Jersey and eastern Pennsylvania before and after the rise. Comparisons of employment growth at stores in New Jersey and Pennsylvania (where the minimum wage was constant) provide simple estimates of the effect of the higher minimum wage. We also compare employment changes at stores in New Jersey that were initially paying high wages (above \$5) to the changes at lower-wage stores. We find no indication that the rise in the minimum wage reduced employment. (JEL J30, J23)

<https://www.jstor.org/stable/2118030>

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 - ▶ Wave 1: March 1992, one month before the minimum wage increased
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- Based on survey data:
 - ▶ Wave 1: March 1992, one month before the minimum wage increased
 - ▶ Wave 2: December 1992, eight months after increase
- “What would a skeptic consider convincing evidence?” David Card
- “There was a time when we thought econometric techniques would solve a lot of the data problems. Now I think the feeling is that there are a lot of problems for which it is easier to get better data.” Alan Krueger

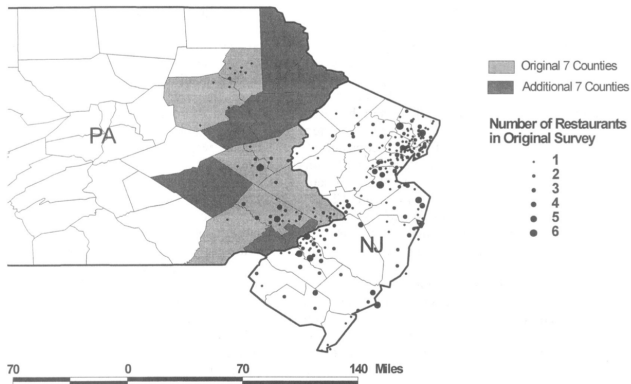


FIGURE 1. AREAS OF NEW JERSEY AND PENNSYLVANIA COVERED BY ORIGINAL SURVEY AND BLS DATA

Source: Card and Krueger 2000

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- $I(t = 2)$ is a dummy variable for the second time period
- β_1 is the quantity of interest: it's the effect of being treated

Diff-in-Diff Mechanics

- Let's take differences:

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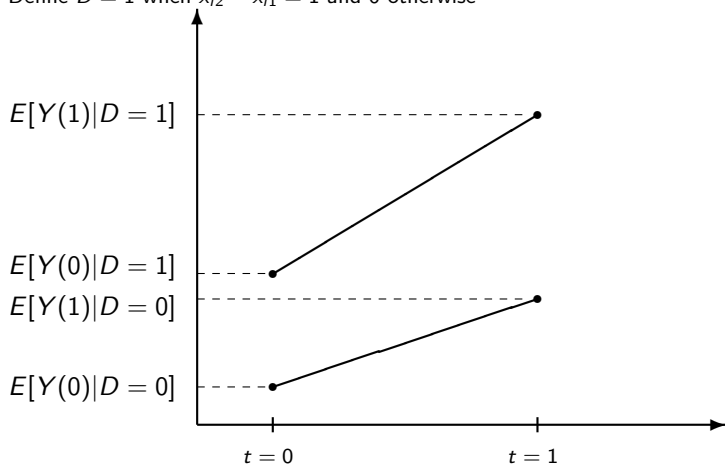
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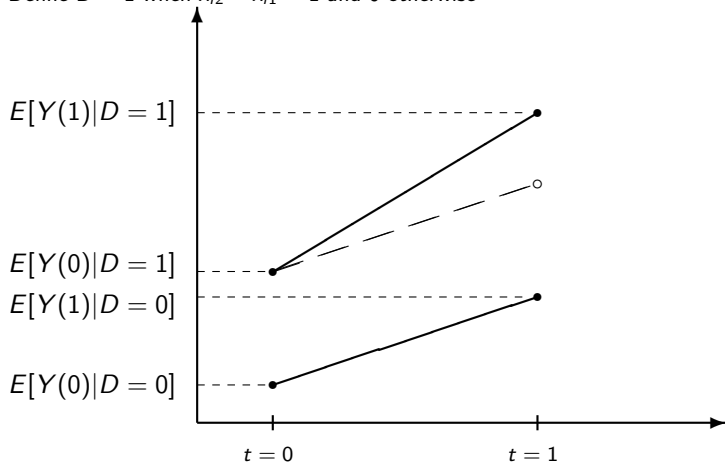
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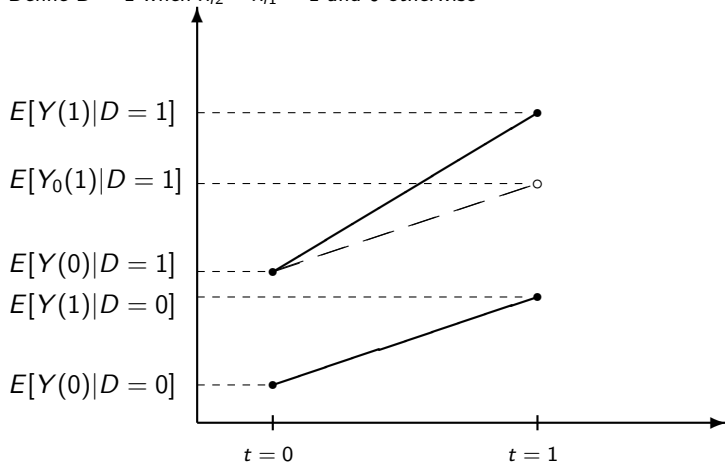
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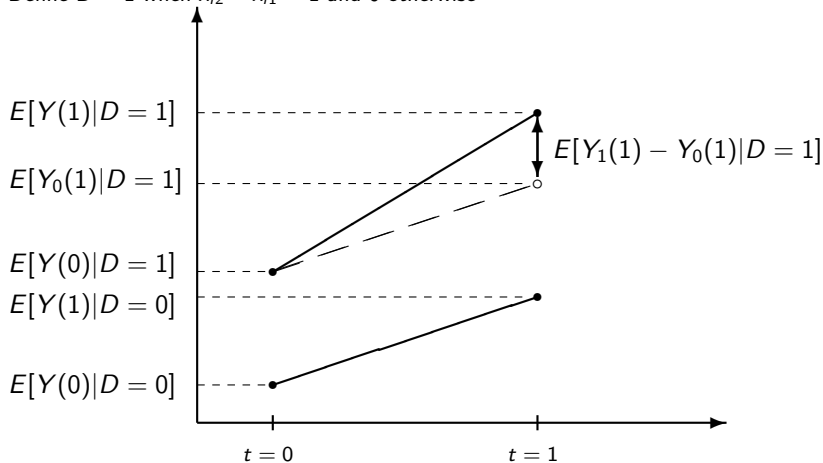
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Identification with Difference-in-Differences

Identification Assumption (parallel trends)

$$E[Y_0(1) - Y_0(0)|D = 1] = E[Y_0(1) - Y_0(0)|D = 0]$$

Identification Result

Given parallel trends the ATT is identified as:

$$\begin{aligned} E[Y_1(1) - Y_0(1)|D = 1] &= \left\{ E[Y(1)|D = 1] - E[Y(1)|D = 0] \right\} \\ &\quad - \left\{ E[Y(0)|D = 1] - E[Y(0)|D = 0] \right\} \end{aligned}$$

Identification with Difference-in-Differences

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Proof.

Note that the identification assumption implies

$$E[Y_0(1)|D = 0] = E[Y_0(1)|D = 1] - E[Y_0(0)|D = 1] + E[Y_0(0)|D = 0]$$

plugging in we get

$$\begin{aligned} & \{E[Y(1)|D = 1] - E[Y(1)|D = 0]\} - \{E[Y(0)|D = 1] - E[Y(0)|D = 0]\} \\ = & \{E[Y_1(1)|D = 1] - E[Y_0(1)|D = 0]\} - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & \{E[Y_1(1)|D = 1] - (E[Y_0(1)|D = 1] - E[Y_0(0)|D = 1] + E[Y_0(0)|D = 0])\} \\ & - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & E[Y_1(1) - Y_0(1)|D = 1] + \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ & - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & E[Y_1(1) - Y_0(1)|D = 1] \end{aligned}$$



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- DiD works for **additive** and **time-invariant** confounding (i.e. satisfies parallel trends)

Does Indiscriminate Violence Incite Insurgent Attacks?

Evidence from Chechnya

Jason Lyall

*Department of Politics and the Woodrow Wilson School
Princeton University, New Jersey*

Journal of Conflict Resolution

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- Counterintuitive findings: shelled villages experience a 24% reduction in insurgent attacks relative to controls.

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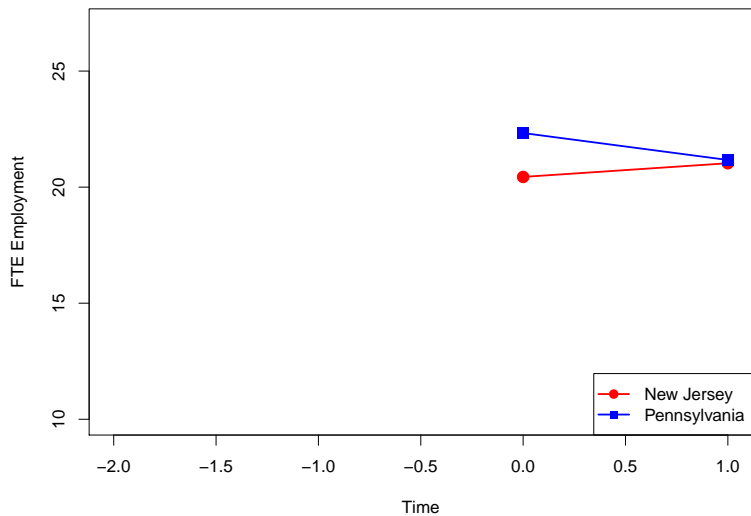
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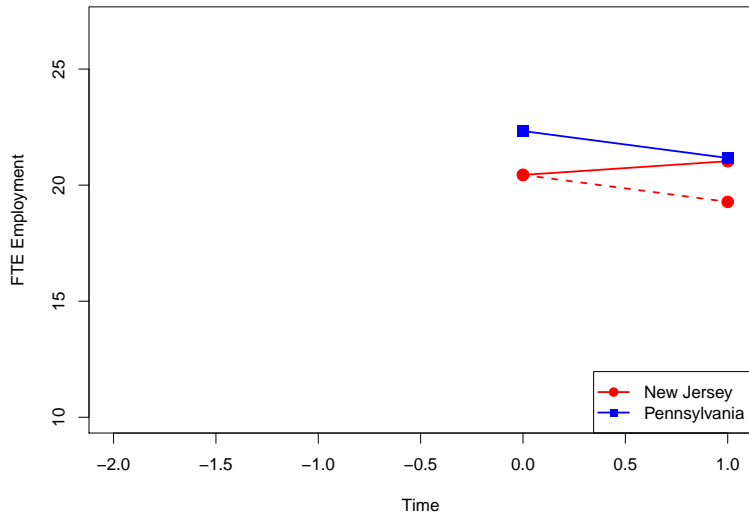
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- NJ_i indicates which stores received the treatment of a higher minimum wage at time period $t = 2$

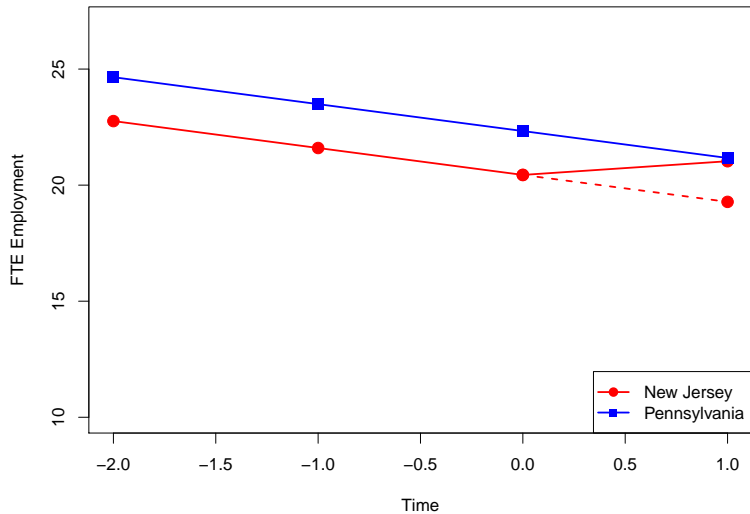
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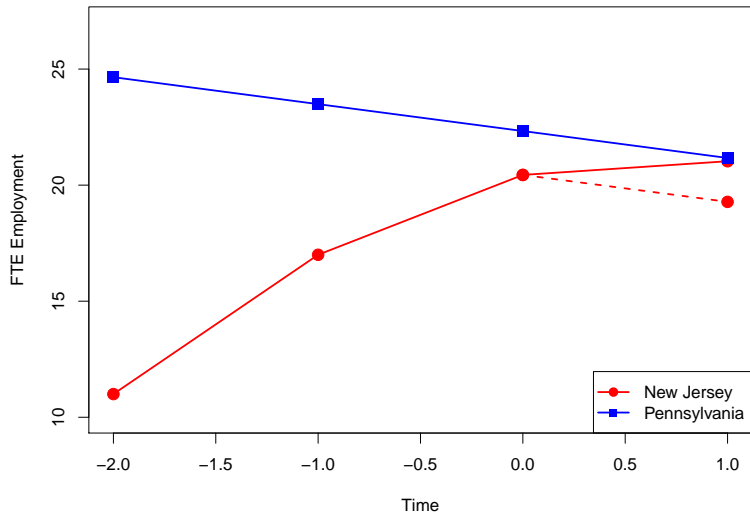
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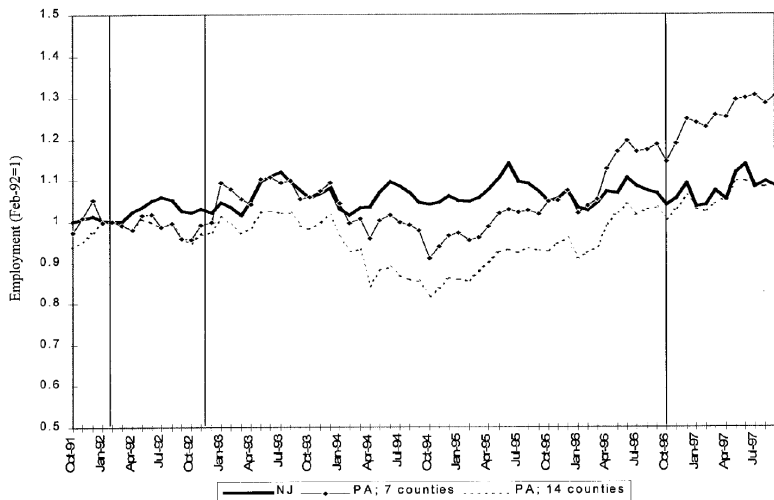
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Longer Trends in Employment (Card and Krueger 2000)



First two vertical lines indicate the dates of the Card-Krueger survey. October 1996 line is the federal minimum wage hike which was binding in PA but not NJ

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6) Endogenous Control Variables

can add (time-varying) covariates to help with some of above concerns \rightsquigarrow “regression diff-in-diff”

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but need to be careful that they aren't affected by the treatment.

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What to read next?

- Angrist and Pischke Chapter 5 Parallel Worlds: Fixed Effects, Differences-in-Differences and Panel Data
- Morgan and Winship Chapter 11 Repeated Observations and the Estimation of Causal Effects

We Covered

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Next Time: Fixed Effects

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

- 1 Differencing Models
- 2 Difference-in-Differences
- 3 Fixed Effects
- 4 Non-parametric Identification and Fixed Effects
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- We discussed a **differencing** approach to this model
- The **Fixed effects model** is an alternative way to remove time-invariant unmeasured confounding
- We will start by assuming the model and discussing properties and in the next section, we will consider non-parametric identification.

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$$\begin{aligned}\bar{y}_i &= \frac{1}{T} \sum_{t=1}^T [\mathbf{x}'_{it}\boldsymbol{\beta} + a_i + u_{it}] \\ &= \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}'_{it} \right) \boldsymbol{\beta} + \frac{1}{T} \sum_{t=1}^T a_i + \frac{1}{T} \sum_{t=1}^T u_{it} \\ &= \bar{\mathbf{x}}'_i \boldsymbol{\beta} + a_i + \bar{u}_i\end{aligned}$$

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Fixed Effects Models

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- Key fact: because it is **time-constant** the mean of a_i is just a_i
- This regression is sometimes called the “between regression”

Within Transformation

Within Transformation

- The “fixed effects,” “within,” or “time-demeaning” transformation is when we subtract off the over-time means from the original data:

$$(y_{it} - \bar{y}_i) = (\mathbf{x}'_{it} - \bar{\mathbf{x}}'_i)\boldsymbol{\beta} + (u_{it} - \bar{u}_i)$$

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- NB: you **must** demean the X variables not just the Y variables.

Fixed Effects with Ross data

```
fe.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur), data = ross, index = c("id", "year"),
  model = "within")
summary(fe.mod)

## Oneway (individual) effect Within Model
##
## Call:
## plm(formula = log(kidmort_unicef) ~ democracy + log(GDPcur),
## data = ross, model = "within", index = c("id", "year"))
##
## Unbalanced Panel: n=166, T=1-7, N=649
##
## Residuals :
## Min. 1st Qu. Median 3rd Qu. Max.
## -0.70500 -0.11700 0.00628 0.12200 0.75700
##
## Coefficients :
## Estimate Std. Error t-value Pr(>|t|)
## democracy -0.143233 0.033500 -4.2756 2.299e-05 ***
## log(GDPcur) -0.375203 0.011328 -33.1226 < 2.2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Total Sum of Squares: 81.711
## Residual Sum of Squares: 23.012
## R-Squared : 0.71838
## Adj. R-Squared : 0.53242
## F-statistic: 613.481 on 2 and 481 DF, p-value: < 2.22e-16
```

Strict Exogeneity

- FE models are valid if $E[\mathbf{u}|\mathbf{X}] = 0$: all errors are uncorrelated with covariates in every period:

$$E[\ddot{u}_{it}|\ddot{\mathbf{X}}] = E[u_{it}|\ddot{\mathbf{X}}] - E[\bar{u}_i|\ddot{\mathbf{X}}] = 0 - 0 = 0$$

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- This is because the composite errors, \ddot{u}_{it} are function of the errors in every time period through the average, \bar{u}_i
- This rules out, for instance, lagged dependent variables, since $y_{i,t-1}$ has to be correlated with $u_{i,t-1}$. Thus it can't be a covariate for y_{it} .

Fixed Effects and Time-Invariant Covariates

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- Basic message: any time-constant variable gets “absorbed” by the fixed effect. It has nothing to contribute because the comparison is **within the units**.
- Can include interactions between time-constant and time-varying variables, but lower order term of the time-constant variables get absorbed by fixed effects too

Time-constant variables

- Pooled model with a time-constant variable, proportion Islamic:

```
library(lmtest)
p.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam,
             data = ross, index = c("id", "year"), model = "pooling")
coeftest(p.mod)

##
## t test of coefficients:
##
##              Estimate  Std. Error  t value  Pr(>|t|)
## (Intercept) 10.30607817  0.35951939  28.6663 < 2.2e-16 ***
## democracy   -0.80233845  0.07766814 -10.3303 < 2.2e-16 ***
## log(GDPcur) -0.25497406  0.01607061 -15.8659 < 2.2e-16 ***
## islam        0.00343325  0.00091045   3.7709 0.0001794 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Time-constant variables

- FE model, where the islam variable drops out, along with the intercept:

```
fe.mod2 <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam,
               data = ross, index = c("id", "year"), model = "within")
coeftest(fe.mod2)
```

```
##
## t test of coefficients:
##
##           Estimate Std. Error  t value  Pr(>|t|)
## democracy  -0.129693   0.035865  -3.6162 0.0003332 ***
## log(GDPcur) -0.379997   0.011849 -32.0707 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Alternate Computation: Least Squares Dummy Variable

- As an alternative to the within transformation, we can also include a series of $n - 1$ dummy variables for each unit:

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + d_i^{(1)}\alpha_1 + d_i^{(2)}\alpha_2 + \cdots + d_i^{(n)}\alpha_n + u_{it}$$

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- Why are these equivalent? (remember partialing out strategy and Frisch-Waugh-Lovell theorem)

Example with Ross data

```
library(lmtest)
lsdv.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur) +
               as.factor(id), data = ross)
coeftest(lsdv.mod)[1:6,]
coeftest(fe.mod)[1:2,]
```



```
##              Estimate Std. Error   t value    Pr(>|t|)
## (Intercept)    13.7644887 0.26597312  51.751427 1.008329e-198
## democracy      -0.1432331 0.03349977  -4.275644 2.299393e-05
## log(GDPcur)    -0.3752030 0.01132772 -33.122568 3.494887e-126
## as.factor(id)AGO  0.2997206 0.16767730   1.787485 7.448861e-02
## as.factor(id)ALB -1.9309618 0.19013955 -10.155498 4.392512e-22
## as.factor(id)ARE -1.8762909 0.17020738 -11.023558 2.386557e-25
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- Note that when the second dimension isn't time, fixed effects will be relevant more often.

We Covered

- Fixed Effects!
- Computation for Fixed Effects!

Next Time: Non-parametric Identification and Fixed Effects

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

- 1 Differencing Models
- 2 Difference-in-Differences
- 3 Fixed Effects
- 4 Non-parametric Identification and Fixed Effects
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 - Questions
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 - ▶ linearity
 - ▶ strict exogeneity
- We've seen the trouble with constant effects before, it goes back to Lecture 10 and results on regression with heterogeneous treatment effects more generally.

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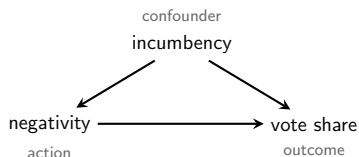
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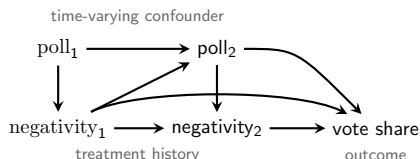
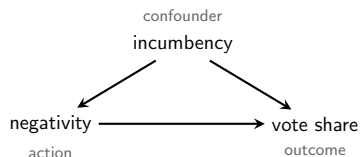
Examples of static and dynamic causal inference problems:



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There is a (possibly irresolvable) tension: modeling **causal dynamics** between treatment and outcomes OR addressing **unobserved time-invariant confounders**. Three great recent papers:

A Framework for Dynamic Causal Inference in Political Science

Matthew Blackwell University of Rochester

Dynamic strategies are an essential part of politics. In the context of campaigns, for example, candidates continuously modify their campaign strategy in response to polls and opponent actions. Traditional causal inference methods, however, assume that these dynamic decisions are made all at once, an assumption that leaves a choice between omitted variable bias and posttreatment bias. Thus, these kinds of “single shot” causal inference methods are inappropriate for dynamic, process-like campaigns. I resolve this dilemma by adapting methods from econometrics, thereby providing a holistic framework for dynamic causal inference. I then use this method to estimate the effectiveness of an inherently dynamic process: a candidate’s decision to “go negative.” Drawing on U.S. congressional elections (2000–2006), I find, in contrast to the previous literature and alternative methods, that negative advertising is an effective strategy for nonincumbents. I also describe a set of diagnostic tools and an approach to sensitivity analysis.

When a candidate would plan all of their rallies, write all of their speeches, and film all of their advertisements at the beginning of a campaign, then sit back and watch them unfold until Election Day? Clearly this is absurd, and yet it is the only way that the usual ways of making causal inferences allow us to study. While political science has seen enormous growth in attention to causal inference over the past decade, these advances have heavily focused on subfields where the dynamic nature of politics is centered into a single point in time. As political science finds itself with a growing number of raster pictures—panel data, time-series cross-sectional data—methods have emerged between substance and method. Indeed, applied to dynamic data, the best practices of single-shot causal inference methods provide conflicting advice and fail to address omitted variable or posttreatment bias.

This article focuses on a specific dynamic process: negative advertising in US House and gubernatorial elections from 2000 until 2006. Candidates in these races change their tone over the course of the campaign, react-

are more likely to go negative than those that are safe. Attempting to correct for this dynamic selection by controlling for polls leads to posttreatment bias since earlier campaign tone influences polling. The inappropriate application of single-shot causal inference therefore leaves scholars between a rock and a hard place, stumped in bias with either approach. This dilemma is not limited to negative advertising on campaigns—every field of political science has a variable of interest that evolves over time.

This article solves this dilemma by presenting a framework for dynamic causal inference and a set of tools, developed in econometrics and epidemiology (Ghirina, Hernan, and Imbens 2001), to estimate dynamic causal effects. These tools directly model dynamic selection and overcome the above problems of single-shot causal inference. Actions (such as campaign tone) are allowed to vary over time along with any confounding covariates (such as polling). Thus, we can study the effects of the action history (candidate’s tone across the entire campaign) as opposed to a single action (simply “going negative”).

Core Conundrum

There is a (possibly irresolvable) tension: modeling **causal dynamics** across treatment and outcomes **OR** addressing **unobserved time-invariant confounders**. Three great recent papers:

A Framework for Dynamic Causal Inference in Political Science

Matthew Blackwell University of Rochester

Dynamic strategies are an essential part of politics. In the context of campaigns, for example, candidates continuously monitor their campaign strategy response to public and opponent actions. Theoretical causal inference models, however, assume that these dynamic decisions are made all at once, so an assumption that leaves a chasm between empirical results and what practitioners face. This, then, motivates a “single shot” causal inference method an appropriate for dynamic processes like campaigns. I resolve this dilemma by adapting models from biostatistics, thereby providing a holistic framework for dynamic causal inference. I then use this method to estimate the effectiveness of an inherently dynamic process: a candidate’s decision to “go negative.” Drawing on U.S. statewide elections (2008–2006), I find, in contrast to the previous literature and alternative methods, that negative advertising is an effective strategy for nonincumbents. I also describe an set of diagnostic tools and an approach to sensitivity analysis.

Who has candidate would plan all of their rallies, write all their speeches, and film all of their advertisements at the beginning of a campaign, then sit back and watch their unfolds? Election Day? Clearly this is absurd, and yet it is the only way that the usual way of making causal inferences allows us to study. While political science has seen enormous growth in attention to causal inference over the past decade, these advances have been focused on situations where the dynamic nature of politics is captured within a single point in time. As political science finds itself with a growing number of random placebo—panel data, time-series cross-sectional data, treatment based designs (e.g., DiD, RDs), and random, indeed, applied to dynamic data, the best practice of single-shot causal inference methods provide conflicting advice and fall to address central variables or post-treatment bias.

This article focuses on a specific, dynamic process: negative advertising in US state and gubernatorial elections from 2006 until 2008. Candidates in these races change their tone over the course of the campaign, react-

are more likely to go negative than those that are safe. Attempting to correct for this dynamic adjustment by controlling for public leads to post-treatment bias since earlier campaign tone influences polling. The inappropriate application of single-shot causal inference therefore leaves scholars between a rock and a hard place, stumped in how with optimal approach. This dilemma is not limited to negative advertising or campaigns—every field of political science has a variable of interest that evolves over time.

This article shows this dilemma by providing a framework for dynamic causal inference and sets it afire, developed in biostatistics and epidemiology (Robins, Hernan, and Brumback 2004), to estimate dynamic causal effects. These tools directly model dynamic selection and overcome the above problems of single-shot causal inference. Actions (such as campaign tone) are allowed to vary over time along with any confounding variables (such as polling). Thus, we can study the effects of the active factor (candidate’s tone across the entire campaign) as opposed to a single action (simply “going negative”).

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How to Make Causal Inferences with Time-Series Cross-Sectional Data under Selection on Observables

MATTHEW BLACKWELL, Harvard University
ADAM N. GLYNN, Emory University

Repeated measurements of the same countries, people, or groups over time are vital to many fields of political science. These measurements, sometimes called time-series cross-sectional (TSCS) data, allow researchers to estimate a broad set of causal quantities, including contemporaneous effects and direct effects of lagged treatments. Unfortunately, popular methods for TSCS data can only provide valid inferences for lagged effects under some strong assumptions. In this paper, we use potential outcomes to define causal quantities of interest in these settings and clarify how standard models fail the stronger assumptions but model can produce biased estimates of these quantities due to post-treatment conditioning. We then describe two estimation strategies that avoid these post-treatment biases—inverse probability weighting and control treated event models—and show via simulations that they outperform standard approaches in small sample settings. We illustrate these methods in a study of how welfare spending affects turnover.

INTRODUCTION

Many inquiries in political science involve the study of repeated measurements of the same countries, people, or groups at several points in time. This type of data, sometimes called time-series cross-sectional (TSCS) data, allows researchers to draw on a larger pool of information when estimating causal effects. TSCS data also give researchers the power to ask a richer set of questions than data with a single measurement for each unit (for example, see Black and Katz 2011). Using this data, researchers can move past the standard contemporary questions—what are the effects of a single event?—and instead ask how the history of a process affects the political world. Unfortunately, the most common approaches to modeling TSCS data require strict assumptions to estimate the effect of treatment histories without bias and make it difficult to understand the nature of the counterfactual comparisons.

This paper makes three contributions to the study of TSCS data. Our first contribution is to define some

overfactual causal effects and discuss the assumptions needed to identify them nonparametrically. We also relate these quantities of interest to common quantities in the TSCS literature, like impulse responses, and show how to derive them from the parameters of a common TSCS model, the autoregressive distributed lag (ADL) model. These treatment effects can be nonparametrically identified under a key selection-on-observables assumption called sequential ignorability; unfortunately, however, many common TSCS approaches rely on more stringent assumptions, including a lack of causal feedback between the treatment and time-varying covariates. This feedback, for example, might involve a country’s level of welfare spending affecting the vote share of left wing parties. We argue that this type of feedback is common in TSCS settings. While we focus on a selection-on-observables assumption in this paper, we discuss the tradeoffs with the choice compared to standard feedback effects methods, noting that the latter may also rule out this type of dynamic feedback.

Our second contribution is to provide an introduction to two methods from biostatistics that can estimate the effect of treatment histories without bias and under weaker assumptions than common TSCS models. We focus on two methods: (1) structural nested mean models or SNMMs (Robins 1997) and (2) marginal structural models (MSMs) using inverse probability of treatment weighting (IPTW) (Robins, Hernan, and

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Adam N. Glynn is an Associate Professor, Department of Political Science, Emory University, 1101 Dickey Drive, Atlanta, GA 30322 (aglynn@emory.edu).

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What candidates would plan all of their rallies, write all of their speeches, and fill all of their advertisements at the beginning of a campaign, then sit back and watch their rallies unfold? Election Day? Clearly this is absurd, and yet it is the only strategy that the usual way of making causal inferences allows us to study. While political science has seen enormous growth in attention to causal inference over the past decade, these advances have been focused on situations where the dynamic nature of politics is captured into a single point in time. As political science finds itself with a growing number of motion pictures—panel data, time-series cross-sectional data, longitudinal data, randomized experiments, and methods, indeed, applied to dynamic data, the best practice of single-shot causal inference methods provide conflicting advice and fall far short of capturing the complexity of political science.

This article focuses on a specific dynamic process: negative advertising in US state and gubernatorial elections from 2008 until 2016. Candidates in these races change their tone over the course of the campaign, react-

are more likely to go negative than those that are safe. Attempting to correct for this dynamic selection by controlling for polls leads to posttreatment bias since earlier campaign tone influences polling. The inappropriate application of single-shot causal inference therefore leaves scholars between a rock and a hard place, stumped in how with other approach. This dilemma is not limited to negative advertising or campaigns—every field of political science has a variety of interest that evolves over time.

This article solves this dilemma by providing a framework for dynamic causal inference and an offshoot, dynamic causal inference, that are both conceptually and methodologically sound. I illustrate this framework with data from Florida and Michigan (2008), two statewide causal effects. These two directly model dynamic selection and overcome the above problems of single-shot causal inference. Actions (such as campaigning) are allowed to vary over time along with any confounding variables (such as polling). Thus, we can study the effects of the active factor (candidate's tone across the entire campaign) as opposed to a single action (simply "going negative").

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MATTHEW BLACKWELL, Harvard University
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Repeated measurements of the same countries, people, or groups over time are vital to many fields of political science. These measurements, sometimes called time-series cross-sectional (TSCS) data, allow researchers to estimate a broad set of causal questions, including contemporaneous effects and direct effects of lagged treatments. Unfortunately, popular methods for TSCS data can only provide valid inferences for lagged effects under some strong assumptions. In this paper, we propose novel ways to define causal questions of interest in these settings and clarify how standard methods fail the stronger, more general, but model-free conditions that avoid these problems. We then describe two estimation strategies that avoid these problems: treatment effects—directly estimated, and indirect effects—estimated via propensity score methods. We illustrate these methods in an study of how welfare spending affects terrorism.

INTRODUCTION

Many inquiries in political science involve the study of repeated measurements of the same countries, people, or groups at several points in time. This type of data, sometimes called time-series cross-sectional (TSCS) data, allows researchers to draw on a larger pool of information when estimating causal effects. TSCS data also give researchers the power to ask a richer set of questions than data with a single measurement for each unit (for example, see Heck and Katz 2011). Using this data, researchers can instead pose the standard contemporary questions—like what are the effects of a single event?—and instead ask the history of a process affects the political world. Unfortunately, the most common approaches to modeling TSCS data require strong assumptions to estimate the effects of treatment histories without bias and make it difficult to understand the nature of the counterfactual comparisons.

This paper makes three contributions to the study of TSCS data. Our first contribution is to define some

overstated causal effects and discuss the assumptions needed to identify them nonparametrically. We also relate these quantities of interest to common questions in the TSCS literature, like spillover responses, and show how to derive them from the parameters of a common TSCS model, the autoregressive distributed lag (ADL) model. These treatment effects can be nonparametrically identified under a key selection-on-observables assumption called sequential ignorability; unfortunately, however, many common TSCS approaches rely on more stringent assumptions, including a lack of causal feedback, between the treatment and time-varying covariates. This feedback, for example, might involve a country's GDP and welfare spending affecting the vote share of left wing parties. To avoid causal feedback, researchers often restrict to the causal effect of treatment at a single point in time. We argue that this type of feedback is common in TSCS data. What we focus on is selection-on-observability assumption in this paper, we discuss the tradeoffs with this choice compared to standard fixed effects methods, and explain how the latter may also risk this type of dynamic feedback.

Our second contribution is to provide an introduction to two methods from biostatistics that can estimate causal effects in the presence of causal feedback, but weaker assumptions than common TSCS models. We describe the use of (1) marginal structural models or MSMs (Robins 1997) and (2) marginal structural mean models or MSMs (Robins, Hernan, and

AMERICAN JOURNAL OF POLITICAL SCIENCE

When Should We Use Unit Fixed Effects Regression Models for Causal Inference with Longitudinal Data?

Kosuke Imai Harvard University
In Song Kim Massachusetts Institute of Technology

Abstract: These researchers use unit fixed effect regression models to analyze individual-level causal inference with longitudinal data. We discuss the ability of these models to deliver valid causal inferences, especially under the presence of dynamic causal relationships, which has potential under an alternative selection-on-observability approach. Using the regression discontinuity design, we highlight how key causal identification assumptions of unit fixed effect models may be violated under dynamic causal relationships, and past treatment may affect current treatment. Furthermore, we consider a more conservative modeling framework that declines how to use unit fixed effect models to compare treated and control groups over time. Specifically, we establish the conditions for which matching and regression discontinuity designs, but not fixed effects, are able to deliver valid inferences in the absence of dynamic causal relationships between treatment and outcome variables. The authors use the proposed methodology through an application to the effectiveness of LGBT workplace equality on suicide risk.

Reproduction Methods: This data, code, and an additional materials package to replicate the analyses in this article are available on the American Journal of Political Science Database within the Harvard Dataverse Network, at <https://dataverse.harvard.edu/dataset.xhtml?persistentId=doi:10.7927/H733-N1M3M3>.

Unit fixed effects regression models are widely used for causal inference with longitudinal data, and have led to the solid success in, for example, political science (e.g., Angrist and Pischke 2009). Many researchers use these models to compare the treated and control groups over time. However, we argue that the ability of unit fixed effects regression models to deliver valid causal inferences with longitudinal data is nontrivial and may be violated under dynamic causal relationships. In particular, we discuss the conditions under which unit fixed effects regression models may be violated under dynamic causal relationships between treatment and outcome variables, which are allowed to enter under an alternative selection-on-observability approach (e.g., Imbens, Hoxby, and Heckman 2008). Our analysis highlights new key

Imai, K., and S. Kim. 2018. "When Should We Use Unit Fixed Effects Regression Models for Causal Inference with Longitudinal Data?" *American Journal of Political Science* 62(1): 1367–1387.

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DOI: 10.1111/xaps.12017

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Directed Acyclic Graph (DAG)

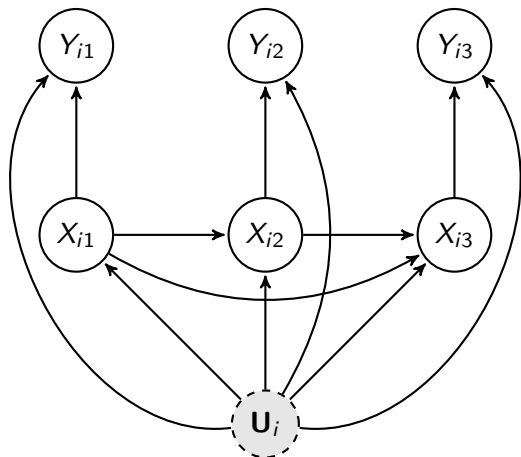
Non-parametric identification assumptions for fixed effects:

$$Y_{it} = g(X_{it}, \mathbf{U}_i, \epsilon_{it}) \quad \text{and} \quad \epsilon_{it} \perp\!\!\!\perp \{\mathbf{X}_i, \mathbf{U}_i\}$$

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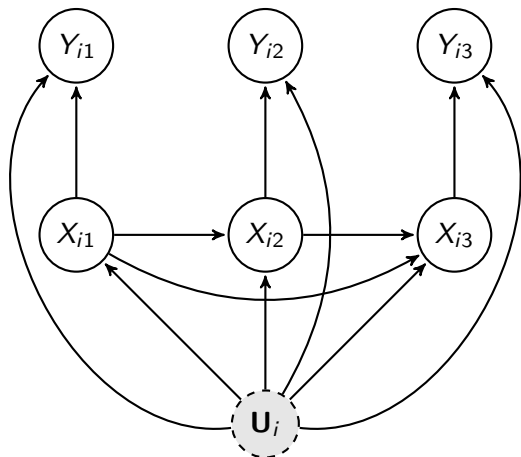


Assumptions:

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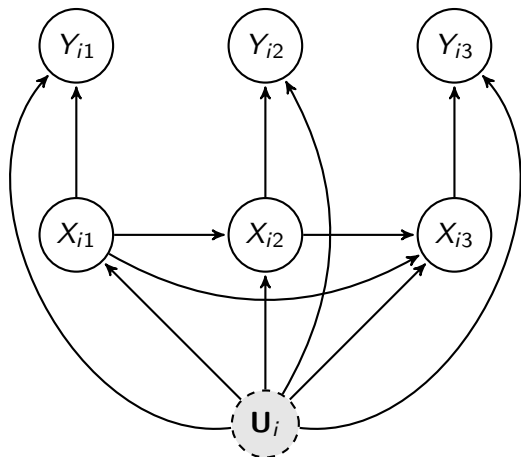
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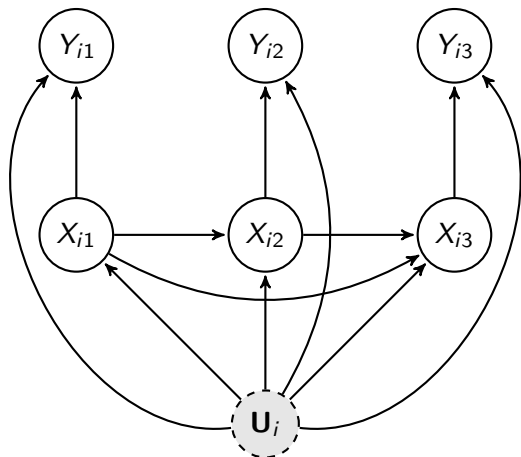
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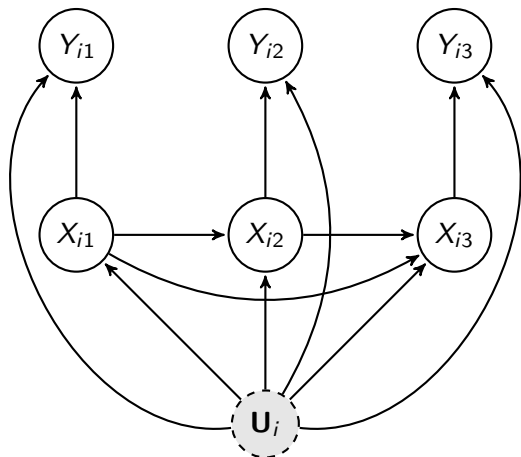
Assumptions:

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- 3 Past outcomes do not directly affect current treatment

Directed Acyclic Graph (DAG)

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Assumptions:

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- 2 Past outcomes do not directly affect current outcome
- 3 Past outcomes do not directly affect current treatment
- 4 Past treatments do not directly affect current outcome

*the result implies that the **counterfactual** outcome for a treated observation in a given time period is estimated using the **observed outcomes of different time periods of the same unit**. Since such a comparison is **valid only when no causal dynamics exist**, this finding underscores the important limitation of linear regression models with unit fixed effects.*

- Imai and Kim (2019)

What Ideal Experiment Corresponds to the Fixed Effects Model?

- Experiment that satisfies the model assumptions:

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- Experiment that satisfies the model assumptions:
 - 1 randomize X_{i1} given \mathbf{U}_i

What Ideal Experiment Corresponds to the Fixed Effects Model?

- Experiment that satisfies the model assumptions:
 - ① randomize X_{i1} given \mathbf{U}_i
 - ② randomize X_{i2} given X_{i1} and \mathbf{U}_i

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 - ③ randomize X_{i3} given X_{i2} , X_{i1} , and \mathbf{U}_i
 - ④ and so on

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 - ④ and so on
- Experiment that does not satisfy the model assumptions:

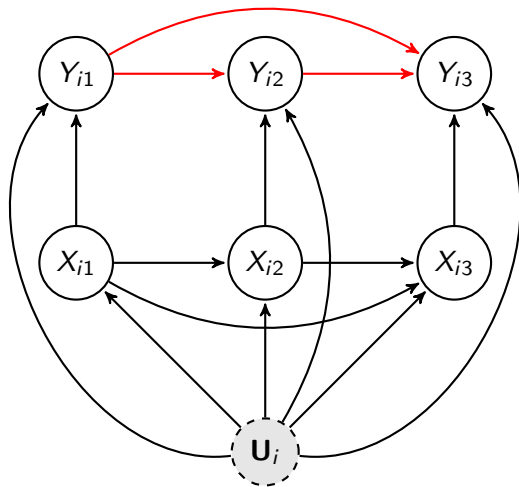
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- Experiment that does not satisfy the model assumptions:
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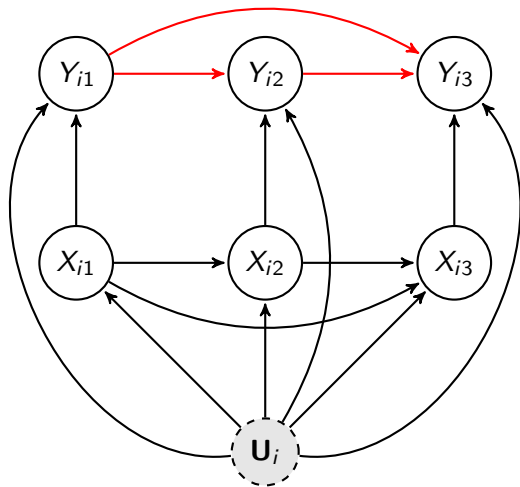
- Experiment that satisfies the model assumptions:
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 - ② randomize X_{i2} given X_{i1} and \mathbf{U}_i
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 - ① randomize X_{i1}
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 - ③ randomize X_{i3} given X_{i2} , X_{i1} , Y_{i1} , and Y_{i2}
 - ④ and so on
- Now let's consider each assumption in turn.

Past Outcomes Don't Directly Affect Current Outcome (A2)



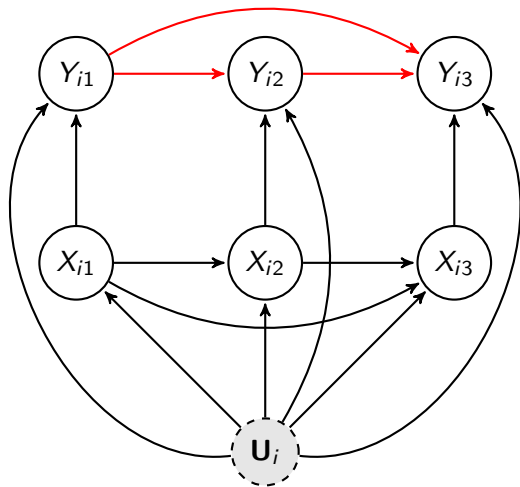
- Strict exogeneity still holds.

Past Outcomes Don't Directly Affect Current Outcome (A2)



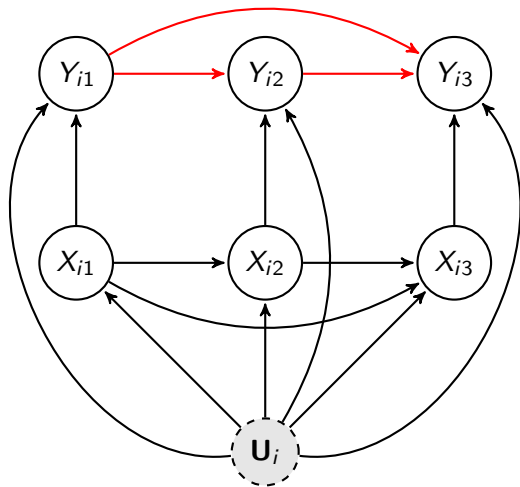
- Strict exogeneity still holds.
- Past outcomes do not confound $X_{it} \rightarrow Y_{it}$ given U_i .

Past Outcomes Don't Directly Affect Current Outcome (A2)



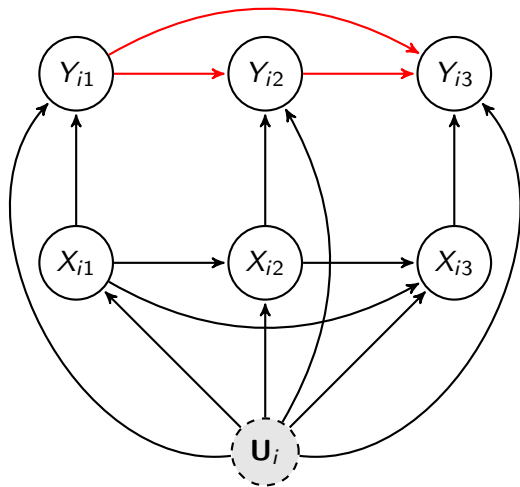
- Strict exogeneity still holds.
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- No need to adjust for past outcomes.

Past Outcomes Don't Directly Affect Current Outcome (A2)



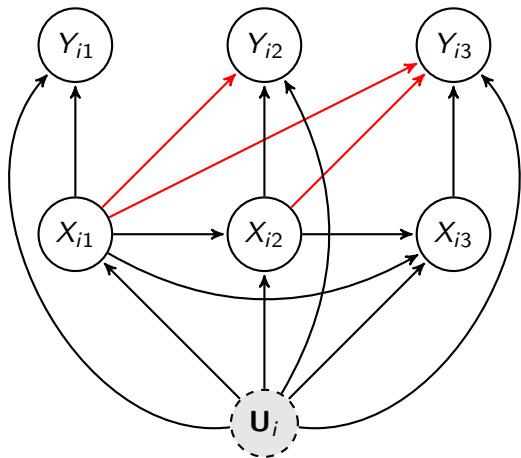
- Strict exogeneity still holds.
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- No need to adjust for past outcomes.
- Should use cluster robust standard errors for inference.

Past Outcomes Don't Directly Affect Current Outcome (A2)



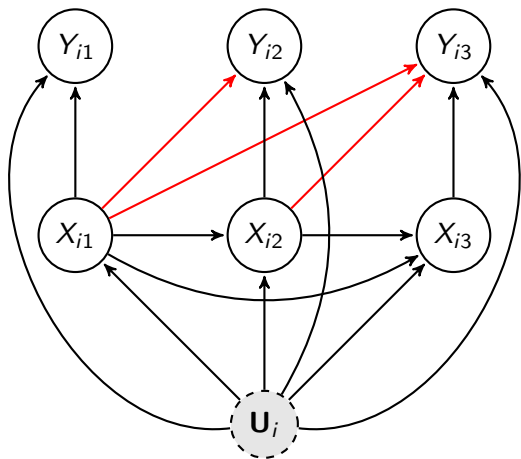
- Strict exogeneity still holds.
- Past outcomes do not confound $X_{it} \rightarrow Y_{it}$ given U_i .
- No need to adjust for past outcomes.
- Should use cluster robust standard errors for inference.
- Conclusion: **The assumption can be relaxed**

Past Treatments Don't Directly Affect Current Outcome (A4)



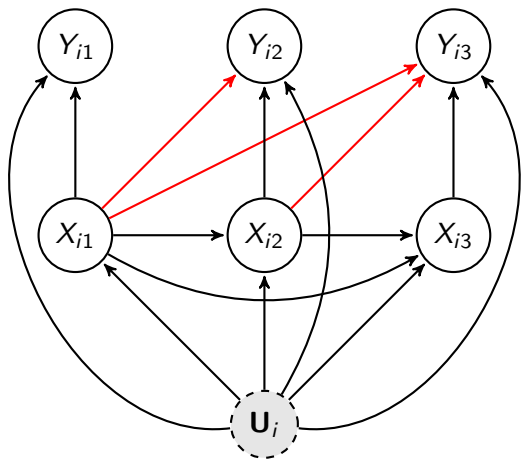
- Need to adjust for past treatments

Past Treatments Don't Directly Affect Current Outcome (A4)



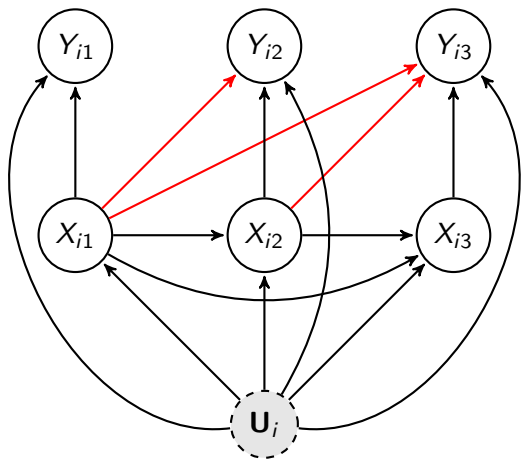
- Need to adjust for past treatments
- Strict exogeneity holds given past treatments and U_i

Past Treatments Don't Directly Affect Current Outcome (A4)



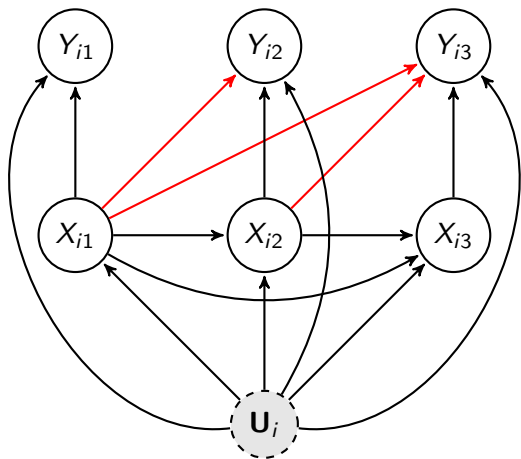
- Need to adjust for past treatments
- Strict exogeneity holds given past treatments and U_i
- Impossible to adjust for an entire treatment history and U_i at the same time

Past Treatments Don't Directly Affect Current Outcome (A4)



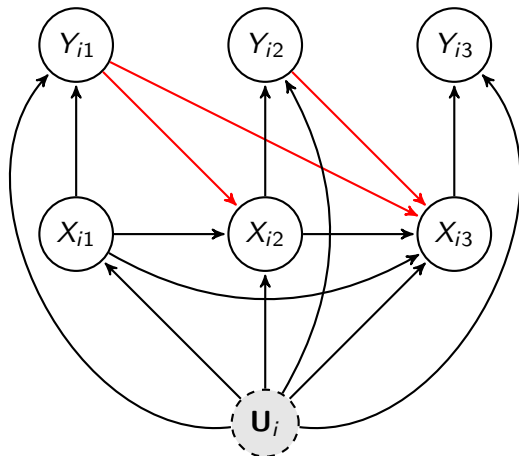
- Need to adjust for past treatments
- Strict exogeneity holds given past treatments and U_i
- Impossible to adjust for an entire treatment history and U_i at the same time
- Adjust for a small number of past treatments \rightsquigarrow often arbitrary

Past Treatments Don't Directly Affect Current Outcome (A4)



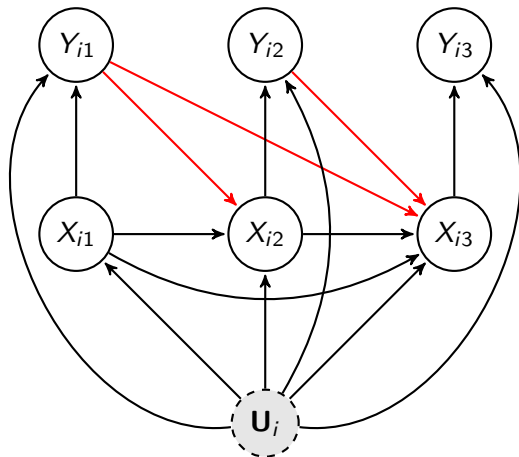
- Need to adjust for past treatments
- Strict exogeneity holds given past treatments and U_i
- Impossible to adjust for an entire treatment history and U_i at the same time
- Adjust for a small number of past treatments \rightsquigarrow often arbitrary
- Conclusion: **The assumption can be partially relaxed**

Past Outcomes Don't Directly Affect Current Treatment (A3)

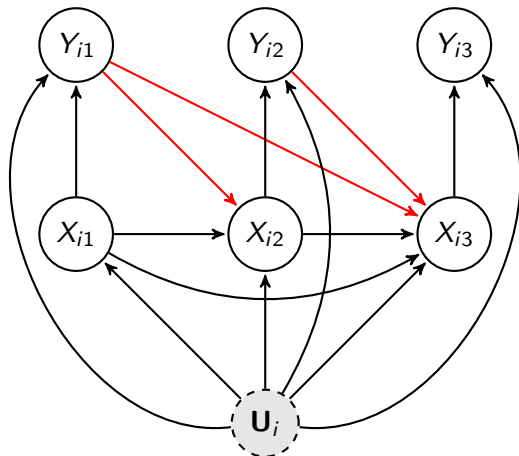


Past Outcomes Don't Directly Affect Current Treatment (A3)

- Correlation between error term and future treatments

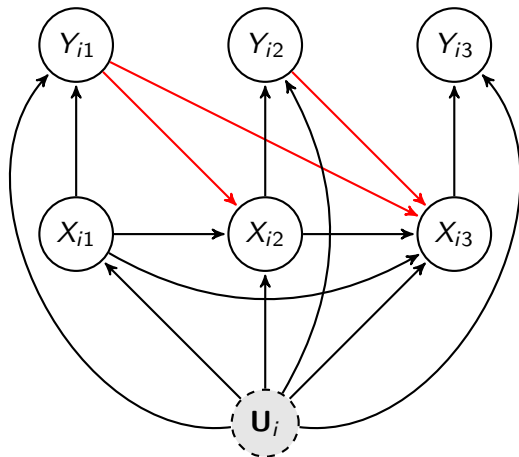


Past Outcomes Don't Directly Affect Current Treatment (A3)



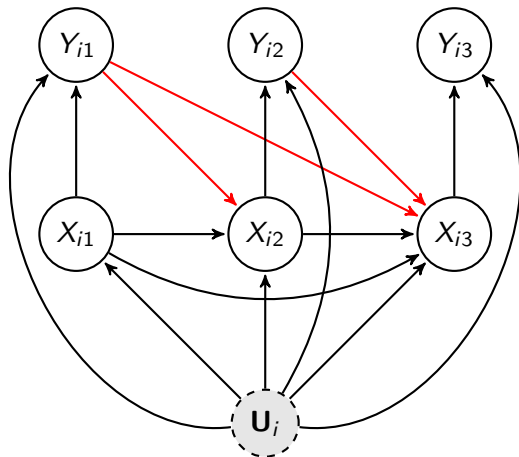
- Correlation between error term and future treatments
- Violation of strict exogeneity

Past Outcomes Don't Directly Affect Current Treatment (A3)



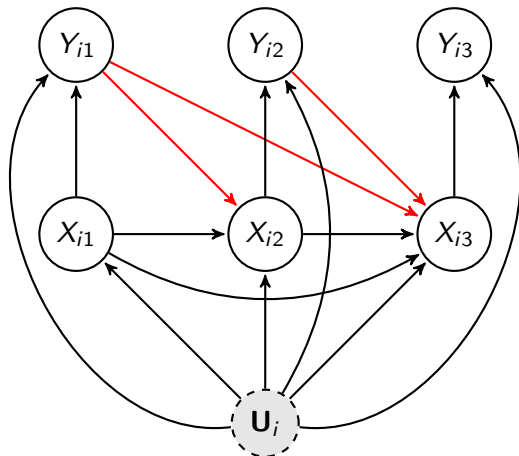
- Correlation between error term and future treatments
- Violation of strict exogeneity
- No adjustment is sufficient

Past Outcomes Don't Directly Affect Current Treatment (A3)



- Correlation between error term and future treatments
- Violation of strict exogeneity
- No adjustment is sufficient
- Implication: No dynamic causal relationships between treatment and outcome variables

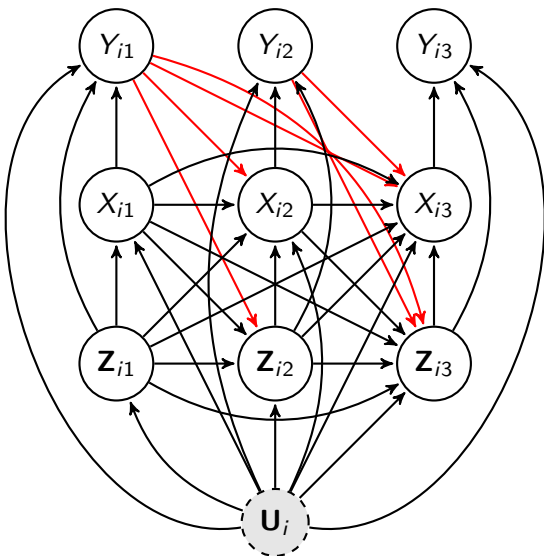
Past Outcomes Don't Directly Affect Current Treatment (A3)



- Correlation between error term and future treatments
- Violation of strict exogeneity
- No adjustment is sufficient
- Implication: No dynamic causal relationships between treatment and outcome variables
- Conclusion: **The assumption cannot be relaxed**

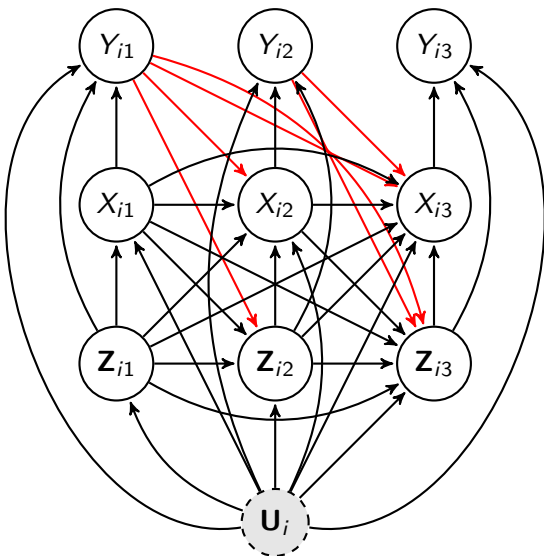
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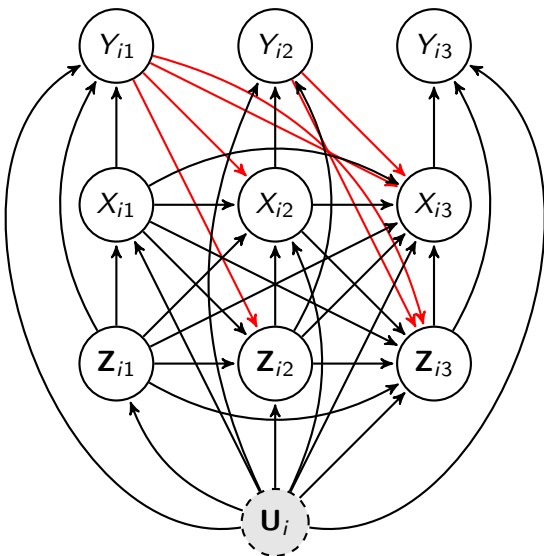
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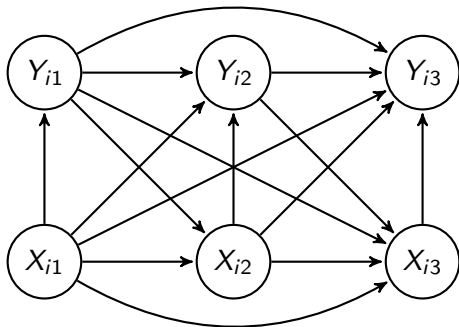
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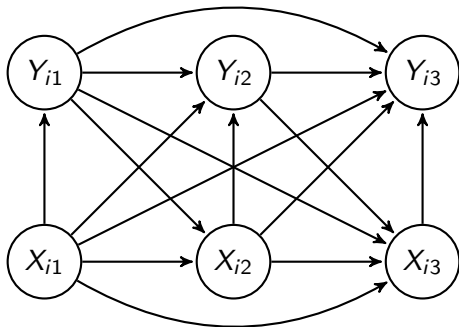
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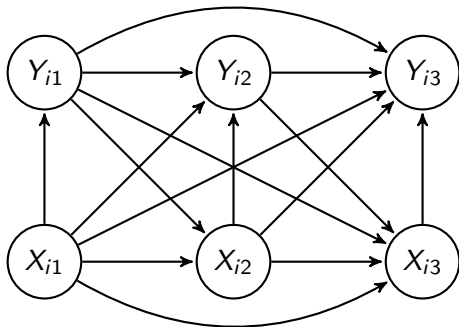
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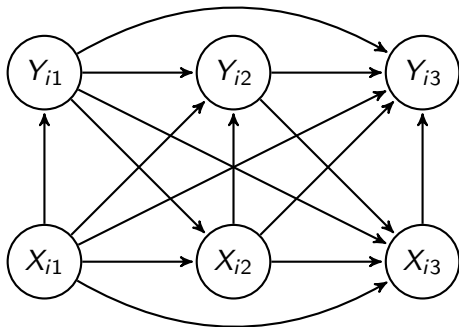
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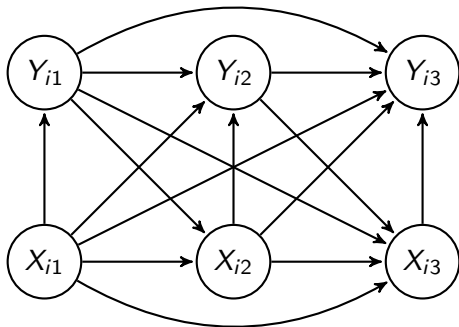
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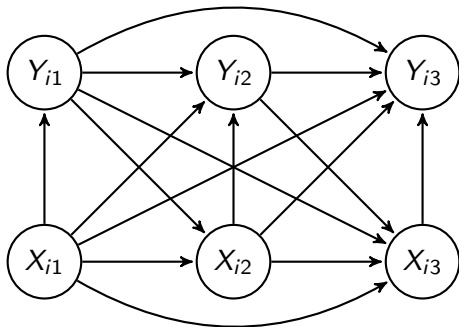


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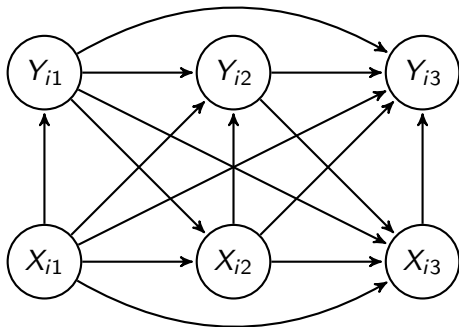


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Conclusions and Nonparametric Estimation

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 - 2) causal dynamics between treatment and outcome \rightsquigarrow selection-on-observables

Summary Table (Imai and Kim 2019)

TABLE 1 Identification Assumptions of Various Estimators

	Linearity	Time-Invariant Unobservables	Past Outcomes Affect Current Treatment	Past Treatments Affect Current Outcome
$Y_{it} = \alpha_i + \beta X_{it} + \epsilon_{it}$	Yes	Allowed	Not allowed	Not allowed
$Y_{it} = \alpha_i + \beta X_{it} + \rho Y_{i,t-1} + \epsilon_{it}$	Yes	Allowed	Allowed	Not allowed
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$Y_{it} = \alpha_i + \beta_1 X_{it} + \beta_2 X_{i,t-1} + \rho Y_{i,t-1} + \epsilon_{it}$	Yes	Allowed	Partially allowed	Partially allowed
Marginal structural models	No	Not allowed	Allowed	Allowed

What to read next?

- Morgan and Winship Chapter 11 Repeated Observations and the Estimation of Causal Effects
- Imai and Kim (2019) “When Should We Use Unit Fixed Effects Regression Models for Causal Inference with Longitudinal Data?” *American Journal of Political Science*, <http://dx.doi.org/10.1111/ajps.12417>

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Next Time: Review

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

- 1 Differencing Models
- 2 Difference-in-Differences
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- 5 Wrap-Up
 - Questions
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1 Differencing Models

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5 **Wrap-Up**

- Questions
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Q: What conditions do we need to infer causality?

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A: A clear estimand, an identification strategy and an estimation strategy.

Identification Strategies in This Class

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Almost everything assumes: consistency/SUTVA (no interference between units, variation in the treatment is irrelevant) and positivity (there is some chance of all getting treatment)

Some Estimation Strategies

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- Stratification

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- Stratification
- Regression (and relatives)
- Matching (lightly covered)
- Weighting (not covered)

Q: Can you review how instrumental variables deal with issues of confounding?

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A: We use only the units whose treatment status was effectively randomized by the instrument (because they are compliers).

Q: What can make standard errors larger or smaller?

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A: Let's consider the anatomy of a standard error.

Anatomy of the Standard Error

Imagine we have a regression of Y on a variable of interest X and a vector of other variables \mathbf{Z} .

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Further Reading:

- Lin, W., 2013. 'Agnostic notes on regression adjustments to experimental data: Reexamining Freedman's critique.' *The Annals of Applied Statistics*
- Athey, S. and Imbens, G.W., 2017. 'The Econometrics of Randomized Experiments.' In *Handbook of Economic Field Experiments* (Vol. 1, pp. 73-140).
- Egap Methods Guide: 10 things you need to know about covariate adjustment. <https://egap.org/methods-guides/10-things-know-about-covariate-adjustment>

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- 3 Derive the equations/math
- 4 Try to explain it to someone else

Q: In the real world of research, when you have your data, how do you know which method to use? For example, how do you know that you need to use matching/regression discontinuity?

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A: Let's chat.

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Where are you?

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You've been given a powerful set of tools



Your New Weapons

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- Basic probability theory
 - ▶ Probability axioms, random variables, marginal and conditional probability, building a probability model
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- **Univariate Inference**

- ▶ Interval estimation (normal and non-normal Population)
- ▶ Confidence intervals, hypothesis tests, p-values
- ▶ Practical versus statistical significance

Your New Weapons

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- Simple Regression
 - ▶ regression to approximate the conditional expectation function
 - ▶ idea of conditioning
 - ▶ kernel and loess regressions
 - ▶ OLS estimator for bivariate regression
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• Multiple Regression

- ▶ OLS estimator for multiple regression in matrix notation
- ▶ Regression assumptions (classical and agnostic)
- ▶ Properties: Bias, Efficiency, Consistency
- ▶ Standard errors, testing, p-values, and confidence intervals
- ▶ Polynomials, Interactions, Dummy Variables
- ▶ F-tests

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- Diagnosing and Fixing Regression Problems
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- And you learned how to use R: you're not afraid of trying something new!

Using these Tools

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So, Admiral Ackbar, now that you've learned how to run these regressions we can just use them blindly, right?



IT'S A TRAP!



Beyond Linear Regressions

You need more training



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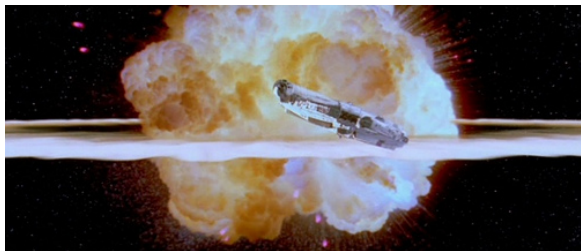
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Thanks!

Thanks so much for an amazing semester.



I will see you in the final synchronous session!