

Week 12: Repeated Observations and Panel Data

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¹These slides are heavily influenced by Matt Blackwell, Adam Glynn, Jens Hainmueller, and Erin Hartman.

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

1 Differencing Models

2 Difference-in-Differences

3 Fixed Effects

4 Non-parametric Identification and Fixed Effects

5 Wrap-Up

- Questions
- Concluding Thoughts for the Course

Is Democracy Good for the Poor?

Michael Ross University of California, Los Angeles

- Relationship between democracy and infant mortality?
- Compare levels of democracy with levels of infant mortality, but. . .
- Democratic countries are different from non-democracies in ways that we can't measure?
 - ▶ they are richer or developed earlier
 - ▶ provide benefits more efficiently
 - ▶ possess some cultural trait correlated with better health outcomes
- If we have data on countries over time, can we make any progress in spite of these problems?

Ross Data

##	cty_name	year	democracy	infmort_unicef
## 1	Afghanistan	1965	0	230
## 2	Afghanistan	1966	0	NA
## 3	Afghanistan	1967	0	NA
## 4	Afghanistan	1968	0	NA
## 5	Afghanistan	1969	0	NA
## 6	Afghanistan	1970	0	215

Notation for Panel Data

- Units, $i = 1, \dots, n$
- Time, $t = 1, \dots, T$
- Slightly different focus than clustered data we covered earlier
 - ▶ **Panel**: we have repeated measurements of the same units
 - ▶ **Clustering**: units are clustered within some grouping.
 - ▶ The main difference is what level of analysis we care about (individual, city, county, state, country, etc).
- Time is a typical application, but applies to other groupings:
 - ▶ counties within states
 - ▶ states within countries
 - ▶ people within professions
- NB: we won't be using T for treatment today because it is extremely consistently used for time. We will end up using D for treatment which is another common letter for treatment.

Nomenclature

Names are used in different ways across fields but generally:

- **Panel data**: large n , relatively short T
- **Time series, cross-sectional (TSCS) data**: smaller n , large T
- We are primarily going to focus on similarities today but there are some differences.

A Baseline Linear Model

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + a_i + u_{it}$$

- \mathbf{x}_{it} is a vector of (possibly time-varying) covariates
- a_i is an **unobserved** time-constant unit effect (“fixed effect”)
- u_{it} are the unobserved time-varying “idiosyncratic” errors
- $v_{it} = a_i + u_{it}$ is the combined unobserved error:

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + v_{it}$$

- Covers the case of **separable, linear unmeasured confounding**.

We will start by considering performance of estimators assuming this model is true.

Naive Strategy: Pooled OLS

- **Pooled OLS**: pool all observations into one regression
- Treats all unit-periods (each it) as an iid unit.
- Has two problems:
 - ① Heteroskedasticity (see clustering from diagnostics week)
 - ② Possible violation of zero conditional mean errors
- Both problems arise out of ignoring the **unmeasured heterogeneity** inherent in a_i

Pooled OLS with Ross data

```
pooled.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur),
                 data = ross)
summary(pooled.mod)

##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  9.76405    0.34491   28.31  <2e-16 ***
## democracy   -0.95525    0.06978  -13.69  <2e-16 ***
## log(GDPcur) -0.22828    0.01548  -14.75  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.7948 on 646 degrees of freedom
## (5773 observations deleted due to missingness)
## Multiple R-squared:  0.5044, Adjusted R-squared:  0.5029
## F-statistic: 328.7 on 2 and 646 DF,  p-value: < 2.2e-16
```

Unmeasured Heterogeneity

- Assume that zero conditional mean error holds for the idiosyncratic error:

$$E[u_{it}|\mathbf{X}] = 0$$

- But time-constant effect, a_i , is correlated with the \mathbf{X} :

$$E[a_i|\mathbf{X}] \neq 0$$

- Example: democratic institutions correlated with **time-invariant** unmeasured aspects of health outcomes, like quality of health system or a lack of ethnic conflict.
- Ignore the heterogeneity \rightsquigarrow **correlation between the combined error and the independent variables**:

$$E[v_{it}|\mathbf{X}] = E[a_i + u_{it}|\mathbf{X}] \neq 0$$

- Pooled OLS will be **biased and inconsistent** because zero conditional mean error fails for the combined error.

First Differencing

- First approach: compare **changes over time** as opposed to **levels**
- Intuitively, the **levels** include the **unobserved heterogeneity**, but **changes over time** should be free of **time-invariant** heterogeneity
- Two time periods:

$$y_{i1} = \mathbf{x}'_{i1}\boldsymbol{\beta} + a_i + u_{i1}$$

$$y_{i2} = \mathbf{x}'_{i2}\boldsymbol{\beta} + a_i + u_{i2}$$

- Look at the change in y over time:

$$\begin{aligned}\Delta y_i &= y_{i2} - y_{i1} \\ &= (\mathbf{x}'_{i2}\boldsymbol{\beta} + a_i + u_{i2}) - (\mathbf{x}'_{i1}\boldsymbol{\beta} + a_i + u_{i1}) \\ &= (\mathbf{x}'_{i2} - \mathbf{x}'_{i1})\boldsymbol{\beta} + (a_i - a_i) + (u_{i2} - u_{i1}) \\ &= \Delta \mathbf{x}'_i \boldsymbol{\beta} + \Delta u_i\end{aligned}$$

First Differences Model

$$\Delta y_i = \Delta \mathbf{x}'_i \boldsymbol{\beta} + \Delta u_i$$

- Coefficient on the levels \mathbf{x}_{it} is the **same** as the coefficient on the changes $\Delta \mathbf{x}_i$!
- fixed effect/unobserved heterogeneity, a_i drops out (relies on unobserved component being **constant** over time!)
- If $E[u_{it}|\mathbf{X}] = 0$, then, $E[\Delta u_i|\Delta \mathbf{X}] = 0$ and zero conditional mean error holds.
- Due to 'no perfect collinearity': \mathbf{x}_{it} has to change over time for **some** units. High variance if its slow moving.
- Differencing will **reduce** the variation in the independent variables and thus **increase** standard errors.

First Differences in R (via plm package)

```
library(plm)

fd.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur), data = ross,
              index = c("id", "year"), model = "fd")

summary(fd.mod)

## Oneway (individual) effect First-Difference Model
##
## Call:
## plm(formula = log(kidmort_unicef) ~ democracy + log(GDPcur),
##      data = ross, model = "fd", index = c("id", "year"))
##
## Unbalanced Panel: n=166, T=1-7, N=649
##
## Residuals :
##      Min. 1st Qu.  Median 3rd Qu.    Max.
## -0.9060 -0.0956  0.0468  0.1410  0.3950
##
## Coefficients :
##              Estimate Std. Error t-value Pr(>|t|)
## (intercept) -0.149469   0.011275 -13.2567 < 2e-16 ***
## democracy   -0.044887   0.024206  -1.8544  0.06429 .
## log(GDPcur) -0.171796   0.013756 -12.4886 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Total Sum of Squares:    23.545
## Residual Sum of Squares: 17.762
## R-Squared      : 0.24561
##      Adj. R-Squared : 0.24408
## F-statistic: 78.1367 on 2 and 480 DF, p-value: < 2.22e-16
```

We Covered

- The basic panel data notation
- First Difference Models

Next Time: Difference-in-Differences

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Motivation: Studying the Minimum Wage

Minimum Wages and Employment: A Case Study of the Fast-Food Industry in New Jersey and Pennsylvania

By DAVID CARD AND ALAN B. KRUEGER*

On April 1, 1992, New Jersey's minimum wage rose from \$4.25 to \$5.05 per hour. To evaluate the impact of the law we surveyed 410 fast-food restaurants in New Jersey and eastern Pennsylvania before and after the rise. Comparisons of employment growth at stores in New Jersey and Pennsylvania (where the minimum wage was constant) provide simple estimates of the effect of the higher minimum wage. We also compare employment changes at stores in New Jersey that were initially paying high wages (above \$5) to the changes at lower-wage stores. We find no indication that the rise in the minimum wage reduced employment. (JEL J30, J23)

<https://www.jstor.org/stable/2118030>

Motivation: Studying the Minimum Wage

- Economics conventional wisdom: higher minimum wages decrease low-wage jobs.
- Card and Krueger (1994) study a 1992 NJ minimum wage increase (\$4.25 to \$5.05).
- Idea: compare employment rates in 410 fast-food restaurants in NJ and eastern PA (where there wasn't a wage increase) both before and after the change.
- Based on survey data:
 - ▶ Wave 1: March 1992, one month before the minimum wage increased
 - ▶ Wave 2: December 1992, eight months after increase
- “What would a skeptic consider convincing evidence?” David Card
- “There was a time when we thought econometric techniques would solve a lot of the data problems. Now I think the feeling is that there are a lot of problems for which it is easier to get better data.” Alan Krueger

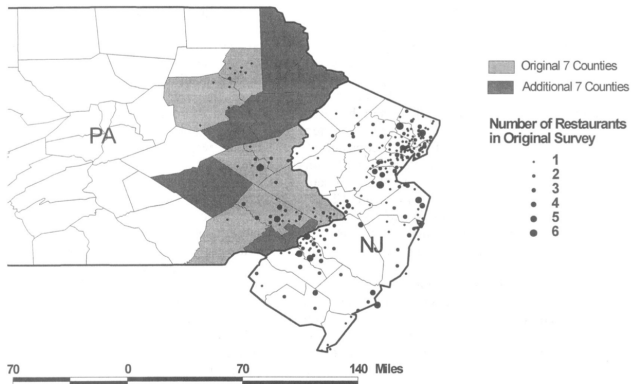


FIGURE 1. AREAS OF NEW JERSEY AND PENNSYLVANIA COVERED BY ORIGINAL SURVEY AND BLS DATA

Source: Card and Krueger 2000

Two Economists Catch Clinton's Eye By Bucking the Common Wisdom

BY PUYEA NABAR

ACTING AS A CONFIDENTIAL source for Bill Clinton, the two economists have helped the president to see the value of a program that only a small number of economists support: the \$1.2 billion minimum-wage law that Clinton signed in 1996.

The real issue was how to fix a low minimum wage. Clinton wanted a change in the minimum wage. Economists, on the other hand, have been telling him that raising the minimum wage would hurt the economy. But Clinton was not listening. He was listening to the economists who were telling him that the minimum wage was a good idea.

The two economists, David Card and Alan Krueger, were the ones who convinced Clinton that the minimum wage was a good idea. They were the only economists who were telling him that the minimum wage was a good idea.

Clinton's decision to raise the minimum wage was a bold move. It was a move that went against the common wisdom of the time. It was a move that showed that Clinton was listening to the economists who were telling him that the minimum wage was a good idea.

The New Jersey Test
This analysis of the minimum wage law in New Jersey was a landmark study. It showed that the minimum wage law in New Jersey had a positive effect on the economy. It showed that the minimum wage law in New Jersey was a good idea.

Card and Krueger's research was groundbreaking. It showed that the minimum wage law in New Jersey had a positive effect on the economy. It showed that the minimum wage law in New Jersey was a good idea.



Princeton economists David Card, left, and Alan Krueger.

They use control groups in their research, and test minimum-wage theories by surveying the managers of fast-food restaurants.

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'Let's Not Assume'

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Difference-in-Differences

- Often called “diff-in-diff” (DiD), it is a special kind of FD model
- Let x_{it} be an indicator of a unit being “treated” at time t .
- Focus on two-periods where:
 - ▶ $x_{i1} = 0$ for all i
 - ▶ $x_{i2} = 1$ for the “treated group”
- Assume the model:

$$y_{it} = \beta_0 + \delta_0 I(t = 2) + \beta_1 x_{it} + a_i + u_{it}$$

- $I(t = 2)$ is a dummy variable for the second time period
- β_1 is the quantity of interest: it's the effect of being treated

Diff-in-Diff Mechanics

- Let's take differences:

$$(y_{i2} - y_{i1}) = \delta_0(\mathbf{1} - \mathbf{0}) + \beta_1(x_{i2} - x_{i1}) + (\mathbf{a}_i - \mathbf{a}_i) + (u_{i2} - u_{i1})$$

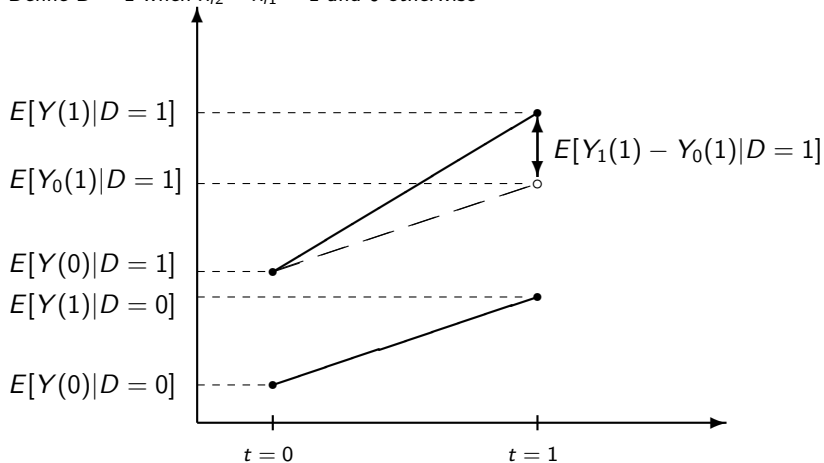
$$(y_{i2} - y_{i1}) = \delta_0 + \beta_1(x_{i2} - x_{i1}) + (u_{i2} - u_{i1})$$

- This represents

- ▶ δ_0 : the difference in the average outcome from period 1 to period 2 in the **untreated** group
- ▶ $(x_{i2} - x_{i1}) = 1$ for the treated group and 0 for the control group
- ▶ β_1 represents the **additional** change in y over time (on top of δ_0) associated with being in the treatment group.

Graphical Representation: Difference-in-Differences

Define $D = 1$ when $x_{i2} - x_{i1} = 1$ and 0 otherwise



Identification with Difference-in-Differences

Identification Assumption (parallel trends)

$$E[Y_0(1) - Y_0(0)|D = 1] = E[Y_0(1) - Y_0(0)|D = 0]$$

Identification Result

Given parallel trends the ATT is identified as:

$$\begin{aligned} E[Y_1(1) - Y_0(1)|D = 1] &= \left\{ E[Y(1)|D = 1] - E[Y(1)|D = 0] \right\} \\ &\quad - \left\{ E[Y(0)|D = 1] - E[Y(0)|D = 0] \right\} \end{aligned}$$

Identification with Difference-in-Differences

Identification Assumption (parallel trends)

$$E[Y_0(1) - Y_0(0)|D = 1] = E[Y_0(1) - Y_0(0)|D = 0]$$

Proof.

Note that the identification assumption implies

$$E[Y_0(1)|D = 0] = E[Y_0(1)|D = 1] - E[Y_0(0)|D = 1] + E[Y_0(0)|D = 0]$$

plugging in we get

$$\begin{aligned} & \{E[Y(1)|D = 1] - E[Y(1)|D = 0]\} - \{E[Y(0)|D = 1] - E[Y(0)|D = 0]\} \\ = & \{E[Y_1(1)|D = 1] - E[Y_0(1)|D = 0]\} - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & \{E[Y_1(1)|D = 1] - (E[Y_0(1)|D = 1] - E[Y_0(0)|D = 1] + E[Y_0(0)|D = 0])\} \\ & - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & E[Y_1(1) - Y_0(1)|D = 1] + \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ & - \{E[Y_0(0)|D = 1] - E[Y_0(0)|D = 0]\} \\ = & E[Y_1(1) - Y_0(1)|D = 1] \end{aligned}$$



Difference-in-Differences Interpretation

- Key idea: comparing the changes over time in the control group to the changes over time in the treated group.
- The differences between these differences is our estimate of the causal effect:

$$\beta_1 = \overline{\Delta y}_{\text{treated}} - \overline{\Delta y}_{\text{control}}$$

- Why more credible than simply looking at the treatment/control differences in period 2?
 - ▶ Unmeasured reasons why the treated group has higher or lower outcomes than the control group
 - ▶ \rightsquigarrow bias due to violation of zero conditional mean error
 - ▶ DiD estimates the bias using period 1 and corrects for it.
- DiD works for **additive** and **time-invariant** confounding (i.e. satisfies parallel trends)

Does Indiscriminate Violence Incite Insurgent Attacks?

Evidence from Chechnya

Jason Lyall

*Department of Politics and the Woodrow Wilson School
Princeton University, New Jersey*

Journal of Conflict Resolution

Volume 53 Number 3

June 2009 331-362

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Example: Lyall (2009)

- Does Russian shelling of villages cause insurgent attacks?

$$\text{attacks}_{it} = \beta_0 + \beta_1 \text{shelling}_{it} + a_i + u_{it}$$

- We might think that artillery shelling by Russians is targeted to places where the insurgency is the strongest
- That is, part of the village fixed effect, a_i might be correlated with whether or not shelling occurs, x_{it}
- This would cause our pooled estimates to be biased
- Instead Lyall takes a diff-in-diff approach: compare attacks over time for shelled and non-shelled villages:

$$\Delta \text{attacks}_i = \beta_0 + \beta_1 \Delta \text{shelling}_i + \Delta u_i$$

- Counterintuitive findings: shelled villages experience a 24% reduction in insurgent attacks relative to controls.

Example: Card and Krueger (2000)

- Do increases to the minimum wage depress employment at fast-food restaurants?

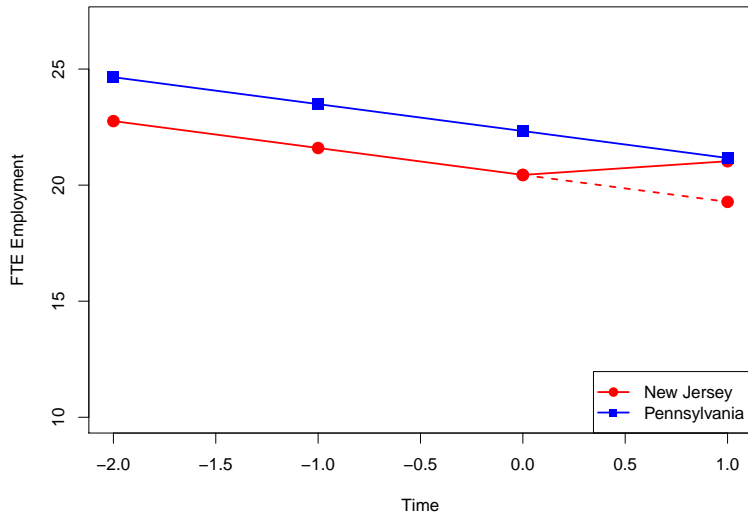
$$\text{employment}_{it} = \beta_0 + \beta_1 \text{minimum wage}_{it} + a_i + u_{it}$$

- Each i here is a different fast food restaurant in either New Jersey or Pennsylvania
- Between $t = 1$ and $t = 2$ NJ raised its minimum wage
- Employment in fast food might be driven by other state-level policies correlated with minimum wage
- Diff-in-diff approach: regress changes in employment on store being in NJ

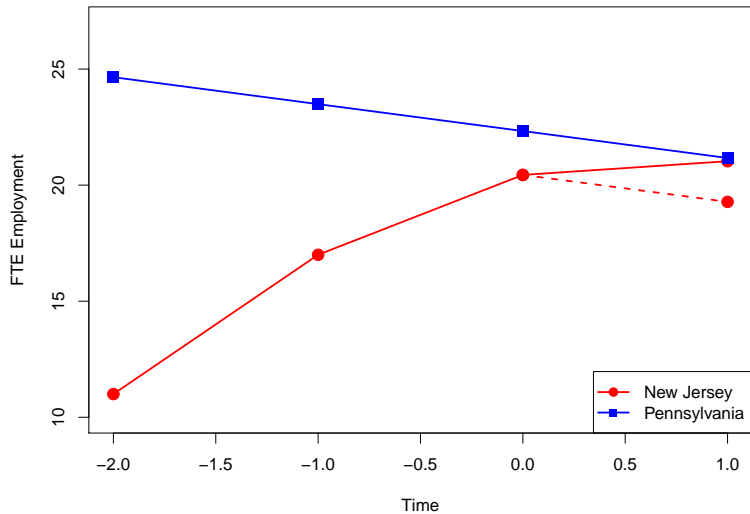
$$\Delta \text{employment}_i = \beta_0 + \beta_1 NJ_i + \Delta u_i$$

- NJ_i indicates which stores received the treatment of a higher minimum wage at time period $t = 2$

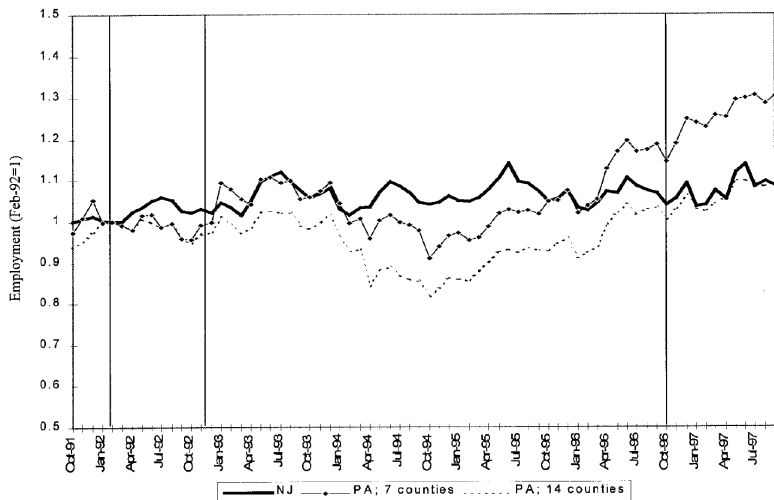
Parallel Trends?



Parallel Trends?



Longer Trends in Employment (Card and Krueger 2000)



First two vertical lines indicate the dates of the Card-Krueger survey. October 1996 line is the federal minimum wage hike which was binding in PA but not NJ

Threats to Identification

1) Failure of Exogeneity

Treatment needs to be independent of the idiosyncratic shocks:

$$E[(u_{i2} - u_{i1})|x_{i2}] = 0$$

2) Non-parallel dynamics

variation in the outcome over time is the same for the treated and control groups (i.e. no omitted time-varying confounders). e.g. Ashenfelter's dip: people who enroll in job training programs see their earnings decline prior to that training (presumably why they are entering)

3) Changes in Composition of Treatment/Control Groups

we don't want composition of sample to change between periods. what if workers move from eastern PA to NJ in search of higher paying jobs?

4) Long-term vs. Short-term Effects

parallel trends are less credible over a long time horizon, but many policies need time to take effect.

Threats to Identification

5) Functional Form Dependence

difference in levels and difference in logs can be quite different (example via Justin Grimmer)

- ▶ imagine a training program for the young
- ▶ employment for the young increases from 20% to 30%
- ▶ employment for the old increases from 5% to 10%
- ▶ positive DiD effect: $(30 - 20) - (10 - 5) = 5\%$
- ▶ but if you consider log changes:
 $[\log(30) - \log(20)] - [\log(10) - \log(5)] = \log(1.5) - \log(2) < 0$
- ▶ how do we tell which (if either) yields parallel trends?

6) Endogenous Control Variables

can add (time-varying) covariates to help with some of above concerns \rightsquigarrow “regression diff-in-diff”

$$y_{i2} - y_{i1} = \delta_0 + \mathbf{z}'_i \tau + \beta(x_{i2} - x_{i1}) + (u_{i2} - u_{i1})$$

but need to be careful that they aren't affected by the treatment.

Concluding Thoughts on Panel Differencing Models

- Useful toolkit for leveraging panel data, often quite straightforward to explain to people
- Be cautious of **assumptions** required
 - ▶ parallel trends assumptions are most likely to hold over a **shorter time-window**. **Impossible** to test.
 - ▶ can conduct placebo tests which can build confidence, but hard to provide definitive evidence.
 - ▶ some approaches use placebos to correct bias (DDD), but this is just a difference assumption.
- Two questions to ask:
 - 1 'what is the **counterfactual**?' or
 - 2 'what **variation** is used to identify this effect?'

What to read next?

- Angrist and Pischke Chapter 5 Parallel Worlds: Fixed Effects, Differences-in-Differences and Panel Data
- Morgan and Winship Chapter 11 Repeated Observations and the Estimation of Causal Effects

We Covered

- Difference-in-Differences
- Parallel Trends Assumption

Next Time: Fixed Effects

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Basic Model Review

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + a_i + u_{it}$$

- Recall our standard linear model with unobserved time-invariant confounding
- We discussed a **differencing** approach to this model
- The **Fixed effects model** is an alternative way to remove time-invariant unmeasured confounding
- We will start by assuming the model and discussing properties and in the next section, we will consider non-parametric identification.

Fixed Effects Models

- Core idea is to focus on **within-unit comparisons**: changes in y_{it} and x_{it} relative to their within-group means
- First note that taking the average of the y 's over time for a given unit leaves us with a very similar model:

$$\begin{aligned}\bar{y}_i &= \frac{1}{T} \sum_{t=1}^T [\mathbf{x}'_{it}\boldsymbol{\beta} + a_i + u_{it}] \\ &= \left(\frac{1}{T} \sum_{t=1}^T \mathbf{x}'_{it} \right) \boldsymbol{\beta} + \frac{1}{T} \sum_{t=1}^T a_i + \frac{1}{T} \sum_{t=1}^T u_{it} \\ &= \bar{\mathbf{x}}'_i \boldsymbol{\beta} + a_i + \bar{u}_i\end{aligned}$$

- Key fact: because it is **time-constant** the mean of a_i is just a_i
- This regression is sometimes called the “between regression”

Within Transformation

- The “fixed effects,” “within,” or “time-demeaning” transformation is when we subtract off the over-time means from the original data:

$$(y_{it} - \bar{y}_i) = (\mathbf{x}'_{it} - \bar{\mathbf{x}}'_i)\boldsymbol{\beta} + (u_{it} - \bar{u}_i)$$

- If we write $\ddot{y}_{it} = y_{it} - \bar{y}_i$, then we can write this more compactly as:

$$\ddot{y}_{it} = \ddot{\mathbf{x}}'_{it}\boldsymbol{\beta} + \ddot{u}_{it}$$

- Degrees of freedom: $nT - n - k - 1$, which accounts for within transformation (i.e. either use a package like `plm` or adjust the degrees of freedom manually).
- We are now modeling observations as deviation from their group mean.
- NB: you **must** demean the X variables not just the Y variables.

Fixed Effects with Ross data

```
fe.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur), data = ross, index = c("id", "year"),
  model = "within")
summary(fe.mod)

## Oneway (individual) effect Within Model
##
## Call:
## plm(formula = log(kidmort_unicef) ~ democracy + log(GDPcur),
## data = ross, model = "within", index = c("id", "year"))
##
## Unbalanced Panel: n=166, T=1-7, N=649
##
## Residuals :
## Min. 1st Qu. Median 3rd Qu. Max.
## -0.70500 -0.11700 0.00628 0.12200 0.75700
##
## Coefficients :
## Estimate Std. Error t-value Pr(>|t|)
## democracy -0.143233 0.033500 -4.2756 2.299e-05 ***
## log(GDPcur) -0.375203 0.011328 -33.1226 < 2.2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Total Sum of Squares: 81.711
## Residual Sum of Squares: 23.012
## R-Squared : 0.71838
## Adj. R-Squared : 0.53242
## F-statistic: 613.481 on 2 and 481 DF, p-value: < 2.22e-16
```

Strict Exogeneity

- FE models are valid if $E[\mathbf{u}|\mathbf{X}] = 0$: all errors are uncorrelated with covariates in every period:

$$E[\ddot{u}_{it}|\ddot{\mathbf{X}}] = E[u_{it}|\ddot{\mathbf{X}}] - E[\bar{u}_i|\ddot{\mathbf{X}}] = 0 - 0 = 0$$

- This is because the composite errors, \ddot{u}_{it} are function of the errors in every time period through the average, \bar{u}_i
- This rules out, for instance, lagged dependent variables, since $y_{i,t-1}$ has to be correlated with $u_{i,t-1}$. Thus it can't be a covariate for y_{it} .

Fixed Effects and Time-Invariant Covariates

- What if there is a covariate that doesn't vary over time?
- Then $x_{it} = \bar{x}_i$ and $\ddot{x}_{it} = 0$ for all periods t .
- If the time-demeaned covariate is always 0, then it will be perfectly collinear with the intercept and will violate full rank. R/Stata and the like will **drop** it from the regression.
- Basic message: any time-constant variable gets “absorbed” by the fixed effect. It has nothing to contribute because the comparison is **within the units**.
- Can include interactions between time-constant and time-varying variables, but lower order term of the time-constant variables get absorbed by fixed effects too

Time-constant variables

- Pooled model with a time-constant variable, proportion Islamic:

```
library(lmtest)
p.mod <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam,
             data = ross, index = c("id", "year"), model = "pooling")
coeftest(p.mod)

##
## t test of coefficients:
##
##              Estimate  Std. Error  t value  Pr(>|t|)
## (Intercept) 10.30607817  0.35951939  28.6663 < 2.2e-16 ***
## democracy   -0.80233845  0.07766814 -10.3303 < 2.2e-16 ***
## log(GDPcur) -0.25497406  0.01607061 -15.8659 < 2.2e-16 ***
## islam        0.00343325  0.00091045   3.7709 0.0001794 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Time-constant variables

- FE model, where the islam variable drops out, along with the intercept:

```
fe.mod2 <- plm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam,  
               data = ross, index = c("id", "year"), model = "within")  
coeftest(fe.mod2)
```

```
##  
## t test of coefficients:  
##  
##           Estimate Std. Error  t value  Pr(>|t|)  
## democracy  -0.129693   0.035865  -3.6162 0.0003332 ***  
## log(GDPcur) -0.379997   0.011849 -32.0707 < 2.2e-16 ***  
## ---  
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```


Alternate Computation: Least Squares Dummy Variable

- As an alternative to the within transformation, we can also include a series of $n - 1$ dummy variables for each unit:

$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + d_i^{(1)}\alpha_1 + d_i^{(2)}\alpha_2 + \cdots + d_i^{(n)}\alpha_n + u_{it}$$

- Here, $d_i^{(1)}$ is a binary variable which is 1 if $i = 1$ and 0 otherwise—just a unit dummy.
- Gives the **exact** same estimates/standard errors as with time-demeaning
 - Advantage: easy to implement in base R (so is the de-meaning but you have to recompute standard errors by changing the degrees of freedom manually).
 - Disadvantage: computationally difficult with large data sets, since we have to run a regression with $n + k$ variables.
- Why are these equivalent? (remember partialing out strategy and Frisch-Waugh-Lovell theorem)

Example with Ross data

```
library(lmtest)
lsdv.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur) +
               as.factor(id), data = ross)
coeftest(lsdv.mod)[1:6,]
coeftest(fe.mod)[1:2,]
```



```
##              Estimate Std. Error   t value    Pr(>|t|)
## (Intercept)    13.7644887 0.26597312  51.751427 1.008329e-198
## democracy      -0.1432331 0.03349977  -4.275644 2.299393e-05
## log(GDPcur)    -0.3752030 0.01132772 -33.122568 3.494887e-126
## as.factor(id)AGO  0.2997206 0.16767730   1.787485 7.448861e-02
## as.factor(id)ALB -1.9309618 0.19013955 -10.155498 4.392512e-22
## as.factor(id)ARE -1.8762909 0.17020738 -11.023558 2.386557e-25
```



```
##              Estimate Std. Error   t value    Pr(>|t|)
## democracy      -0.1432331 0.03349977  -4.275644 2.299393e-05
## log(GDPcur)    -0.3752030 0.01132772 -33.122568 3.494887e-126
```

Applying Fixed Effects

- We can use fixed effects for other data structures to restrict comparisons to within unit variation
 - ▶ Matched pairs
 - ★ Twin fixed effects to control for unobserved effects of family background
 - ▶ Cluster fixed effects in hierarchical data
 - ★ School fixed effects to control for unobserved effects of school

Fixed Effects Versus First Differences

- Key assumptions:
 - ▶ Strict exogeneity: $E[u_{it}|\mathbf{X}, a_i] = 0$
 - ▶ Time-constant unmeasured heterogeneity, a_i
- Together \implies fixed effects and first differences are unbiased and consistent
- With $T = 2$ the estimators produce identical estimates, but not more generally although they have the same **target estimand**.
- So which one is better when $T > 2$? Which one is more **efficient**?
 - ▶ if u_{it} uncorrelated \rightsquigarrow FE is more efficient
 - ▶ if $u_{it} = u_{i,t-1} + e_{it}$ with e_{it} iid (random walk) \rightsquigarrow FD is more efficient.
- In between, not clear which is better (although if using FD, the errors are serially correlated and need correction).
- Large differences between FE and FD should make us worry about assumptions.
- Note that when the second dimension isn't time, fixed effects will be relevant more often.

We Covered

- Fixed Effects!
- Computation for Fixed Effects!

Next Time: Non-parametric Identification and Fixed Effects

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

- 1 Differencing Models
- 2 Difference-in-Differences
- 3 Fixed Effects
- 4 Non-parametric Identification and Fixed Effects**
- 5 Wrap-Up
 - Questions
 - Concluding Thoughts for the Course

Moving Beyond Linear Separable Confounding

- One reason we like DAGs is that the identification results don't have to start with a statement like, assume the following linear model:

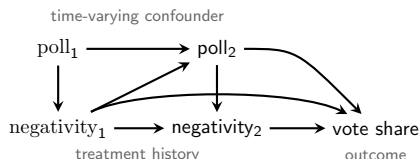
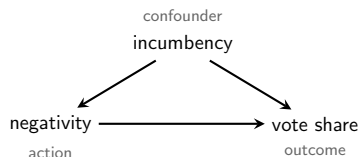
$$y_{it} = \mathbf{x}'_{it}\boldsymbol{\beta} + a_i + u_{it}$$

- What assumptions have we made so far?
 - ▶ constant effects
 - ▶ linearity
 - ▶ strict exogeneity
- We've seen the trouble with constant effects before, it goes back to Lecture 10 and results on regression with heterogeneous treatment effects more generally.

Contemporaneous, Cumulative and Dynamic Effects

- Another assumption we have been making is that our interest is in a single contemporaneous effect: $\mathbf{x}'_{it}\beta$
- What if we want to consider the history of a treatment or the effect of a treatment regime (i.e. a treatment that varies over time)?
- Opens up new estimands, but have to think about how time-varying confounders affect treatment assignment.

Examples of static and dynamic causal inference problems:



Core Conundrum

There is a (possibly irresolvable) tension: modeling causal dynamics between treatment and outcomes **using unobserved** **time-invariant confounders**. Three great recent papers:

A Framework for Dynamic Causal Inference in Political Science

Matthew Blackwell University of Rochester

Dynamic strategies are an essential part of politics. In the context of campaigns, for example, candidates continuously reevaluate their campaign strategy in response to public and opponent actions. Theoretical causal inference methods, however, assume that these dynamic decisions are made at a single point in time, so an assumption that leaves a chasm between empirical reality and postulated theory. This note develops a "single shot" causal inference method and an accompanying framework for dynamic processes like campaigns. I resolve this dilemma by adapting models from Heckavirta, thereby providing a holistic framework for dynamic causal inference. This note will be useful to estimate the effectiveness of an already existing dynamic process, candidate's decisions to "be aggressive." Drawing on U.S. senate election (2006-2008), I find, in contrast to the previous literature and alternative methods, that negative advertising is an effective strategy for noncandidates. I also describe an act to diagnostic tool and an approach to sensitivity analysis.

What candidates would plan all of their rallies, write all of their speeches, and fill all of their advertisements at the beginning of a campaign, then sit back and watch their rallies unfold? Election Day? Clearly this is absurd, and yet it is the only way that the usual way of making causal inferences allows us to study. While political science has seen enormous growth in interest in causal inference over the past decade, these advances have been focused on snapshots where the dynamic nature of politics is captured into a single point in time. As political science finds itself with a growing number of modern platforms—poll data, time-series cross-sectional data, randomized behavioral experiments (Robins, Hernan, and Imbens 2004), ordinary dynamic causal effects, and so on—these methods, indeed, applied to dynamic data, the best practice of single-shot causal inference models provide conflicting advice and fail to address central variables or posttreatment bias.

This article focuses on a specific, dynamic process: negative advertising in US Senate and gubernatorial elections from 2006 until 2008. Candidates in these races change their tone over the course of the campaign, react-

are more likely to go negative than those that are safe, attempting to correct for this dynamic selection by controlling for poll leads to posttreatment bias since earlier campaigns tone influences polling. The inappropriate application of single-shot causal inference therefore leaves scholars between a rock and a hard place, stumped in how to study this approach. This dilemma is not limited to negative advertising or campaigns—every field of political science has a variable of interest that evolves over time.

This article solves this dilemma by providing a framework for dynamic causal inference and an offshoot, developed in Heckavirta and Imbens (2004), Robins, Hernan, and Imbens (2004), ordinary dynamic causal effects. These two both directly model dynamic selection and overcome the above problems of single-shot causal inference. Actions (such as campaign tone) are allowed to vary over time along with any confounding variables (such as polling). This, we see, study the effects of the active factor (candidate's tone across the entire campaign) as opposed to a single action (simply "going negative").

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How to Make Causal Inferences with Time-Series Cross-Sectional Data under Selection on Observables

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Repeated observations of the same countries, people, or groups over time are vital to many fields of political science. These measurements, however, reflect low-order time-series cross-sectional (TSCS) data, which allows researchers to estimate a broad array of causal questions, including contemporaneous effects and direct effects of lagged treatments. Unfortunately, popular methods for TSCS data can only produce valid inferences for lagged effects under some strong assumptions. In this paper, we use potential outcomes to define causal questions of interest in these settings and clarify how standard models fail the autoregressive distributed lag model can produce biased estimates of these quantities due to non-treatment conditions. We then describe two estimation strategies that avoid these past treatment biases—directly modeling selection and control over time—and show how these methods can be used to estimate more standard approaches in small sample settings. We illustrate these methods in a study of how welfare spending affects terrorism.

INTRODUCTION

Many inquiries in political science involve the study of repeated measurements of the same variables, people, or groups at several points in time. This type of data, sometimes called time-series cross-sectional (TSCS) data, allows researchers to draw on a larger pool of information when estimating causal effects. TSCS data also give researchers the power to ask a richer set of questions than with a single measurement for each unit (see Heckavirta and Katz 2013). Using this data, researchers can measure past treatments, contemporaneous questions—what are the effects of a single event?—and instead look the history of a process affecting the political world. Unfortunately, the most common approaches to modeling TSCS data require strict assumptions to estimate the effect of treatment histories without bias and make it difficult to understand the nature of the counterfactual comparisons.

This paper makes three contributions to the study of TSCS data. Our first contribution is to define some

overstated causal effects and discuss the assumptions needed to identify them dynamically. We also relate these quantities of interest to common questions in the TSCS literature, like spillover responses, and show how to derive them from the parameters of a common TSCS model, the autoregressive distributed lag (ADL) model. These treatment effects can be nonparametrically identified under a key selection-on-observables assumption called sequential ignorability; unfortunately, however, many common TSCS approaches rely on more stringent assumptions, including a lack of causal feedback between the treatment and time-varying confounders. This feedback, for example, might involve a country's level of welfare spending affecting the vote share of left wing parties, which in turn affects government's welfare spending. We argue that this type of feedback is common in TSCS data. We then focus on a selection-on-observables assumption in this paper, we discuss the tradeoffs with this choice compared to standard fixed effects models, noting that the latter may also risk this type of dynamic feedback.

We present two methods to provide an introduction to two methods from bootstrapping that can estimate these causal effects under weaker assumptions than common TSCS models: (1) marginal causal effects (MCE) (Robins 2004) and (2) marginal causal effects of treatment (MCE-T) (Robins, Hernan, and Imbens 2004). MCE and MCE-T are closely related to treatment weighting (PTW) (Robins, Hernan, and

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When Should We Use Unit Fixed Effects Regression Models for Causal Inference with Longitudinal Data?

Kosuke Imai, *Harvard University*
In Song Kim, *Massachusetts Institute of Technology*

Abstract: These researchers use an array of fixed effects regression models to avoid confounders with longitudinal data. Do they also find that fixed effects models can avoid confounders with cross-sectional data? This paper shows that the answer to this question is no. Using the empirical data used in the paper, we highlight how key causal identification assumptions of unit fixed effects models implicitly compare treated and control observations from the same person, and past observations of an after-control exposure. Furthermore, we introduce a new regression's matching function that decides how to use unit fixed effects models to compare treated and control observations from the same person. By modeling the counterfactuals between matching and unit fixed effects models, the framework makes a direct test of identification assumptions to show that underplausibility in the absence of dynamic causal relationships between treatment and outcome variables, the theories of potential causality through the application of the extension of OLS methods are not valid.

Reproductive Methods: This article, and all published materials required to replicate all data in this article, are available on the American Journal of Political Science Database within the Harvard Dataverse Network, at <https://dataverse.harvard.edu/dataset.xhtml?persistentId=doi:10.7927/H729-N1M8>.

Unit fixed effects regression models are widely used for causal inference with longitudinal data and have been the standard since the 1960s (e.g., Angrist and Pischke 2009). Many researchers use these models to infer for randomized, unit-specific, and time-varying confounders when estimating causal effects from observational data. In spite of the widespread practice, much methodological discussion of unit fixed effects models in political science has shown that there would be important failure scenarios for unit fixed effects models. To the extent that these assumptions are violated (e.g., Robins 2004; Imbens and Wernicke 2015; Katz and Lerner 2015; Whalen and

Imbens 2007). In contrast, our work builds upon a causal literature with longitudinal data in randomized and nonrandom (e.g., Angrist and Pischke 2009; Sobel 2006; Wooldridge 2010). Specifically, we show that the ability of unit fixed effects regression models to adjust for unobserved treatment confounders comes at the expense of dynamic causal relationships between treatment and outcome variables, which are allowed to enter under an alternative selection on the observed covariate (e.g., Robins, Hernan, and Imbens 2004). Our analysis highlights key

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The methods described in this article can be implemented in the open-source software libraries we designed for causal inference estimation. The causal inference modules that we implemented are: CausalForest (https://github.com/KosukeImai/CausalForest), the latest draft of this article are available: In the list of Linear Fixed Effects Regression Models (https://github.com/KosukeImai/LinearFixedEffectsRegressionModels), and the R package for causal inference: CausalForest (https://github.com/KosukeImai/CausalForest). We thank Robert Gelman, Scott Levitt, Eric Lipton, and the anonymous referees for their helpful comments.

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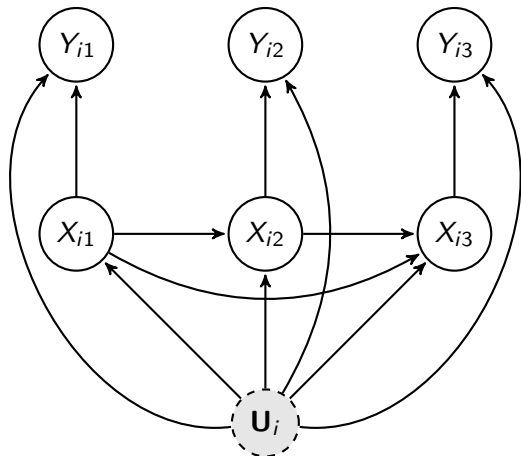
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We are going to focus on addressing unobserved time-invariant confounders using the last paper. Next several slides are based on slides graciously provided by In Song Kim and Kosuke Imai.

Directed Acyclic Graph (DAG)

Non-parametric identification assumptions for fixed effects:

$$Y_{it} = g(X_{it}, \mathbf{U}_i, \epsilon_{it}) \quad \text{and} \quad \epsilon_{it} \perp\!\!\!\perp \{\mathbf{X}_i, \mathbf{U}_i\}$$



Assumptions:

- 1 No unobserved time-varying confounders
- 2 Past outcomes do not directly affect current outcome
- 3 Past outcomes do not directly affect current treatment
- 4 Past treatments do not directly affect current outcome

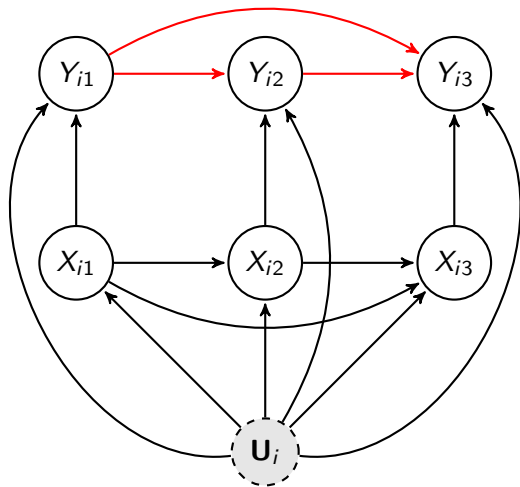
*the result implies that the **counterfactual** outcome for a treated observation in a given time period is estimated using the **observed outcomes of different time periods of the same unit**. Since such a comparison is **valid only when no causal dynamics exist**, this finding underscores the important limitation of linear regression models with unit fixed effects.*

- Imai and Kim (2019)

What Ideal Experiment Corresponds to the Fixed Effects Model?

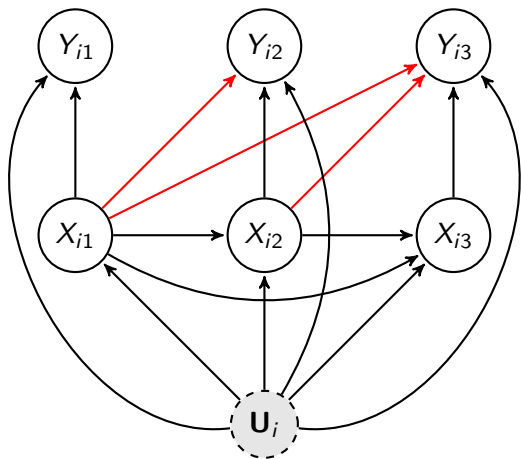
- Experiment that satisfies the model assumptions:
 - ① randomize X_{i1} given \mathbf{U}_i
 - ② randomize X_{i2} given X_{i1} and \mathbf{U}_i
 - ③ randomize X_{i3} given X_{i2} , X_{i1} , and \mathbf{U}_i
 - ④ and so on
- Experiment that does not satisfy the model assumptions:
 - ① randomize X_{i1}
 - ② randomize X_{i2} given X_{i1} and Y_{i1}
 - ③ randomize X_{i3} given X_{i2} , X_{i1} , Y_{i1} , and Y_{i2}
 - ④ and so on
- Now let's consider each assumption in turn.

Past Outcomes Don't Directly Affect Current Outcome (A2)



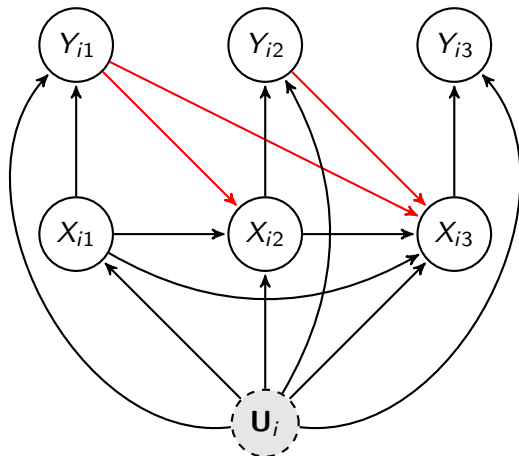
- Strict exogeneity still holds.
- Past outcomes do not confound $X_{it} \rightarrow Y_{it}$ given U_i .
- No need to adjust for past outcomes.
- Should use cluster robust standard errors for inference.
- Conclusion: **The assumption can be relaxed**

Past Treatments Don't Directly Affect Current Outcome (A4)



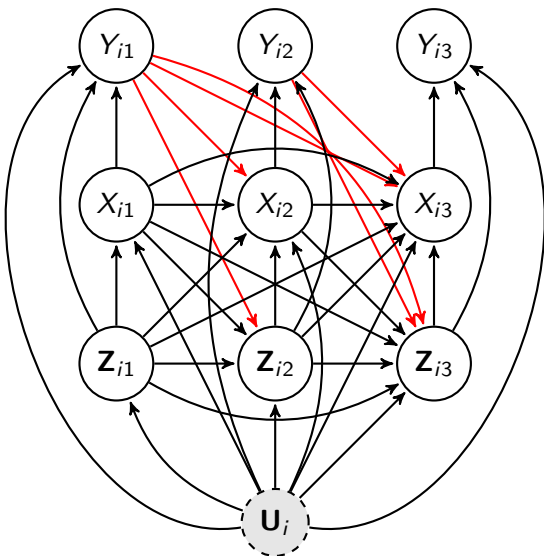
- Need to adjust for past treatments
- Strict exogeneity holds given past treatments and U_i
- Impossible to adjust for an entire treatment history and U_i at the same time
- Adjust for a small number of past treatments \rightsquigarrow often arbitrary
- Conclusion: **The assumption can be partially relaxed**

Past Outcomes Don't Directly Affect Current Treatment (A3)



- Correlation between error term and future treatments
- Violation of strict exogeneity
- No adjustment is sufficient
- Implication: No dynamic causal relationships between treatment and outcome variables
- Conclusion: **The assumption cannot be relaxed**

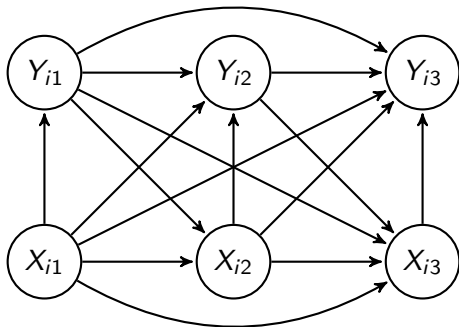
Can't We Just Adjust for Time-Varying Confounders?



- $Y_{it} = \alpha_i + \beta X_{it} + \gamma^T \mathbf{Z}_{it} + \epsilon_{it}$
- past outcomes cannot directly affect current treatment
- past outcomes cannot *indirectly* affect current treatment through \mathbf{Z}_{it}

But What If I Have Causal Dynamics?

Alternative: **Marginal Structural Models** (Robins, Hernán and Brumback, 2000) — see Blackwell 2013 and Blackwell and Glynn 2018 for accessible introductions.



- Absence of unobserved time-invariant confounders \mathbf{U}_i
- past treatments can directly affect current outcome
- past outcomes can directly affect current treatment

- Comparison across units within the same time rather than across different time periods within the same unit
- Can identify the average effect of an entire treatment sequence
- Trade-off \rightsquigarrow no free lunch

Conclusions and Nonparametric Estimation

- Imai and Kim (2019) offer a matching framework for fixed effects models which exploits an equivalence to weighted unit fixed effects estimators (see `wfe` package in R as well).
- The paper clarifies assumptions for fixed effects and first difference estimators.
- Follow-up working paper Imai and Kim (2020) and Imai, Kim and Wang extends to two-way fixed effects estimator.
- Tradeoff:
 - 1) unobserved time-invariant confounders \rightsquigarrow fixed effects
 - 2) causal dynamics between treatment and outcome \rightsquigarrow selection-on-observables

Summary Table (Imai and Kim 2019)

TABLE 1 Identification Assumptions of Various Estimators

	Linearity	Time-Invariant Unobservables	Past Outcomes Affect Current Treatment	Past Treatments Affect Current Outcome
$Y_{it} = \alpha_i + \beta X_{it} + \epsilon_{it}$	Yes	Allowed	Not allowed	Not allowed
$Y_{it} = \alpha_i + \beta X_{it} + \rho Y_{i,t-1} + \epsilon_{it}$	Yes	Allowed	Allowed	Not allowed
$Y_{it} = \alpha_i + \beta_1 X_{it} + \beta_2 X_{i,t-1} + \epsilon_{it}$	Yes	Allowed	Not allowed	Allowed
$Y_{it} = \alpha_i + \beta_1 X_{it} + \beta_2 X_{i,t-1} + \rho Y_{i,t-1} + \epsilon_{it}$	Yes	Allowed	Partially allowed	Partially allowed
Marginal structural models	No	Not allowed	Allowed	Allowed

What to read next?

- Morgan and Winship Chapter 11 Repeated Observations and the Estimation of Causal Effects
- Imai and Kim (2019) “When Should We Use Unit Fixed Effects Regression Models for Causal Inference with Longitudinal Data?” *American Journal of Political Science*, <http://dx.doi.org/10.1111/ajps.12417>

We Covered

- Non-parametric identification for fixed effects.
- A glimpse at dynamic causal inference.

Next Time: Review

Where We've Been and Where We're Going...

- Last Week
 - ▶ causal inference with unmeasured confounding
- This Week
 - ▶ panel data
 - ▶ diff-in-diff
 - ▶ fixed effects
 - ▶ wrap-up
- The Following Week
 - ▶ ?
- Long Run
 - ▶ probability \rightarrow inference \rightarrow regression \rightarrow causality

1 Differencing Models

2 Difference-in-Differences

3 Fixed Effects

4 Non-parametric Identification and Fixed Effects

5 **Wrap-Up**

- Questions
- Concluding Thoughts for the Course

Q: What conditions do we need to infer causality?

A: A clear estimand, an identification strategy and an estimation strategy.

Identification Strategies in This Class

- Experiments (ignorability via randomization)
- Selection on Observables (conditional ignorability)
- Natural Experiments (ignorability via quasi-randomization)
- Instrumental Variables (instrument + exclusion restriction)
- Regression Discontinuity (continuity assumption)
- Difference-in-Differences (parallel trends)
- Fixed Effects (time-invariant unobserved heterogeneity, strict ignorability)

Almost everything assumes: consistency/SUTVA (no interference between units, variation in the treatment is irrelevant) and positivity (there is some chance of all getting treatment)

Some Estimation Strategies

- Stratification
- Regression (and relatives)
- Matching (lightly covered)
- Weighting (not covered)

Q: Can you review how instrumental variables deal with issues of confounding?

A: We use only the units whose treatment status was effectively randomized by the instrument (because they are compliers).

Q: What can make standard errors larger or smaller?

A: Let's consider the anatomy of a standard error.

Anatomy of the Standard Error

Imagine we have a regression of Y on a variable of interest X and a vector of other variables \mathbf{Z} .

$$\widehat{\text{Var}}(\widehat{\beta}_X) = \frac{\frac{1}{(n-k-1)} \sum_{i=1}^n \hat{u}_i^2}{(1 - R_{X \sim \mathbf{Z}}^2) \sum_{i=1}^n (X_i - \bar{X})^2}$$

- the numerator is our estimator for σ_u^2 the unknown error variance. It is formed by the degrees of freedom correction times the sum of the squared residuals.
- the denominator includes one minus the R^2 from the regression of X_i on \mathbf{Z}_i
- we complete the denominator by multiplying a measure of the variation in X_i , the sum of squared deviations from the mean.

$$\widehat{\text{SE}}(\widehat{\beta}_X) = \sqrt{\widehat{\text{Var}}(\widehat{\beta}_X)}$$

Q: When conducting an experiment, should we avoid OLS and always go for difference in means?

A: Regression adjustment of experiments can be helpful for improving precision. We don't need it for confounding, but it can improve our standard errors to adjust for pre-treatment covariates that are highly predictive of the output. If done correctly and in moderate-to-large samples, this can dramatically improve your standard errors. Even better though is blocking which is adjustment by design.

Further Reading:

- Lin, W., 2013. 'Agnostic notes on regression adjustments to experimental data: Reexamining Freedman's critique.' *The Annals of Applied Statistics*
- Athey, S. and Imbens, G.W., 2017. 'The Econometrics of Randomized Experiments.' In *Handbook of Economic Field Experiments* (Vol. 1, pp. 73-140).
- Egap Methods Guide: 10 things you need to know about covariate adjustment. <https://egap.org/methods-guides/10-things-know-about-covariate-adjustment>

Q: What are your favorite resources for learning tricky concepts?

I've used the following procedure many times:

- 1 Identify approx. the best textbook (often can do this via syllabi hunting)
- 2 Read the relevant textbook material
- 3 Derive the equations/math
- 4 Try to explain it to someone else

Q: In the real world of research, when you have your data, how do you know which method to use? For example, how do you know that you need to use matching/regression discontinuity?

A: Let's chat.

Q: What would you have covered with more time?

- 1 Missing Data
- 2 Sensitivity Analysis
- 3 Mediation (and Front Door Adjustment)
- 4 Bounds and Partial Identification
- 5 Weighting Approaches
- 6 Quantile Regression
- 7 On the Ground Decision Making

1 Differencing Models

2 Difference-in-Differences

3 Fixed Effects

4 Non-parametric Identification and Fixed Effects

5 **Wrap-Up**

- Questions
- Concluding Thoughts for the Course

Where are you?

You've been given a powerful set of tools



Your New Weapons

- **Basic probability theory**

- ▶ Probability axioms, random variables, marginal and conditional probability, building a probability model
- ▶ Expected value, variances, independence
- ▶ CDF and PDF (discrete and continuous)

- **Properties of Estimators**

- ▶ Bias, Efficiency, Consistency
- ▶ Central limit theorem

- **Univariate Inference**

- ▶ Interval estimation (normal and non-normal Population)
- ▶ Confidence intervals, hypothesis tests, p-values
- ▶ Practical versus statistical significance

Your New Weapons

● Simple Regression

- ▶ regression to approximate the conditional expectation function
- ▶ idea of conditioning
- ▶ kernel and loess regressions
- ▶ OLS estimator for bivariate regression
- ▶ Variance decomposition, goodness of fit, interpretation of estimates, transformations

● Multiple Regression

- ▶ OLS estimator for multiple regression in matrix notation
- ▶ Regression assumptions (classical and agnostic)
- ▶ Properties: Bias, Efficiency, Consistency
- ▶ Standard errors, testing, p-values, and confidence intervals
- ▶ Polynomials, Interactions, Dummy Variables
- ▶ F-tests

Your New Weapons

- **Diagnosing and Fixing Regression Problems**
 - ▶ Non-normality
 - ▶ Outliers, leverage, and influence points, Robust Regression
 - ▶ Non-linearities and GAMs
 - ▶ Heteroscedasticity and Clustering
- **Causal Inference**
 - ▶ Frameworks: potential outcomes and DAGs
 - ▶ Measured Confounding
 - ▶ Unmeasured Confounding
 - ▶ Methods for repeated data
- **And you learned how to use R:** you're not afraid of trying something new!

Using these Tools

So, Admiral Ackbar, now that you've learned how to run these regressions we can just use them blindly, right?



IT'S A TRAP!



Beyond Linear Regressions

You need more training



Beyond Linear Regressions

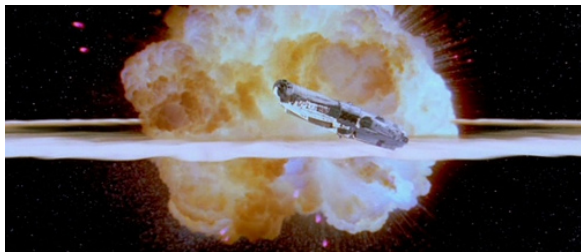
There is so much more to learn! Take classes, read books!

- Take SOC 504 or the POL sequence!
- Pursue the SML certificate!
- Go to workshops and seminars etc.!
- Read the suggested books in the syllabus!

I've tried to offer a **perspective on technique** in addition to just a list of methods. See Lundberg, Johnson and Stewart “[What's Your Estimand? Defining the Target Quantity Connects Statistical Evidence to Theory](#)”

Thanks!

Thanks so much for an amazing semester.



I will see you in the final synchronous session!